

Generalized Method of Moments Estimation with extensions to structural breaks in cointegration models

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Abstract

Generalized Method of Moments (GMM) Estimators are derived for Random Walk Regression Models, the Error Correction Cointegration Model (ECCM) and the Incomplete Simultaneous Equations Model (ISEEM). The GMM (2SLS) estimators of the cointegrating vector in the ECCM are shown to have normal limiting distributions. Tests for the number of unit roots are also constructed straightforwardly and have Dickey-Fuller type limiting distributions. Two extensions of the ECCM, which are important in practice, are analyzed. First, cointegration estimators and tests allowing for structural shifts in the variance (heteroskedasticity) of the series are derived and analyzed using a Generalized Least Squares Estimator. Second, cointegrating vector estimators and tests are derived which allow for structural breaks in the cointegrating vector and/or multiplication. The resulting cointegrating vectors estimators have again normal limiting distributions while the cointegration tests have limiting distributions which differ from the standard Dickey-Fuller type.

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1 Introduction

Comitology has been an important research topic since its definition in [1] and already a large literature has evolved on it. An important part of this literature is devoted to the construction of asset returns, asset volatilities and their limiting distributions, see e.g. [1], [4] and [12]. These constructions cover stylized models, which are constant over time and hence a constant variance. Although models, which deviate from these stylized models, no longer exhibit the condition of weak (or variance) stationarity, they can still show some regularity so that they still possess properties of comitology, see for example [7], whereas it is shown that comitology can still be defined in fractal models although the model for the comitology relationship is not weakly stationary but still some regularity. So, the comitology relationship do not exhibit weak stationarity conditions in these cases but comitology is still an important property of the series generated by these kind of models. In practice, there is a need for the construction of comitology asset returns and asset volatilities which can be applied in these kind of models as a large number of series possess properties resulting from these models, like heteroscedasticity and structural breaks, and still show some regularity of linear combinations. Besides the fact that there is a need for heteroscedasticity is a stylized fact, and macro-economic, where structural breaks are an important topic. Application of the comitology asset returns, which essentially assesses their linear properties are not possible, in these kind of series can lead to inconsistent asset returns and/or wrong assessments of the (asymptotic) variance of the asset returns. There is, therefore, a need for the development of comitology asset returns and asset volatilities which can be applied in these kind of models. We develop a generalized BEKK (GEBEK) framework, see [6], for comitology models which allow for the incorporation of the asset heteroscedasticity and/or structural breaks. Also the stylized models are covered by this framework and lead to asset returns which are the 2SLS (two stage least squares) counterpart of the canonical correlation comitology asset returns, see [4].

The paper is organized as follows. In section 2, the relation between the GEBEK-2SLS asset returns in comitology and simultaneous equations models is discussed jointly with the limiting distributions of the comitology vector asset returns for a few widely used specifications of the data-generating processes. Section 3, shows the limiting distribution of the GEBEK objective function which can be used to test for the number of unit roots/comitology relationships. In section 4, the stylized model is extended to a model where a shift of variance occurs after a predefined fraction of time has elapsed. A generalized Least Squares approach, which assesses a priori knowledge of the variance shift point, is used to construct the comitology asset returns and volatilities that allow for heteroscedasticity. In section 5, comitology asset returns and volatilities that account for a change in the comitology relationship and/or multiplicity, are constructed. Some extensions can be formally generalized to more shifts and also other model conditions

can be added. Finally, the sixth section concludes.

Note that the following definitions are used throughout the paper; \Rightarrow indicates weak convergence; integrals are taken over the unit interval unless indicated otherwise; when possible without confusion, integrals like $\int_0^1 \mathbb{E}(t)dt$ are shortly denoted as $\int \mathbb{E}$. The theorems in the paper are derived assuming Gaussian disturbances, which assumption can be relaxed, see for example [15].

2 Reduced Rank Regression in Reduced Rank Regression Models

2.1 Reduced Rank Regression Models

Reduced rank regression models are characterized by the lower column or row rank of a parameter matrix. Two well known models which possess this property are the Error Correction Cointegration Model (ECCM) and the Incomplete Simultaneous Equations Model (INSEM). The ECCM is specified as

$$\mathbb{E}z_t = \alpha\mathbb{E}^1 z_{t-1} + \varepsilon_t, \quad (1)$$

where $z_t : \mathbb{R}^2 \times L$, $t = 1, \dots, T$; $\alpha, \mathbb{E}^1 : \mathbb{R}^2 \times \sigma$; $\mathbb{E}^1 = (\mathbb{I}_2 - \mathbb{E}^1)$; and ε_t is Gaussian white noise with covariance matrix Σ . For simplicity higher order lags are left out. The INSEM reads

$$\begin{aligned} g_{1t} &= \mathbb{E}_2^1 g_{2t} + \tau_1^1 z_{1t} + \varepsilon_{1t} \\ g_{2t} &= \mathbb{E}_{21} z_{1t} + \mathbb{E}_{22} z_{2t} + \varepsilon_{2t} \end{aligned} \quad (2)$$

where $g_{1t} : \mathbb{R}_1 \times L$, $g_{2t} : \mathbb{R}_2 \times L$, $z_{1t} : \mathbb{R}_1 \times L$, $z_{2t} : \mathbb{R}_2 \times L$, $t = 1, \dots, T$; $\mathbb{E}_2^1 : \mathbb{R}_2 \times \mathbb{R}_1$; $\tau_1^1 : \mathbb{R}_1 \times \mathbb{R}_1$; $\mathbb{E}_{21} : \mathbb{R}_2 \times \mathbb{R}_1$; $\mathbb{E}_{22} : \mathbb{R}_2 \times \mathbb{R}_2$. The disturbances ε_{1t} and ε_{2t} are assumed to be Gaussian white noise with covariance matrix Ω . The variables z_{1t} and z_{2t} are assumed to be (weakly) exogenous. The INSEM in (2) is identified when the number of excluded exogenous variables from the first set of equations, \mathbb{R}_1 , is at least as large as the number of equations in the second set, \mathbb{R}_2 , $\mathbb{R}_1, \mathbb{R}_2 \geq \mathbb{R}_2$.

The reduced rank property of cointegration models is obtained when we specify them as restrictions of the standard linear model,

$$z_t = \mathbb{E}w_t + w_t. \quad (3)$$

Since the ECCM and the INSEM are restricted versions of the model in (3).

The ECCM is obtained by specifying $z_t = \mathbb{E}z_t$, $\mathbb{E} = \alpha\mathbb{E}^1 = \begin{pmatrix} \alpha_{11} & -\alpha_{11}\mathbb{E}_2^1 \\ \alpha_{21} & -\alpha_{21}\mathbb{E}_2^1 \end{pmatrix}$, $w_t = \varepsilon_t$, $w_t = z_{t-1}$, while the INSEM is obtained when we substitute the equation of g_{2t} in the equation of g_{1t} which then results in (3) with $z_t = \begin{pmatrix} g_{1t} \\ g_{2t} \end{pmatrix}$, $w_t =$

$\begin{pmatrix} \mathbb{C}_{14} \\ \mathbb{C}_{24} \end{pmatrix}$, $\mathbb{a}_t = \begin{pmatrix} \mathbb{C}_{14} \oplus \mathbb{C}_{24}^{\otimes 2} \\ \mathbb{C}_{24} \end{pmatrix}$, $\mathbb{B} = \begin{pmatrix} \mathbb{C}_{24}^{\otimes 2} \oplus \mathbb{C}_{21} \oplus \mathbb{C}_{22} \\ \mathbb{C}_{21} \oplus \mathbb{C}_{22} \end{pmatrix}$. The reduced rank structure of the $\mathbb{C}\mathbb{C}\mathbb{C}\mathbb{B}$ is obvious while the $\mathbb{B}\mathbb{S}\mathbb{E}\mathbb{C}\mathbb{B}$ has a reduced rank structure when $\mathbb{C}_{21} = 0$ since the first set of rows of \mathbb{B} is a linear function of the other rows in that case. The reduced rank properties of both models are different in nature, however, as in the $\mathbb{C}\mathbb{C}\mathbb{C}\mathbb{B}$ the last set of columns is a linear combination of the first set while in the $\mathbb{B}\mathbb{S}\mathbb{E}\mathbb{C}\mathbb{B}$ the first set of rows is a linear combination of the last set.

2.2 $\mathbb{C}\mathbb{C}\mathbb{C}\mathbb{B}$ -2SLS estimators

In the $\mathbb{B}\mathbb{S}\mathbb{E}\mathbb{C}\mathbb{B}$ form (2), a consistent estimator of the parameters \mathbb{C}_{24} and \mathbb{C}_{21} is obtained when we replace \mathbb{C}_{24} in the first set of equations by $\mathbb{C}_{24}^* = \mathbb{C}_{21}\mathbb{C}_{14} \oplus \mathbb{C}_{22}\mathbb{C}_{24}$, where \mathbb{C}_{21} and \mathbb{C}_{22} are the least squares estimators obtained from the second set of equations, and estimate the parameters of the resulting equation using least squares. The resulting estimator of $(\mathbb{C}_{24}^*, \mathbb{C}_{21})$ is known as the two stage least squares (2SLS) estimator. A similar kind of 2SLS estimator can be constructed for the cointegrating vector \mathbb{C} in the $\mathbb{C}\mathbb{C}\mathbb{C}\mathbb{B}$ (1). An important difference between the cointegrating vector parameter \mathbb{C} and the structural form parameters \mathbb{C}_{24} and \mathbb{C}_{21} arises, however, from the presence of the cointegrating vector in all equations of the $\mathbb{C}\mathbb{C}\mathbb{C}\mathbb{B}$ while the structural form parameters of the $\mathbb{B}\mathbb{S}\mathbb{E}\mathbb{C}\mathbb{B}$ only appear in the first set of equations. The 2SLS estimator for the $\mathbb{C}\mathbb{C}\mathbb{C}\mathbb{B}$ has, therefore, a different specification than the 2SLS estimator for the $\mathbb{B}\mathbb{S}\mathbb{E}\mathbb{C}\mathbb{B}$. Some of these estimators are generalized method of moments (GMM) estimators, see [8].

To derive the expressions of the GMM-2SLS estimators both in the $\mathbb{B}\mathbb{S}\mathbb{E}\mathbb{C}\mathbb{B}$ and the $\mathbb{C}\mathbb{C}\mathbb{C}\mathbb{B}$, we use the first order conditions for a maximum of the likelihood. The derivatives of the log likelihood, when assuming Gaussian white noise disturbances with covariance matrix \mathbb{E} , of the model in (3), read

$$\begin{aligned}
 \frac{\partial \ln l(\mathbb{B})}{\partial \mathbb{B}'} &= \text{vec}(\mathbb{E}^{-1})' \sum_{t=1}^T (\mathbb{a}_t \oplus \mathbb{I}_k) \frac{\partial \mathbb{a}_t}{\partial \mathbb{B}'} \\
 &= \sum_{t=1}^T \text{vec}(\mathbb{a}_t \mathbb{a}_t')' (\mathbb{I}_k \oplus \mathbb{E}^{-1}) \frac{\partial \text{vec}(\mathbb{B})}{\partial \mathbb{B}'}.
 \end{aligned} \tag{4}$$

In the GMM objective function we only use the $\sum_{t=1}^T \text{vec}(\mathbb{a}_t \mathbb{a}_t')$ part of the derivatives in (4). When we substitute the expression of \mathbb{B} in $\frac{\partial \text{vec}(\mathbb{B})}{\partial \mathbb{B}'}$, the first order derivatives of the different parameters are obtained. The resulting expressions read, for the $\mathbb{C}\mathbb{C}\mathbb{C}\mathbb{B}$,

$$\begin{aligned}
 \frac{\partial \text{vec}(\mathbb{B})}{\partial \text{vec}(\mathbb{C}_{24})'} &= -(\mathbb{I}_k \oplus \mathbb{0}), \\
 \frac{\partial \text{vec}(\mathbb{B})}{\partial \text{vec}(\mathbb{C}_{21})'} &= -(\mathbb{0} \oplus \mathbb{I}_k),
 \end{aligned} \tag{5}$$

and for the INVERSE ,

$$\begin{aligned}\frac{\partial \text{var}(\mathbb{I})}{\partial \text{var}(\mathbb{S}_2^2)^2} &= -\left(\begin{array}{cc} \mathbb{I}_{21} & \mathbb{I}_{22} \end{array}\right)' \mathbb{I}^{-1} \left(\begin{array}{c} \mathbb{I}_{22} \\ \mathbb{I} \end{array}\right), \\ \frac{\partial \text{var}(\mathbb{I})}{\partial \text{var}(\mathbb{I}_1^2)^2} &= -\left(\begin{array}{cc} \mathbb{I}_{k1} & \mathbb{I} \end{array}\right)' \mathbb{I}^{-1} \left(\begin{array}{c} \mathbb{I}_{22} \\ \mathbb{I} \end{array}\right), \\ \frac{\partial \text{var}(\mathbb{I})}{\partial \text{var}(\mathbb{I}_{21}^2)^2} &= -\left(\begin{array}{cc} \mathbb{I}_{k1} & \mathbb{I} \end{array}\right)' \mathbb{I}^{-1} \left(\begin{array}{c} \mathbb{S}_2^2 \\ \mathbb{I}_{22} \end{array}\right), \\ \frac{\partial \text{var}(\mathbb{I})}{\partial \text{var}(\mathbb{I}_{22}^2)^2} &= -\left(\begin{array}{cc} \mathbb{I} & \mathbb{I}_{k2} \end{array}\right)' \mathbb{I}^{-1} \left(\begin{array}{c} \mathbb{S}_2^2 \\ \mathbb{I}_{22} \end{array}\right).\end{aligned}\quad (6)$$

The expressions of the derivatives of the individual parameters are substituted in the first order derivatives of the objective function which is minimized in the ECLS framework. As we cannot exactly solve the normal equation, $\sum_{t=1}^T a_t a_t' = \mathbb{I}$, in case of reduced rank parameter matrices, we take a quadratic form containing these normal equations as objective function to be minimized in the ECLS framework, see also [2],

$$\mathfrak{L}(\theta) = \text{var}\left(\sum_{t=1}^T a_t a_t'\right)' \left(\sum_{t=1}^T a_t a_t'\right)^{-1} \mathbb{I} \mathbb{I}^{-1} \text{var}\left(\sum_{t=1}^T a_t a_t'\right). \quad (7)$$

The first order condition of the ECLS objective function then becomes

$$\begin{aligned}\frac{\partial \mathfrak{L}(\theta)}{\partial \theta} &= \mathbb{I} \mathbb{I} \quad (8) \\ \sum_{t=1}^T \left(\frac{\partial a_t}{\partial \theta}\right) (a_t' \mathbb{I} \mathbb{I}_k) \left(\sum_{t=1}^T a_t a_t'\right)^{-1} \mathbb{I} \mathbb{I}^{-1} \text{var}\left(\sum_{t=1}^T a_t a_t'\right) &= \mathbb{I} \mathbb{I} \\ \left(\frac{\partial \text{var}(\mathbb{I})}{\partial \theta}\right)' \text{var}\left(\mathbb{I}^{-1} \sum_{t=1}^T a_t a_t'\right) &= \mathbb{I}\end{aligned}$$

The first order condition of the ECLS objective function in (8) equals the first order condition for a maximum likelihood value, see (4).

For the parameters of the ECLS these first order conditions read,

$$(\mathbb{I}_k \mathbb{I} \mathbb{I})' \text{var}\left(\mathbb{I}^{-1} \sum_{t=1}^T a_t a_{t-1}'\right) = \mathbb{I} \mathbb{I} \quad (9)$$

$$\left(\sum_{t=1}^T a_{t-1} a_{t-1}'\right)^{-1} \left(\sum_{t=1}^T a_{t-1} \mathbb{I} a_t'\right) \mathbb{I}^{-1} \mathbb{I} (\mathbb{I} \mathbb{I}^{-1} \mathbb{I})^{-1} = \mathbb{I},$$

$$(\mathbb{I} \mathbb{I} \mathbb{I}_k)' \text{var}\left(\mathbb{I}^{-1} \sum_{t=1}^T a_t a_{t-1}'\right) = \mathbb{I} \mathbb{I} \quad (10)$$

$$\left(\sum_{t=1}^T \mathbb{I} a_t a_{t-1}' \mathbb{I}\right) \left(\sum_{t=1}^T a_{t-1} a_{t-1}' \mathbb{I}\right)^{-1} = \mathbb{I},$$

and for the parameters of the INSESS the first order conditions read,

$$\begin{aligned} \left(\begin{array}{cc} \mathbb{I}_{21} & \mathbb{I}_{22} \end{array} \right)' & \mathbb{I} \left(\begin{array}{c} \mathbb{I}_{11} \\ \mathbb{I} \end{array} \right)' \text{var} \left(\mathbb{I}^{-1} \sum_{t=1}^T \alpha_t \varepsilon_t^1 \right) = \mathbb{0} \quad (11) \\ \left(\begin{array}{cc} \mathbb{I}_{21} & \mathbb{I}_{22} \end{array} \right)' \left(\sum_{t=1}^T \varepsilon_t \varepsilon_t' \right)^{-1} \left(\begin{array}{cc} \mathbb{I}_{21} & \mathbb{I}_{22} \end{array} \right) \left(\sum_{t=1}^T \varepsilon_t (\varepsilon_{1t} - \gamma_1' \varepsilon_{1t}) \right)' & = \mathbb{0}_2, \end{aligned}$$

$$\begin{aligned} \left(\begin{array}{c} \mathbb{I}_{31} \\ \mathbb{I} \end{array} \right)' & \mathbb{I} \left(\begin{array}{c} \mathbb{I}_{11} \\ \mathbb{I} \end{array} \right)' \text{var} \left(\mathbb{I}^{-1} \sum_{t=1}^T \alpha_t \varepsilon_t^1 \right) = \mathbb{0} \quad (12) \\ \left(\sum_{t=1}^T \varepsilon_{1t} \varepsilon_{1t}' \right)^{-1} \sum_{t=1}^T \varepsilon_{1t} (\varepsilon_{1t} - \mathbb{0}_2' \varepsilon_{1t})' & = \mathbb{I}_1, \end{aligned}$$

$$\begin{aligned} \left(\begin{array}{c} \mathbb{I}_2 \\ \mathbb{I} \end{array} \right)' & \mathbb{I} \left(\begin{array}{c} \mathbb{0}_2' \\ \mathbb{I} \end{array} \right)' \text{var} \left(\mathbb{I}^{-1} \sum_{t=1}^T \alpha_t \varepsilon_t^1 \right) = \mathbb{0} \quad (13) \\ \left(\sum_{t=1}^T \varepsilon_{2t} \varepsilon_{2t}' \right) \left(\sum_{t=1}^T \varepsilon_t \varepsilon_t' \right)^{-1} & = \mathbb{I}_2. \end{aligned}$$

The normal equations for the INSESS directly lead to the 2SLS estimation as the estimation of \mathbb{I}_2 is independent of the parameters $\mathbb{0}_2$ and γ_1 such that it can be estimated independently. The resulting estimation of \mathbb{I}_2 is then used to construct estimations for $\mathbb{0}_2$ and γ_1 (2SLS estimations). The estimations of α and $\mathbb{0}$ in the ECLS don't depend on our model. As we didn't restrict α and $\mathbb{0}$, they are also not identified. If we specify $\mathbb{0}$ as, $\mathbb{0} = (\mathbb{I}_2 - \mathbb{0}_2')'$, then α and $\mathbb{0}_2$ are perfectly identified. If this specification of $\mathbb{0}$ is used, a consistent estimation of α is,

$$\begin{aligned} \alpha &= \left(\sum_{t=1}^T \mathbb{0}_2' \varepsilon_t (\mathbb{I} - \varepsilon_{2t-1}' \left(\sum_{t=1}^T \varepsilon_{2t-1} \varepsilon_{2t-1}' \right)^{-1} \varepsilon_{2t-1}) \varepsilon_{1t-1}' \right) \quad (14) \\ & \left(\sum_{t=1}^T \varepsilon_{1t-1} (\mathbb{I} - \varepsilon_{2t-1}' \left(\sum_{t=1}^T \varepsilon_{2t-1} \varepsilon_{2t-1}' \right)^{-1} \varepsilon_{2t-1}) \varepsilon_{1t-1}' \right)^{-1} \end{aligned}$$

where $\varepsilon_t = \begin{pmatrix} \varepsilon_{1t} \\ \varepsilon_{2t} \end{pmatrix}$, $\varepsilon_{1t} : \sigma \times \mathbb{I}$, $\varepsilon_{2t} : (\mathbb{I} - \sigma) \times \mathbb{I}$, which is just the first σ columns of the least squares estimation of \mathbb{I} in (8).

If the estimation of α (14) is used in the estimation of the cointegrating vector $\mathbb{0}$, (9), the identifying restrictions on $\mathbb{0}$ are automatically fulfilled. The resulting estimation of $\mathbb{0}$ is then the 2SLS estimation of the cointegrating vector $\mathbb{0}$. In a Koyckian analysis this 2SLS estimation equals the sum of the conditional probabilities of $\mathbb{0}$ given α when a diffuse prior is used, see [6]. The estimations of α and $\mathbb{0}$ in (9) and (10) also allow for the construction of an iterative estimation scheme for which the resulting estimations converge to the maximum likelihood estimations.

Asymptotically the 2SLS least squares cointegrating vector estimation processes are the same kind of processes as the maximum likelihood estimation, i.e. ergodic, stationary and normal limiting distribution. This is proved in the theorems in the following (sub)sections.

2.3 Limiting distributions of 2SLS cointegration estimators

We discuss the limiting distribution of the 2SLS estimator in the INSE model is discussed at length in the literature, see for example [10], we concentrate on the limiting distribution of the 2SLS estimator for the cointegration case, which is only sparsely discussed in the literature, see for example [16], where the case that w_t in (7) is uncorrelated with w_{t-1} is discussed. Theorem 1 states the limiting distribution of the multiplication estimator, \hat{m} , and the 2SLS cointegrating vector estimator, $\hat{\beta}$.

Theorem 1 *When the Data Generating Process (DGP) in (7) is such that the number of cointegrating vectors equals n ($k - n$ unit roots), the estimators*

$$\hat{m} = \left(\sum_{t=1}^T \tilde{w}_t w_t' (I - w_{t-1}' (\sum_{t=1}^T w_{t-1} w_{t-1}')^{-1} w_{t-1}) w_{t-1}' \right) \left(\sum_{t=1}^T w_{t-1} w_{t-1}' (I - w_{t-1}' (\sum_{t=1}^T w_{t-1} w_{t-1}')^{-1} w_{t-1}) w_{t-1}' \right)^{-1} \quad (15)$$

and

$$\hat{\beta} = \left(\sum_{t=1}^T w_{t-1} w_{t-1}' \right)^{-1} \left(\sum_{t=1}^T w_{t-1} \tilde{w}_t' \right) \Sigma^{-1} \hat{m} (\hat{m}' \Sigma^{-1} \hat{m})^{-1} \quad (16)$$

have a limiting behavior which can be characterized by

$$\sqrt{T}(\hat{m} - m) \rightsquigarrow N(0, \text{cov}(\hat{\beta}' \Sigma^{-1} \hat{\beta})) \quad (17)$$

$$\begin{aligned} \sqrt{T}(\hat{\beta} - \beta) &\rightsquigarrow \begin{pmatrix} \int_0^1 (\hat{\beta}_1' \hat{\beta}_1)^{-1} \hat{\beta}_1' m \hat{\sigma}_1^{-1} \left(\int_0^1 \hat{\beta}_1 \hat{\beta}_1' \right)^{-1} \int_0^1 \hat{\beta}_1 \hat{\Sigma} \hat{\beta}_2' \hat{\sigma}_2^{-1} \\ \int_0^1 m(\hat{\beta}_1' \hat{\beta}_1)^{-1} m' \hat{\Sigma}^{-1} \hat{\beta}_1 \end{pmatrix}, \end{aligned} \quad (18)$$

where $\hat{\beta}_1$, resp. $\hat{\beta}_2$ are $(k - n)$, resp. n dimensional stochastically independent Brownian motions defined on the unit interval, $\hat{\sigma}_1 = (m' \hat{\Sigma} m)^{\frac{1}{2}}$, $\hat{\sigma}_2 = (m' \hat{\Sigma}^{-1} m)^{\frac{1}{2}}$, $\hat{\Sigma} = (\hat{\beta}_1' \hat{\beta}_1)^{-1} \hat{\beta}_1' m \hat{\sigma}_1^{-1} \left(\int_0^1 \hat{\beta}_1 \hat{\beta}_1' \right)^{-1} \hat{\sigma}_1^{-1} m' \hat{\beta}_1 (\hat{\beta}_1' \hat{\beta}_1)^{-1}$ and $\hat{\Sigma}$ is estimated by the sum of squared residuals, $\hat{\Sigma} = \frac{1}{T} \sum_{t=1}^T \left(\tilde{w}_t w_t' (I - w_{t-1}' (\sum_{t=1}^T w_{t-1} w_{t-1}')^{-1} w_{t-1}) \tilde{w}_t' \right)$.

Proof: see Appendix.

Theorem 1 discusses the limiting distribution of the cointegrating vector estimation for the most straightforward case, i.e. no further lags in the VAR polynomial and no deterministic components, and shows that it is identical to the limiting distribution of the canonical correlation maximum likelihood estimation of Johansen, see [4]. The addition of lags of $\mathbb{S}t_t$ only changes the limiting distribution of the cointegrating vector estimation, $\hat{\beta}$, in the sense that $\mathbb{M}(\hat{\beta})$ has to be replaced by $\mathbb{M}(\Gamma)\hat{\beta}$, where $\Gamma(\mathbb{K})\mathbb{S}t_t = \mathbb{M}(\mathbb{S}^{\mathbb{K}})e_{t-1} + e_t$ and $\Gamma(\mathbb{K})$ is a $(p-1)$ -dimensional lag polynomial in case of a VAR(p), inclusion of deterministic components does also change the functional form of the cointegrating vector estimation, see for example [4] and [5] for the influence of the deterministic components on other kind of cointegrating vector estimators. **Theorem 2** states the estimators and limiting distributions of the multiplication and cointegrating vector estimators including deterministic components for a few commonly used specifications of the deterministic components.

Theorem 2 *Under the DGP rules*

$$\mathbb{S}t_t = \mathbb{M}(\mathbb{S}^{\mathbb{K}})e_{t-1} + e_t, \quad (18)$$

with the number of cointegrating vectors equals \mathbb{K} ($\mathbb{K} < p$ unit roots), the estimator

$$\hat{\mathbb{M}} = \left(\sum_{t=1}^T \mathbb{S}t_t \mathbb{S}t_t' \right) \left(\mathbb{I} - \sum_{j=1}^{\mathbb{K}-1} \frac{\mathbb{S}t_{t-j} \mathbb{S}t_{t-j}'}{\mathbb{I}} \right)^{-1} \left(\sum_{t=1}^T \mathbb{S}t_t \right) \left(\sum_{t=1}^T \mathbb{S}t_t \mathbb{S}t_t' \right)^{-1} \left(\sum_{t=1}^T \mathbb{S}t_t \right)' \left(\mathbb{I} - \sum_{j=1}^{\mathbb{K}-1} \frac{\mathbb{S}t_{t-j} \mathbb{S}t_{t-j}'}{\mathbb{I}} \right)^{-1} \quad (19)$$

$$\left(\sum_{t=1}^T \mathbb{S}t_{t-1} \mathbb{S}t_{t-1}' \right) \left(\sum_{t=1}^T \mathbb{S}t_{t-1} \right) \left(\sum_{t=1}^T \mathbb{S}t_{t-1} \mathbb{S}t_{t-1}' \right)^{-1} \left(\sum_{t=1}^T \mathbb{S}t_{t-1} \right)' \left(\mathbb{I} - \sum_{j=1}^{\mathbb{K}-1} \frac{\mathbb{S}t_{t-j} \mathbb{S}t_{t-j}'}{\mathbb{I}} \right)^{-1} \quad (20)$$

$$\left(\sum_{t=1}^T \mathbb{S}t_{t-1} \mathbb{S}t_{t-1}' \right)^{-1} \quad (21)$$

with

$$\sum_{t=1}^T \mathbb{S}t_t \mathbb{S}t_t' = \left(\sum_{t=1}^T \mathbb{S}t_t \right) \left(\sum_{t=1}^T \mathbb{S}t_t \mathbb{S}t_t' \right)^{-1} \left(\sum_{t=1}^T \mathbb{S}t_t \right)' \quad (22)$$

have a limiting behavior which can be characterized by

$$\mathbb{M}(\hat{\mathbb{M}} - \mathbb{M}) \xrightarrow{d} \mathbb{M}(\mathbb{0}, \text{cov}(\mathbb{S}^{\mathbb{K}}e - e^{\mathbb{K}}))^{-1} \mathbb{M}(\mathbb{M}) \quad (23)$$

$$\begin{aligned} & \left(\sum_{t=1}^T \mathbb{S}t_t \mathbb{S}t_t' \right)^{-1} \left(\sum_{t=1}^T \mathbb{S}t_t \right) \left(\sum_{t=1}^T \mathbb{S}t_t \mathbb{S}t_t' \right)^{-1} \left(\sum_{t=1}^T \mathbb{S}t_t \right)' \left(\mathbb{I} - \sum_{j=1}^{\mathbb{K}-1} \frac{\mathbb{S}t_{t-j} \mathbb{S}t_{t-j}'}{\mathbb{I}} \right)^{-1} \left(\sum_{t=1}^T \mathbb{S}t_t \right) \left(\sum_{t=1}^T \mathbb{S}t_t \mathbb{S}t_t' \right)^{-1} \left(\sum_{t=1}^T \mathbb{S}t_t \right)' \left(\mathbb{I} - \sum_{j=1}^{\mathbb{K}-1} \frac{\mathbb{S}t_{t-j} \mathbb{S}t_{t-j}'}{\mathbb{I}} \right)^{-1} \quad (24) \\ & \left(\sum_{t=1}^T \mathbb{S}t_{t-1} \mathbb{S}t_{t-1}' \right)^{-1} \left(\sum_{t=1}^T \mathbb{S}t_{t-1} \right) \left(\sum_{t=1}^T \mathbb{S}t_{t-1} \mathbb{S}t_{t-1}' \right)^{-1} \left(\sum_{t=1}^T \mathbb{S}t_{t-1} \right)' \left(\mathbb{I} - \sum_{j=1}^{\mathbb{K}-1} \frac{\mathbb{S}t_{t-j} \mathbb{S}t_{t-j}'}{\mathbb{I}} \right)^{-1} \left(\sum_{t=1}^T \mathbb{S}t_{t-1} \right) \left(\sum_{t=1}^T \mathbb{S}t_{t-1} \mathbb{S}t_{t-1}' \right)^{-1} \left(\sum_{t=1}^T \mathbb{S}t_{t-1} \right)' \left(\mathbb{I} - \sum_{j=1}^{\mathbb{K}-1} \frac{\mathbb{S}t_{t-j} \mathbb{S}t_{t-j}'}{\mathbb{I}} \right)^{-1} \quad (25) \\ & \left(\sum_{t=1}^T \mathbb{S}t_{t-1} \mathbb{S}t_{t-1}' \right)^{-1} \quad (26) \end{aligned}$$

and

$$\begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} = \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \quad (21)$$

where a limiting behavior which can be characterized by

$$\mathbb{Z} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \approx \mathbb{Z} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \quad (22)$$

$$\begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \quad (23)$$

$$\approx \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \quad (24)$$

$$\approx \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \quad (25)$$

where $\mathbb{Z}_1, \mathbb{Z}_2$ and \mathbb{Z}_3 are $(\mathbb{Z} - \mathbb{Z}), (\mathbb{Z} - \mathbb{Z} - 1)$ and \mathbb{Z} dimensional stochastically independent Gaussian matrices, $\mathbb{Z}_1 = (\mathbb{Z}^2 \mathbb{Z}^2)^{1/2}, \mathbb{Z}_2 = (\mathbb{Z}^2 \mathbb{Z}^2)^{1/2}, \mathbb{Z}_3 = (\mathbb{Z}^2 \mathbb{Z}^2)^{1/2}$.

$$\mathbb{Z} = \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix}, \quad \mathbb{Z} = (\mathbb{Z}^2 \mathbb{Z}^2)^{-1} \mathbb{Z}^2 \mathbb{Z}^2 (\mathbb{Z}^2 \mathbb{Z}^2)^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix},$$

$$\mathbb{Z}_1 = (\mathbb{Z}^2 \mathbb{Z}^2)^{-1} \mathbb{Z}^2 \mathbb{Z}^2 (\mathbb{Z}^2 \mathbb{Z}^2)^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix},$$

$$\mathbb{Z}_2 = \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix},$$

$$\mathbb{Z}_3 = (\mathbb{Z}^2 \mathbb{Z}^2)^{-1} \mathbb{Z}^2 \mathbb{Z}^2 (\mathbb{Z}^2 \mathbb{Z}^2)^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix} \begin{pmatrix} \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \\ \mathbb{Z} & \mathbb{Z} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \\ \mathbb{Z} \end{pmatrix}.$$

Proof: The first and third part of the theorem are natural extensions of theorem 1. The second part of the theorem is proved in the appendix.

Theorems 1 and 2 show that the limiting distributions of elements of the cointegrating vector estimation are normal and standard (asymptotic) \mathbb{Z}^2 tests can be performed to test hypotheses on the cointegrating vectors, see [12]. The next section discusses the use of the cointegrating vector estimation, \mathbb{Z} , and the multiplication, \mathbb{Z} , in the \mathbb{Z}^2 objective function, (7), to construct a statistic to test for the number of cointegrating vectors, unit roots, in the system.

where $\mathbb{C}_t = \begin{pmatrix} \mathbb{C}_{1t} \\ \mathbb{C}_{2t} \end{pmatrix}$, $\mathbb{C}_{1t} : \mathfrak{a} \times \mathbb{L}$, $\mathbb{C}_{2t} : (\mathfrak{B} - \mathfrak{a}) \times \mathbb{L}$; $\mathbb{C}_{t-1} = \mathbb{C}_{t-1} - \frac{1}{\tau} \sum_{j=1}^{\tau} \mathbb{C}_{t-1}$,
 $\bar{t} = t - \frac{1}{\tau} \sum_{j=1}^{\tau} t$; \mathbb{M}_{11} , \mathbb{M}_{21} are $(\mathfrak{B} - \mathfrak{a})$, $(\mathfrak{B} - \mathfrak{a} - \mathbb{L})$ linearized linearizations,
 $\mathbb{M}_{11} = \begin{pmatrix} \mathbb{M}_{111} \\ \mathbb{M}_{112} \end{pmatrix}$, $\mathbb{M}_{21} = \mathbb{M}_{21} - \tau \mathbb{M}_{21}$, $\mathbb{M}_{211} = \mathbb{M}_{211} - \tau \mathbb{M}_{211}$, $\tau(t) = t$, $\epsilon(t) = \mathbb{L}$,
 $0 \leq t \leq \mathbb{L}$, $\bar{\tau} = \tau - \tau$, and \mathbb{E} is estimated by the residual sum of squares for the
unrestricted model.

Proof: In the first part a proof is given in the appendix, the other parts follow straightforwardly.

Theorems 1 to 3 show that the limiting distributions using the ~~NSMM~~-2SLS estimators are identical to the limiting distributions with ~~linear~~ likelihood estimators are used, see [4]. The ~~linear~~ likelihood estimators can be constructed in a straightforward way using canonical correlations where it is not much gain when 2SLS estimators are used compared to ~~linear~~ likelihood estimators from a limiting distribution perspective. Possible gains can be found in the small sample distribution of the 2SLS estimator and in model restrictions as ~~linear~~ likelihood estimators become analytically intractable when more complicated models are used than the one shown in (1).

In [13], it is shown that the canonical correlation cointegrating vector estimator has a small sample distribution with ~~U~~ rank type tails and that it has no finite moments. When we neglect the dynamic property of the data and assume fixed regressors, results from [10] indicate that the small sample distribution of the 2SLS cointegrating vector estimator has finite moments up to the degree $(\mathfrak{B} - \mathfrak{a})$. This degree is determined by the $\mathbb{E}^{-1}(\mathbb{E}^{-1})^{-1}$ regression appearing in the cointegrating vector estimator $\hat{\beta}$. The $\hat{\beta}$ is specified such that it always has rank \mathfrak{a} , rank reduction of \mathbb{E}^{-1} implies that it has a lower rank value. In that case \mathbb{E}^{-1} would not be invertible leading to the fat tails of the small sample distribution. So, cointegration tests essentially test for the rank of \mathbb{E} and can be considered as tests for the local identification of $\hat{\beta}$ and are, therefore, comparable with the cointegration parameter in the NSMM, see [10].

The ~~linear~~ likelihood cointegrating vector estimator is appealing as it has a simple expression in the standard case. The relation between ~~linear~~ likelihood cointegrating vector estimators and canonical correlations is, however, lost when restrictions of the model are considered. Furthermore, model restrictions often lead to analytically intractable ~~linear~~ likelihood estimators. The ~~NSMM~~ framework used in this paper offers a framework which allows for the analytical construction of cointegrating vector estimators for a general class of models. In the next sections two kind of structural break model restrictions are analyzed, i.e. structural breaks in the variance (heteroscedasticity) and cointegrating vector and/or multiplication, whereas cointegrating vector ~~linear~~ likelihood estimators

are not of the canonical correlation type.

4. Cointegration in a VAR with Heteroscedasticity

Assuming homoscedastic disturbances in (1), the maximum likelihood estimation of the cointegrating vector can be constructed using canonical correlations. This estimation has a normal limiting distribution under conditions which are more general than strict homoscedasticity, see [15], where it is shown that the weak convergence properties are retained in case of conditional heteroscedasticity with constant unconditional variances. These weak convergence properties are, however, lost when the mean of the conditional variances changes from period to period. Furthermore, also the relation between the maximum likelihood estimation and canonical correlations is lost in that case. A VAR-ESLS cointegrating vector estimation can still be constructed when the functional form of the heteroscedasticity is known. The constructed estimators and limiting distributions for an example of a change of the variances after a predefined period of time T_1 has evolved over that the analyzed model reads,

$$\mathbb{E}x_t = \alpha \mathbb{E}x_{t-1} + \varepsilon_t, \quad (29)$$

where

$$\begin{aligned} \text{cov}(\varepsilon_t) &= \Sigma_1, & t = 1, \dots, T_1 \\ &= \Sigma_2, & t = T_1 + 1, \dots, T \end{aligned} \quad (30)$$

In the next subsection, the VAR cointegrating vector estimation and cointegration test and their limiting distributions are derived using a Generalized Least Squares (GLS) framework to account for the heteroscedasticity.

4.1 Generalized Least Squares Cointegration Estimators

Assuming that we know the form of heteroscedasticity, a different GLS objective function than (7) is used in the construction of the GLS estimators,

$$\begin{aligned} \mathbb{E}^0(\alpha, \beta) &= \text{var} \left(\sum_{t=1}^{T_1} \Sigma_1^{-1} \varepsilon_t x_{t-1}' + \sum_{t=T_1+1}^T \Sigma_2^{-1} \varepsilon_t x_{t-1}' \right) \\ &\quad \left(\sum_{t=1}^{T_1} (\varepsilon_{t-1} x_{t-1}' + \Sigma_1^{-1}) + \sum_{t=T_1+1}^T (\varepsilon_{t-1} x_{t-1}' + \Sigma_2^{-1}) \right)^{-1} \\ &\quad \text{var} \left(\sum_{t=1}^{T_1} \Sigma_1^{-1} \varepsilon_t x_{t-1}' + \sum_{t=T_1+1}^T \Sigma_2^{-1} \varepsilon_t x_{t-1}' \right). \end{aligned} \quad (31)$$

In this case, however, the \mathbb{R}^2 estimations and their limiting distributions jointly with the limiting distribution of the optimal value of the \mathbb{R}^2 objective function are stated.

Theorem 2 *Under the \mathbb{R}^2 equations (36), (37) is such that the number of integrating factors is ν ($\delta - \nu$ unit roots), the estimators,*

$$\begin{aligned} var(\hat{m}) &= \left(\left(\sum_{t=1}^{T_1} \mathbb{I}_{t-1} \mathbb{I}_{t-1}' \otimes \mathbb{I}_2^{-1} \right) \otimes \left(\sum_{t=T_1+1}^T \mathbb{I}_{t-1} \mathbb{I}_{t-1}' \otimes \mathbb{I}_2^{-1} \right) \right)^{-1} & (41) \\ & var \left(\sum_{t=1}^{T_1} \mathbb{I}_2^{-1} \mathbb{I}_{t-1} \mathbb{I}_{t-1}' \otimes \mathbb{I}_2 \otimes \mathbb{I}_2^{-1} \right) \otimes \sum_{t=T_1+1}^T \mathbb{I}_2^{-1} \mathbb{I}_{t-1} \mathbb{I}_{t-1}' \otimes \mathbb{I}_2 \otimes \mathbb{I}_2^{-1}, \end{aligned}$$

with

$$\begin{aligned} var(\hat{m}^0) &= \left(\left(\sum_{t=1}^{T_1} \mathbb{I}_{t-1} \mathbb{I}_{t-1}' \otimes \mathbb{I}^0 \mathbb{I}_2^{-1} \mathbb{I} \right) \otimes \left(\sum_{t=T_1+1}^T \mathbb{I}_{t-1} \mathbb{I}_{t-1}' \otimes \mathbb{I}^0 \mathbb{I}_2^{-1} \mathbb{I} \right) \right)^{-1} & (42) \\ & var \left(\sum_{t=1}^{T_1} \mathbb{I}^0 \mathbb{I}_2^{-1} \mathbb{I}_{t-1} \mathbb{I}_{t-1}' \otimes \mathbb{I} \otimes \mathbb{I}_2 \otimes \mathbb{I}_2^{-1} \right) \otimes \sum_{t=T_1+1}^T \mathbb{I}^0 \mathbb{I}_2^{-1} \mathbb{I}_{t-1} \mathbb{I}_{t-1}' \otimes \mathbb{I} \otimes \mathbb{I}_2 \otimes \mathbb{I}_2^{-1}, \end{aligned}$$

have a limiting behavior which can be characterized by

$$\begin{aligned} \sqrt{T} var(\hat{m} - m) &\rightsquigarrow m(\mathbb{I}, (var(cov(\hat{m}^0) \otimes \mathbb{I}^0 \mathbb{I}_2^{-1} \mathbb{I})) \\ &\otimes (\mathbb{I} - \pi)(var(\hat{m}^0) \otimes \mathbb{I}^0 \mathbb{I}_2^{-1} \mathbb{I}))^{-1}), \end{aligned} & (43)$$

with

$$\begin{aligned} & \mathcal{F}[var(\hat{m}_2^0 - \hat{m}_2^0)] & (44) \\ & \rightsquigarrow \left((\hat{m}_2^0 \hat{m}_2^0)' \right)^{-1} \hat{m}_2^0 \otimes \mathbb{I}_2 \otimes \left(\hat{m}_2^0 \left(\sum_{j=0}^M \mathbb{I}_2 \otimes \mathbb{I}_2 \otimes \mathbb{I}_2 \otimes \mathbb{I}^0 \mathbb{I}_2^{-1} \mathbb{I} \right) \otimes \right. \\ & \left. \left(\sum_{j=0}^1 \left(\hat{m}_2 \otimes \mathbb{I}_2(t) \otimes \hat{m}_2 \otimes \mathbb{I}_2(\pi) \right) \left(\hat{m}_2 \otimes \mathbb{I}_2(t) \otimes \hat{m}_2 \otimes \mathbb{I}_2(\pi) \right)' \mathbb{I} \otimes \mathbb{I}^0 \mathbb{I}_2^{-1} \mathbb{I} \right) \right)^{-1} \\ & var \left[\mathbb{Q}_1 \left(\sum_{j=0}^M \mathbb{I}^0 \mathbb{I}_2 \otimes \mathbb{I}_2 \otimes \mathbb{I}_2 \right) \hat{m}_2^0 \otimes \mathbb{Q}_2 \left(\sum_{j=0}^1 \mathbb{I}^0 \mathbb{I}_2 \otimes \mathbb{I}_2 \otimes \mathbb{I}_2 \otimes \mathbb{I}^0 \mathbb{I}_2^{-1} \mathbb{I} \right) \right], \end{aligned}$$

The limiting behavior of the optimal value of the \mathbb{R}^2 objective function, can be characterized by

$$\begin{aligned} & \mathbb{E}(\hat{m}, \hat{m}^0) & (45) \\ & \rightsquigarrow var \left[\hat{m}_2^0 \left(\sum_{j=0}^M \mathbb{I}^0 \mathbb{I}_2 \otimes \mathbb{I}_2 \otimes \mathbb{I}_2 \right) \hat{m}_2^0 \otimes \mathbb{Q}_2 \left(\sum_{j=0}^1 \mathbb{I}^0 \mathbb{I}_2 \otimes \mathbb{I}_2 \otimes \mathbb{I}_2 \otimes \mathbb{I}^0 \mathbb{I}_2^{-1} \mathbb{I} \right) \right] \end{aligned}$$

$$\begin{aligned}
& \left(\left(\mathcal{D}_1 \int_0^T \mathbb{W}_1^{\otimes 2} \mathcal{D}_1^{\otimes 2} \mathbb{W}_1^{\otimes 2} \mathcal{D}_1^{\otimes 2} \mathbb{W}_1^{\otimes 2} \mathcal{D}_1^{\otimes 2} \mathbb{W}_1^{\otimes 2} \right) \mathbb{W}_1^{\otimes 2} \mathbb{W}_1^{\otimes 2} \right)^{-1} \\
& \left(\mathcal{D}_2 \int_0^T \mathbb{W}_2^{\otimes 2} \mathcal{D}_2^{\otimes 2} \mathbb{W}_2^{\otimes 2} \mathcal{D}_2^{\otimes 2} \mathbb{W}_2^{\otimes 2} \right)^{-1} \\
& \text{var} \left[\mathcal{D}_1 \left(\int_0^T \mathbb{W}_1^{\otimes 2} \mathcal{D}_1^{\otimes 2} \mathbb{W}_1^{\otimes 2} \right) \mathcal{D}_1^{\otimes 2} \mathbb{W}_1^{\otimes 2} \right] \left(\mathcal{D}_2 \int_0^T \mathbb{W}_2^{\otimes 2} \mathcal{D}_2^{\otimes 2} \mathbb{W}_2^{\otimes 2} \right)^{-1} \left(\mathcal{D}_2 \int_0^T \mathbb{W}_2^{\otimes 2} \mathcal{D}_2^{\otimes 2} \mathbb{W}_2^{\otimes 2} \right)^{-1} \text{var} \left[\mathcal{D}_2 \left(\int_0^T \mathbb{W}_2^{\otimes 2} \mathcal{D}_2^{\otimes 2} \mathbb{W}_2^{\otimes 2} \right) \mathcal{D}_2^{\otimes 2} \mathbb{W}_2^{\otimes 2} \right],
\end{aligned}$$

where $\alpha = \frac{T_1}{T}$, \mathbb{W}_1 and \mathbb{W}_2 are stochastically independent α , $(\mathbb{S} - \alpha)$ linear-stochastic Brownian motions with identity covariance matrices, $\mathcal{D}_1 = (\mathbb{W}_1^{\otimes 2} \mathbb{W}_1^{\otimes 2})^{\frac{1}{2}}$, $\mathcal{D}_2 = (\mathbb{W}_2^{\otimes 2} \mathbb{W}_2^{\otimes 2})^{\frac{1}{2}}$, $\mathbb{Q}_1 = (\mathbb{W}_1^{\otimes 2} \mathbb{W}_1^{\otimes 2})^{\frac{1}{2}}$, $\mathbb{Q}_2 = (\mathbb{W}_2^{\otimes 2} \mathbb{W}_2^{\otimes 2})^{\frac{1}{2}}$, $\mathbb{S}_1 = \frac{1}{\alpha_1 - k} \sum_{t=1}^{\frac{T_1}{\alpha_1}} \mathbb{W}_1^{\otimes 2} (\mathbb{I} - \mathbb{e}_{t-1}^{\otimes 2} (\sum_{s=1}^{\frac{T_1}{\alpha_1}} \mathbb{e}_{t-1}^{\otimes 2} \mathbb{e}_{t-1}^{\otimes 2})^{-1} \mathbb{e}_{t-1}^{\otimes 2}) \mathbb{W}_1^{\otimes 2}$, $\mathbb{S}_2 = \frac{1}{\alpha_2 - k} \sum_{t=1}^{\frac{T_2}{\alpha_2}} \mathbb{W}_2^{\otimes 2} (\mathbb{I} - \mathbb{e}_{t-1}^{\otimes 2} (\sum_{s=1}^{\frac{T_2}{\alpha_2}} \mathbb{e}_{t-1}^{\otimes 2} \mathbb{e}_{t-1}^{\otimes 2})^{-1} \mathbb{e}_{t-1}^{\otimes 2}) \mathbb{W}_2^{\otimes 2}$, $\text{var}(\mathbb{S}_1^{\otimes 2}) = \mathbb{S}_1^{\otimes 2} \mathbb{S}_1^{\otimes 2} \mathbb{S}_1^{\otimes 2}$, $\text{var}(\mathbb{S}_2^{\otimes 2}) = \mathbb{S}_2^{\otimes 2} \mathbb{S}_2^{\otimes 2} \mathbb{S}_2^{\otimes 2}$, $(\cdot)_1^{-1}$ are the first two terms \mathbb{S}_1^{-1} .

Proof: The asymptotic results for sub-samples using the fraction α are from [8]. Using these asymptotics for sub-samples, the other results follow straightforwardly from the proofs of theorems 1-5.

The cointegrating vector estimation in theorem 4 is a 2SLS estimation as it is constructed in two sequential stages. In the first stage, we estimate \mathbb{W} in (5) using least squares and use the first α columns to construct \mathbb{W}_1 . Furthermore, we construct \mathbb{S}_1 and \mathbb{S}_2 as the sum of squared residuals of the two sub-samples. In the second stage, we construct the estimation $\mathbb{S}_1^{\otimes 2}$ (42).

Theorem 4 shows that the cointegrating vector estimation $\mathbb{S}_1^{\otimes 2}$ has a normal limiting distribution. While we use a cointegrating vector estimation which neglects the heteroscedasticity of the disturbances, we cannot find accurate expressions of the covariance matrices since it is hard to test hypotheses on the cointegrating vector in that case. Although the cointegrating relationships are not weakly stationary in this case, as they have a different variance in each of the two variance regimes, they still show mean reversion. The estimations and limiting distributions from theorem 4 can be extended to more variance shifts and other non-stationary conditions (relationships) for the variances can be incorporated. The limiting distribution of the optimal value of the GMM objective function depends on the relative change of the covariance matrices and the relative time fraction during which the variance differs, α . As it is not known what the true values of these parameters are, they are typically replaced by sample estimates. The resulting distribution is in that case no longer the true limiting distribution but only an approximation of it. It is interesting to investigate whether non-parametric covariance estimations, like the white covariance matrices estimation, see [17], can be used to overcome these difficulties. These covariance matrices estimations can directly

be used in the MLE objective function and expressions of the resulting limiting distributions are still unknown.

5. Cointegration with structural breaks

In this section, we investigate the influence of a change in the value of the multiplication, α , and cointegrating vector, β , at T_1 . The model, therefore, is

$$\begin{aligned} \mathbb{E}z_t &= \alpha\beta'z_{t-1} + \varepsilon_t & t = 1, \dots, T_1, \\ \mathbb{E}z_t &= \beta'z_{t-1} + \varepsilon_t & t = T_1 + 1, \dots, T, \end{aligned} \quad (46)$$

where ε_t , $t = 1, \dots, T$, are Gaussian white noise disturbances with covariances matrix Σ . The MLE objective function corresponding with this model reads,

$$\begin{aligned} \mathbb{E}(\alpha, \beta, \gamma, \beta) &= \text{var}\left(\sum_{t=1}^{T_1} z_t z_{t-1}', \sum_{t=T_1+1}^T z_t z_{t-1}'\right) \\ &\begin{pmatrix} \sum_{t=1}^{T_1} \left(\left(\sum_{t=1}^{T_1} z_{t-1} z_{t-1}' \right)^{-1} \beta \beta' \right) & 0 \\ 0 & \left(\sum_{t=T_1+1}^T z_{t-1} z_{t-1}' \right)^{-1} \beta \beta' \end{pmatrix} \\ &\text{var}\left(\sum_{t=1}^{T_1} z_t z_{t-1}', \sum_{t=T_1+1}^T z_t z_{t-1}'\right), \end{aligned} \quad (47)$$

where $\text{var}(\bar{z}, \bar{\beta}) = (\text{var}(\bar{z}))' \text{var}(\bar{\beta})$. In theorem 6, the MLE estimations of the cointegrating vector, multiplication and their limiting distributions are stated jointly with the limiting distribution of the MLE objective function. As the cointegrating vector estimations and multiplications all have normal limiting distribution, standard χ^2 tests can be performed to test for the equality of the parameters in each of the two periods. Theorem 6 also states the estimations and their limiting distributions, which can be used when either the cointegrating vectors or multiplications in each of the two periods are equal to one another.

Lemma 5 *When the MLE in (46) is such that the number of cointegrating vectors is q ($q < p$ unit roots), the estimators,*

$$\begin{aligned} \hat{\alpha} &= \left(\sum_{t=1}^{T_1} \hat{\beta} z_t (I - z_{t-1}' \left(\sum_{t=1}^{T_1} z_{t-1} z_{t-1}' \right)^{-1} z_{t-1}) z_{t-1}' \right) \\ &\quad \left(\sum_{t=1}^{T_1} z_{t-1} (I - z_{t-1}' \left(\sum_{t=1}^{T_1} z_{t-1} z_{t-1}' \right)^{-1} z_{t-1}) z_{t-1}' \right)^{-1}, \end{aligned} \quad (48)$$

$$\hat{\beta} = \left(\sum_{t=T_1+1}^T \hat{\beta} z_t (I - z_{t-1}' \left(\sum_{t=T_1+1}^T z_{t-1} z_{t-1}' \right)^{-1} z_{t-1}) z_{t-1}' \right) \quad (49)$$

where $m = \frac{T_1}{T}$, \mathbb{W}_1 and \mathbb{W}_2 are stochastically independent n , $(k - n)$ dimensional Gaussian matrices with identity covariance matrices, $\mathbb{S}_1 = (m \mathbb{W}_1 \Sigma^{-1} m \mathbb{W}_1)^\frac{1}{2}$, $\mathbb{S}_2 = (\mathbb{W}_2 \Sigma^{-1} \mathbb{W}_2)^\frac{1}{2}$, $\mathbb{Q}_1 = (m \mathbb{W}_1 \Sigma m)^\frac{1}{2}$, $\mathbb{Q}_2 = (\mathbb{W}_2 \Sigma \mathbb{W}_2)^\frac{1}{2}$, $\mathbb{Z}_1 = \frac{1}{T_1 - k} \sum_{t=1}^{T_1} \mathbb{W}_1 \mathbb{S}_t (I - \mathbb{S}_{t-1}^\frac{1}{2} (\sum_{s=1}^{T_1} \mathbb{S}_{t-1} \mathbb{S}_{t-1}^\frac{1}{2})^{-1} \mathbb{S}_{t-1}^\frac{1}{2}) \mathbb{W}_1 \mathbb{S}_t^\frac{1}{2}$, $\mathbb{Z}_2 = \frac{1}{T - T_1 - k} \sum_{t=T_1+1}^T \mathbb{W}_2 \mathbb{S}_t (I - \mathbb{S}_{t-1}^\frac{1}{2} (\sum_{s=T_1+1}^T \mathbb{S}_{t-1} \mathbb{S}_{t-1}^\frac{1}{2})^{-1} \mathbb{S}_{t-1}^\frac{1}{2}) \mathbb{W}_2 \mathbb{S}_t^\frac{1}{2}$, $\text{cov}(\mathbb{Z}^\frac{1}{2} \mathbb{c})_1 = \mathbb{W}_1^\frac{1}{2} \sum_{i=0}^{k-1} \mathbb{C}_{2i}^\frac{1}{2} \mathbb{Z}_1 \mathbb{C}_{2i}^\frac{1}{2} \mathbb{W}_1^\frac{1}{2}$, $\text{cov}(\mathbb{Z}^\frac{1}{2} \mathbb{c})_2 = \mathbb{W}_2^\frac{1}{2} \sum_{i=0}^{k-1} \mathbb{C}_{2i}^\frac{1}{2} \mathbb{Z}_2 \mathbb{C}_{2i}^\frac{1}{2} \mathbb{W}_2^\frac{1}{2}$, and $\mathbb{C}_1(\mathbb{I})$, $\mathbb{C}_2(\mathbb{I})$ are the Vector Moving Average representations of the first and second subsets.

Proof: again uses asymptotics for submatrices, see [8], and results from proofs of theorems 1-5.

Theorem 6 shows that the GMM estimators of the cointegrating vector and multiplication have normal limiting distributions in case of breaks in the cointegrating vector and/or multiplication. Similar to the limiting distribution of the optimal value of the GMM objective function in case of heteroscedasticity, the limiting distribution of the optimal value of the GMM objective function again depends on model parameters and the relative length of the submatrices. An approximation of this limiting distribution can again be constructed using the estimated values of the parameters, m , \mathbb{W}_1 , \mathbb{W}_2 , τ and \mathbb{T}_1 . As this leads to a rather complicated testing procedure, it may be preferable to fix the number of cointegrating vectors a priori and just perform tests on the estimated cointegrated vectors and multiplications, which are straightforward to construct. This reasoning also holds for the cointegration tests discussed in the previous section.

6 Conclusions

The GMM framework for cointegration analysis is developed allowing for estimation of the models which are analysable using the maximum likelihood procedure documented in the literature. As examples, model estimators incorporating heteroscedasticity and structural breaks are discussed and the resulting cointegration estimators are shown to have normal limiting distributions while the optimal value of the GMM objective function has a limiting distribution which is a Gaussian vector functional with additional parameters resulting from the change of properties of the involved Gaussian vectors. These additional parameters are essentially the parameters in the model which vary over time resulting in heteroscedasticity or structural breaks. In future works, we will apply the developed framework for a.o. cointegration analysis in financial series, for example to examine the interest rates. As heteroscedasticity is a stylized fact of these series, the standard cointegration procedures cannot be applied here as they lead to incorrect (asymptotic) variances of the estimators.

Appendix

Proof of theorem 1.

In [4], it is proved that the stochastic process x_t , from (1), can be represented by

$$\tilde{x}_t = \tilde{C}^*(\tilde{I}) \tilde{Z}_t^1 \tilde{Z}_t^{-1},$$

where $\tilde{Z}_t = \left(\begin{matrix} \tilde{I}_t & -\tilde{Z}_t^1 \\ \tilde{I}_t & -\tilde{Z}_t^2 \end{matrix} \right)^{-1}$, and \tilde{Z}_t is a $2k$ -variate Gaussian white noise process with zero mean and identity covariances matrix. Consequently,

$$x_t = \tilde{Z}_t^1 (\tilde{I}_t^1 \tilde{Z}_t^1)^{-1} \tilde{I}_t^1 \tilde{Z}_t^1 \tilde{Z}_t^{-1} = \tilde{C}^{*1}(\tilde{I}_t) \tilde{Z}_t^1 \tilde{Z}_t^{-1},$$

$$x_{1t} = \tilde{Z}_t^2 (\tilde{I}_t^2 \tilde{Z}_t^2)^{-1} \tilde{I}_t^2 \tilde{Z}_t^2 \tilde{Z}_t^{-1} = \left(\begin{matrix} \tilde{I}_t^1 \\ \tilde{I}_t^2 \end{matrix} \right)^{-1} \tilde{C}^{*2}(\tilde{I}_t) \tilde{Z}_t^1 \tilde{Z}_t^{-1},$$

$$x_{2t} = (\tilde{I}_t^1 \tilde{Z}_t^1)^{-1} \tilde{I}_t^1 \tilde{Z}_t^1 \tilde{Z}_t^{-1} = \left(\begin{matrix} \tilde{I}_t^1 \\ \tilde{I}_t^2 \end{matrix} \right)^{-1} \tilde{C}^{*1}(\tilde{I}_t) \tilde{Z}_t^1 \tilde{Z}_t^{-1},$$

$$\text{where } \tilde{C}^*(\tilde{I}_t) = \tilde{C}^*(\mathbb{I}) = (\mathbb{I} - \tilde{I}_t) \tilde{C}^{*0}(\tilde{I}_t), \quad \tilde{C}^{*0}(\tilde{I}_t) = \sum_{j=0}^{\infty} \tilde{C}_j^* \tilde{I}_t^j.$$

The least squares estimation of \tilde{m} , $\hat{\tilde{m}}$, can also be expressed as

$$\begin{aligned} \hat{\tilde{m}} - \tilde{m} &= \left(\sum_{t=1}^T \alpha_t (\mathbb{I} - \tilde{C}_{2t-1}^1 (\sum_{t=1}^T \tilde{C}_{2t-1}^2 \tilde{C}_{2t-1}^1)^{-1} \tilde{C}_{2t-1}^1) \tilde{C}_{1t-1}^1 \right) \\ &\quad \left(\sum_{t=1}^T \alpha_{1t-1} (\mathbb{I} - \tilde{C}_{2t-1}^1 (\sum_{t=1}^T \tilde{C}_{2t-1}^2 \tilde{C}_{2t-1}^1)^{-1} \tilde{C}_{2t-1}^1) \tilde{C}_{1t-1}^1 \right)^{-1} \\ &= \left(\sum_{t=1}^T \alpha_t (\tilde{C}_{1t-1} - \tilde{Z}_2^1 \tilde{C}_{2t-1}^1) \right) \left(\sum_{t=1}^T (\tilde{C}_{1t-1} - \tilde{Z}_2^1 \tilde{C}_{2t-1}^1) (\tilde{C}_{1t-1} - \tilde{Z}_2^1 \tilde{C}_{2t-1}^1)^{-1} \right)^{-1} \end{aligned}$$

where $\tilde{Z}_2^1 = (\sum_{t=1}^T \tilde{C}_{2t-1}^2 \tilde{C}_{2t-1}^1)^{-1} \tilde{C}_{2t-1}^2 \tilde{C}_{1t-1}^1$. \tilde{Z}_2^1 is a random consistent estimation of \tilde{Z}_2^1 and can therefore be treated as equal to \tilde{Z}_2^1 in the derivation of the limiting distribution of $\hat{\tilde{m}}$. Since

$$\frac{1}{T} \sum_{t=1}^T (\tilde{C}_{1t-1} - \tilde{Z}_2^1 \tilde{C}_{2t-1}^1) (\tilde{C}_{1t-1} - \tilde{Z}_2^1 \tilde{C}_{2t-1}^1)' \Rightarrow \text{row}(\tilde{Z}^1 \tilde{C}) = \tilde{Z}_2^1 \sum_{j=0}^{\infty} \tilde{C}_j^* \tilde{C}_j^* \tilde{Z}_2^1,$$

and, $T^{-1/2} \left(\sum_{t=1}^T \alpha_t (\tilde{C}_{1t-1} - \tilde{Z}_2^1 \tilde{C}_{2t-1}^1) \right)' \Rightarrow \mathcal{N}(\mathbb{0}, \text{row}(\tilde{Z}^1 \tilde{C}) \tilde{Z})$, the limiting distribution of $\hat{\tilde{m}}$ becomes

$$\tilde{Z}_2^1 \tilde{Z}^{-1} (\hat{\tilde{m}} - \tilde{m}) \Rightarrow \mathcal{N}(\mathbb{0}, \text{row}(\tilde{Z}^1 \tilde{C})^{-1} \tilde{Z}).$$

With respect to the integrating vector,

$$\begin{aligned} \tilde{Z}_2^1 &= \left(\sum_{t=1}^T \tilde{C}_{2t-1}^2 \tilde{C}_{2t-1}^1 \right)^{-1} \sum_{t=1}^T \tilde{C}_{2t-1}^2 \tilde{C}_{1t-1}^1 \tilde{Z}_2^1^{-1} (\tilde{I}_t^1 \tilde{Z}_t^1)^{-1} \\ &= \left(\sum_{t=1}^T \left(\sum_{t=1}^T \tilde{C}_{2t-1}^2 \tilde{C}_{2t-1}^1 \right)^{-1} \left(\sum_{t=1}^T \tilde{C}_{2t-1}^2 (\tilde{C}_{2t-1}^1 \tilde{Z}_2^1 \tilde{I}_t^1 \tilde{I}_t^1) \right) \right)^{-1} \tilde{Z}_2^1 (\tilde{I}_t^1 \tilde{Z}_t^1)^{-1} \tilde{Z}_2^1 \end{aligned}$$

$$\begin{aligned}
&= \begin{pmatrix} \mathbb{I} \\ \left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1} \left(\sum_{t=1}^T \mathbb{E}_{t-1} (\mathbb{E}_{t-1}^4 \mathbb{E}_{t-1}^4) \mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1} (\mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1})^{-1} \right) \end{pmatrix} \\
&= \begin{pmatrix} \mathbb{I} \\ -\mathbb{E}_{t-1}^4 \end{pmatrix} \equiv \begin{pmatrix} \mathbb{I} \\ \left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1} \left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right) \mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1} (\mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1})^{-1} \end{pmatrix}
\end{aligned}$$

where $\left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1}$ indicates the last $(\mathbb{E}-\nu)$ rows of $\left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1}$ and it is a consistent estimation of the small bias difference between the small bias and the asymptotic orders of convergence as $T \rightarrow \infty$. Furthermore, $\mathbb{E}_{t-1} = \left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1} \left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)$, where $\left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1}$ indicates the first ν rows of $\left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1}$.

To analyze the limiting behavior of \mathbb{E}_{t-1} , we have to determine the limiting expressions of both $\left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1}$ and $\left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right) \mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1} (\mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1})^{-1}$. Starting with the latter expression, the limiting behavior can be analyzed using the stochastic trend specification of \mathbb{E}_{t-1} .

$$\begin{aligned}
\left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right) \mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1} (\mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1})^{-1} &= \left(\sum_{t=1}^T \mathbb{E}_{t-1} (\mathbb{E}_{t-1}^4 \mathbb{E}_{t-1})^{-1} \mathbb{E}_{t-1}^4 \right) \mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1} (\mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1})^{-1} \\
&\equiv \sum_{t=1}^T \mathbb{E}_{t-1}^4 (\mathbb{E}_{t-1}^4 \mathbb{E}_{t-1}^4)^{-1} \mathbb{E}_{t-1}^4 \mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1} (\mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1})^{-1}
\end{aligned}$$

Since $\mathbb{E}_{t-1}^4 \mathbb{E}_{t-1}$ is orthogonal to $\mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1}$, i.e. $(\mathbb{E}_{t-1}^4 \mathbb{E}_{t-1})' \mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1} = \mathbb{E}_{t-1}^4 \mathbb{E}_{t-1} = \mathbb{0}$, the cross-term vanishes appearing in the limiting expression as indicated,

$$\frac{1}{T} \sum_{t=1}^T \mathbb{E}_{t-1}^4 \mathbb{E}_{t-1}^4 \left(\sum_{t=1}^T \mathbb{E}_{t-1}^4 \right)^{-1} \mathbb{E}_{t-1}^4 \mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1} (\mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1})^{-1} \equiv \mathbb{0}$$

since $\frac{1}{T} \mathbb{E}_{t-1}^4 \mathbb{E}_{t-1}^4 \left(\sum_{t=1}^T \mathbb{E}_{t-1}^4 \right)^{-1} \mathbb{E}_{t-1}^4 \mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1} (\mathbb{E}_{t-1}^{-1} \mathbb{E}_{t-1})^{-1}$ is a $(\mathbb{E}-\nu)$ dimensional deterministic vector with covariance matrix \mathbb{E}_{t-1}^4 and $\mathbb{E}_{t-1} = (\mathbb{E}_{t-1}^4 \mathbb{E}_{t-1})^{\frac{1}{2}}$, \mathbb{E}_{t-1}^4 is a ν dimensional deterministic vector with covariance matrix \mathbb{E}_{t-1}^4 and \mathbb{E}_{t-1}^4 is stochastically independent of \mathbb{E}_{t-1} , $\mathbb{E}_{t-1} = (\mathbb{E}_{t-1}^4 \mathbb{E}_{t-1})^{\frac{1}{2}}$.

Then the limiting behavior of $\left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1}$ is determined by the stochastic trend specification.

$$\left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1} = \begin{pmatrix} \mathbb{E} & \mathbb{E} \\ \mathbb{E} & \mathbb{E} \end{pmatrix}^{-1} \left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1} \begin{pmatrix} \mathbb{E} & \mathbb{E} \\ \mathbb{E} & \mathbb{E} \end{pmatrix}^{-1} \begin{pmatrix} \mathbb{E} & \mathbb{E} \\ \mathbb{E} & \mathbb{E} \end{pmatrix}^{-1}$$

So, the limiting behavior of $\begin{pmatrix} \mathbb{E} & \mathbb{E} \\ \mathbb{E} & \mathbb{E} \end{pmatrix}^{-1} \left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1} \begin{pmatrix} \mathbb{E} & \mathbb{E} \\ \mathbb{E} & \mathbb{E} \end{pmatrix}^{-1}$ is,

$$\begin{aligned}
&\begin{pmatrix} \mathbb{E}^{-\frac{1}{2}} \mathbb{E} & \mathbb{E}^{-\frac{1}{2}} \mathbb{E} \\ \mathbb{E} & \mathbb{E} \end{pmatrix}^{-1} \left(\sum_{t=1}^T \mathbb{E}_{t-1} \mathbb{E}_{t-1}^4 \right)^{-1} \begin{pmatrix} \mathbb{E}^{-\frac{1}{2}} \mathbb{E} & \mathbb{E}^{-\frac{1}{2}} \mathbb{E} \\ \mathbb{E} & \mathbb{E} \end{pmatrix} \\
&\equiv \begin{pmatrix} \text{var}(\mathbb{E}^4 \mathbb{E}) & \mathbb{0} \\ \mathbb{0} & \mathbb{E}^4 \mathbb{E} (\mathbb{E}^4 \mathbb{E})^{-1} \mathbb{E} \left(\mathbb{E}^4 \mathbb{E} \right) \mathbb{E} (\mathbb{E}^4 \mathbb{E})^{-1} \mathbb{E}^4 \mathbb{E} \end{pmatrix}
\end{aligned}$$

$$\begin{aligned}
& \mathbb{T}^{-1} \left[\sum_{t=1}^T \mathbb{S}_t^{\otimes 2} \mathbb{C}_t^{\otimes 2}(\mathbb{I}) \mathbb{S}_t^{-1} \mathbb{C}_{t-1}^{\otimes 2} \right] \mathbb{S}_t^{-1} \mathbb{C}_t^{\otimes 2}(\mathbb{I}) \mathbb{S}_t \neq \text{rot}(\mathbb{S}_t^{\otimes 2} \mathbb{C}_t), \\
& \mathbb{T}^{-2} \mathbb{S}_t^{\otimes 2} \mathbb{S}_t^{-1} (\mathbb{C}_t^{\otimes 2} \mathbb{S}_t^{-1})^{-1} \sum_{t=1}^T (\mathbb{C}_t^{\otimes 2} \mathbb{S}_t^{-1} \left[\sum_{\lambda=1}^{t-1} \mathbb{C}_\lambda^{\otimes 2} \right]) \left(\sum_{\lambda=1}^{t-1} \mathbb{C}_\lambda^{\otimes 2} \mathbb{S}_\lambda^{-1} \mathbb{C}_\lambda \right) (\mathbb{C}_t^{\otimes 2} \mathbb{S}_t^{-1})^{-1} \mathbb{S}_t^{\otimes 2} \mathbb{S}_t^{-1} \\
& \neq \mathbb{S}_t^{\otimes 2} \mathbb{S}_t^{-1} (\mathbb{C}_t^{\otimes 2} \mathbb{S}_t^{-1})^{-1} \mathbb{C}_1^{-1} \left(\prod_{j=1}^{t-1} \mathbb{S}_j^{\otimes 2} \mathbb{S}_j^{-1} \right) \mathbb{C}_1 (\mathbb{C}_t^{\otimes 2} \mathbb{S}_t^{-1})^{-1} \mathbb{S}_t^{\otimes 2} \mathbb{S}_t^{-1}, \\
& \mathbb{T}^{-1} \frac{1}{2} \left[\sum_{t=1}^T \mathbb{S}_t^{\otimes 2} \mathbb{C}_t^{\otimes 2}(\mathbb{I}) \mathbb{S}_t^{-1} \mathbb{C}_{t-1}^{\otimes 2} \right] \left(\sum_{\lambda=1}^{t-1} \mathbb{C}_\lambda^{\otimes 2} \mathbb{S}_\lambda^{-1} \mathbb{C}_\lambda \right) (\mathbb{C}_t^{\otimes 2} \mathbb{S}_t^{-1})^{-1} \mathbb{S}_t^{\otimes 2} \mathbb{S}_t^{-1} \neq \mathbb{0}.
\end{aligned}$$

Consequently,

$$\begin{aligned}
& \left[\begin{array}{c} \mathbb{T}^{-1} \mathbb{S}_t \\ \mathbb{T}^{-1} \mathbb{S}_t \end{array} \right]^{\otimes 2} \left(\sum_{t=1}^T \mathbb{C}_{t-1}^{\otimes 2} \mathbb{C}_{t-1}^{\otimes 2} \right) \left[\begin{array}{c} \mathbb{T}^{-1} \mathbb{S}_t \\ \mathbb{T}^{-1} \mathbb{S}_t \end{array} \right]^{-1} \\
& \neq \left[\begin{array}{c} \text{rot}(\mathbb{S}_t^{\otimes 2} \mathbb{C}_t)^{-1} \\ \mathbb{0} \end{array} \right] \mathbb{0} \left(\mathbb{S}_t^{\otimes 2} \mathbb{S}_t^{-1} \right)^{-1} \mathbb{S}_t^{-1} \mathbb{C}_1^{-1} \left(\prod_{j=1}^{t-1} \mathbb{S}_j^{\otimes 2} \mathbb{S}_j^{-1} \right)^{-1} \mathbb{C}_1^{-1} \mathbb{C}_t^{\otimes 2} \mathbb{S}_t^{-1} \left(\mathbb{S}_t^{\otimes 2} \mathbb{S}_t^{-1} \right)^{-1} \left[\begin{array}{c} \mathbb{0} \\ \mathbb{0} \end{array} \right]
\end{aligned}$$

and

$$\begin{aligned}
& \left(\sum_{t=1}^T \mathbb{C}_{t-1}^{\otimes 2} \mathbb{C}_{t-1}^{\otimes 2} \right)^{-1} \\
& \neq \mathbb{S}(\mathbb{T}^2) \mathbb{S} \text{rot}(\mathbb{S}_t^{\otimes 2} \mathbb{C}_t)^{-1} \mathbb{S}_t^{\otimes 2} \\
& \mathbb{S}(\mathbb{T}^2) \mathbb{S} \left(\mathbb{S}_t^{\otimes 2} \mathbb{S}_t^{-1} \right)^{-1} \mathbb{S}_t^{-1} \mathbb{C}_1^{-1} \left(\prod_{j=1}^{t-1} \mathbb{S}_j^{\otimes 2} \mathbb{S}_j^{-1} \right)^{-1} \mathbb{C}_1^{-1} \mathbb{C}_t^{\otimes 2} \mathbb{S}_t^{-1} \left(\mathbb{S}_t^{\otimes 2} \mathbb{S}_t^{-1} \right)^{-1} \mathbb{S}_t^{\otimes 2}.
\end{aligned}$$

where $\mathbb{S}(\mathbb{T}^2)$ indicates that the limiting expression of this part is proportional to \mathbb{T}^2 . The latter part possesses the limiting expression of $\left(\sum_{t=1}^T \mathbb{C}_{t-1}^{\otimes 2} \mathbb{C}_{t-1}^{\otimes 2} \right)^{-1}$, which can be characterized by

$$\mathbb{T}^2 \left(\sum_{t=1}^T \mathbb{C}_{t-1}^{\otimes 2} \mathbb{C}_{t-1}^{\otimes 2} \right)^{-1} \neq \left(\mathbb{S}_t^{\otimes 2} \mathbb{S}_t^{-1} \right)^{-1} \mathbb{S}_t^{-1} \mathbb{C}_1^{-1} \left(\prod_{j=1}^{t-1} \mathbb{S}_j^{\otimes 2} \mathbb{S}_j^{-1} \right)^{-1} \mathbb{C}_1^{-1} \mathbb{C}_t^{\otimes 2} \mathbb{S}_t^{-1} \left(\mathbb{S}_t^{\otimes 2} \mathbb{S}_t^{-1} \right)^{-1} \mathbb{S}_t^{\otimes 2}$$

as $\mathbb{S}_t = \begin{pmatrix} \mathbb{S}_t^{\otimes 2} \\ \mathbb{I}_{2 \times 2} \end{pmatrix}$. So, the limiting expression for the corresponding vector estimator becomes,

$$\begin{aligned}
\mathbb{T}(\mathbb{S}_t - \mathbb{S}_t) & \neq \left[\begin{array}{c} \mathbb{0} \\ \left(\mathbb{S}_t^{\otimes 2} \mathbb{S}_t^{-1} \right)^{-1} \mathbb{S}_t^{-1} \mathbb{C}_1^{-1} \left(\prod_{j=1}^{t-1} \mathbb{S}_j^{\otimes 2} \mathbb{S}_j^{-1} \right)^{-1} \left(\prod_{j=1}^{t-1} \mathbb{S}_j^{\otimes 2} \mathbb{S}_j^{-1} \right) \mathbb{C}_1 \end{array} \right] \left[\begin{array}{c} \mathbb{0} \\ \mathbb{0} \end{array} \right] \\
& \neq \left[\begin{array}{c} \mathbb{0} \\ \mathbb{0} \end{array} \right] \mathbb{0} \left[\begin{array}{c} \mathbb{0} \\ \mathbb{0} \end{array} \right],
\end{aligned}$$

where $\mathbb{E} = (\mathbb{E}^1 \mathbb{E}^2)^{-1} \mathbb{E}^1 m \mathbb{E}_1^{-1} (\mathbb{E}^1 \mathbb{E}^2)^{-1} \mathbb{E}_1^{-1} m^1 \mathbb{E}^1 (\mathbb{E}^1 \mathbb{E}^2)^{-1}$ and can be approximated by $(\frac{1}{\Delta t} \sum_{i=1}^T \mathbb{E}_{i,t-1} (\mathbb{I} - \mathbb{E}_{i,t-1}^1 (\sum_{j=1}^T \mathbb{E}_{i,t-1}^1 \mathbb{E}_{i,t-1}^1)^{-1} \mathbb{E}_{i,t-1}^1) \mathbb{E}_{i,t-1}^1)^{-1} (\neq \mathbb{E})$.

Proof of Theorem 2 (only the second part of Theorem 2 is proved).

Let the ODE of x_t reads,

$$\dot{x}_t = m x_t + m(\mathbb{E}^1 x_{t-1} + \mathbb{E}^2) + \mathbb{E}^3,$$

where $x = m x + m \mathbb{E}^1$, it has the stochastic tracted representation, see [4],

$$\mathbb{E} x_t = \mathbb{E}^2(\mathbb{E}^1)(x + \mathbb{E}^1 \mathbb{E}^2), \quad \mathbb{E} = \begin{pmatrix} \mathbb{I} & -\mathbb{E}^1 \\ \mathbb{E}^2 & \mathbb{E}^3 \end{pmatrix},$$

where \mathbb{E}^i is a k^i -variate Gaussian white noise process with zero mean and identity covariance matrix. Consequently,

$$x_t = \mathbb{E}^1 (m^1 \mathbb{E}^1)^{-1} m^1 (x_0 + \mathbb{E}^1 \sum_{i=1}^t \mathbb{E}^1 \mathbb{E}^2) + \mathbb{E}^2(\mathbb{I}) m \mathbb{E}^1 + \mathbb{E}^3(\mathbb{E}^1) \mathbb{E}^1 \mathbb{E}^2,$$

$$x_{1t} = \mathbb{E}_2^1 (m^1 \mathbb{E}^1)^{-1} m^1 (x_0 + \mathbb{E}^1 \sum_{i=1}^t \mathbb{E}^1 \mathbb{E}^2) + \sum_{i=1}^t \mathbb{E}^1 \mathbb{E}^2 (\mathbb{E}^2(\mathbb{I}) m \mathbb{E}^1 + \mathbb{E}^3(\mathbb{E}^1) \mathbb{E}^1 \mathbb{E}^2),$$

$$x_{2t} = (m^1 \mathbb{E}^1)^{-1} m^1 (x_0 + \mathbb{E}^1 \sum_{i=1}^t \mathbb{E}^1 \mathbb{E}^2) + \sum_{i=1}^t \mathbb{E}^1 \mathbb{E}^2 (\mathbb{E}^2(\mathbb{I}) m \mathbb{E}^1 + \mathbb{E}^3(\mathbb{E}^1) \mathbb{E}^1 \mathbb{E}^2),$$

where $\mathbb{E}^i(\mathbb{E}^j) = \mathbb{E}^i(\mathbb{I}) + (\mathbb{I} - \mathbb{E}^j) \mathbb{E}^i(\mathbb{E}^j)$, $\mathbb{E}^i(\mathbb{E}^j) = \sum_{i=1}^k \mathbb{E}^i \mathbb{E}^j$, $\mathbb{E}^i \mathbb{E}^i(\mathbb{I}) m = \mathbb{I}$. The least squares estimation of m , \mathbb{E} , can also be expressed as

$$\begin{aligned} \hat{m} - m &= \\ & \left(\sum_{i=1}^T m_t (\mathbb{I} - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1) \right)^{-1} \left(\sum_{i=1}^T m_t (\mathbb{I} - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1) \right) \left(\sum_{i=1}^T m_t (\mathbb{I} - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1) \right)^{-1} \left(\sum_{i=1}^T m_t (\mathbb{I} - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1) \right) \\ & \left(\sum_{i=1}^T \mathbb{E}_{i,t-1}^1 (\mathbb{I} - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1) \right)^{-1} \left(\sum_{i=1}^T \mathbb{E}_{i,t-1}^1 (\mathbb{I} - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1) \right) \left(\sum_{i=1}^T \mathbb{E}_{i,t-1}^1 (\mathbb{I} - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1) \right)^{-1} \left(\sum_{i=1}^T \mathbb{E}_{i,t-1}^1 (\mathbb{I} - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1) \right) \\ & = \left(\sum_{i=1}^T m_t (\mathbb{E}_{i,t-1}^1 - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1 \mathbb{E}_{i,t-1}^1) \right)^{-1} \left(\sum_{i=1}^T m_t (\mathbb{E}_{i,t-1}^1 - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1 \mathbb{E}_{i,t-1}^1) \right) \\ & \left(\sum_{i=1}^T \mathbb{E}_{i,t-1}^1 (\mathbb{E}_{i,t-1}^1 - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1 \mathbb{E}_{i,t-1}^1) \right)^{-1} \end{aligned}$$

with $(\sum_{i=1}^T \mathbb{E}_{i,t-1}^1) = (\sum_{i=1}^T \mathbb{E}_{i,t-1}^1) (\mathbb{I} - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1) \mathbb{E}_{i,t-1}^1$. $\mathbb{E}_{i,t-1}^1$ is a symmetric-singular estimation of $\mathbb{E}_{i,t-1}^1$. Since

$$\begin{aligned} \frac{1}{\Delta t} \sum_{i=1}^T (\mathbb{E}_{i,t-1}^1 - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1 \mathbb{E}_{i,t-1}^1) & \left(\mathbb{E}_{i,t-1}^1 - \sum_{j=1}^T \mathbb{E}_{i,t-1}^1 \mathbb{E}_{i,t-1}^1 \right) \\ \Rightarrow \text{cov}(\hat{m} - m) & = \mathbb{E}^1 \sum_{i=1}^T \mathbb{E}_{i,t-1}^1 \mathbb{E}_{i,t-1}^1 \mathbb{E}^1, \text{ and,} \end{aligned}$$

$\mathbb{Z}^{-1} \left(\prod_{i=1}^T \alpha_i (\mathbb{Z}^{i-1} - \prod_{j=1}^i \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^{i-1}}{\mathbb{Z}^i} \right)^{-1}$ is $\mathfrak{B}(\mathbb{0}, \text{cov}(\mathbb{Z}^i \alpha - \alpha^i) \mathbb{Z}^{-1})$, the limiting distribution of $\hat{\theta}$ becomes

$$\mathfrak{N}(\hat{\theta} - \theta) \rightsquigarrow \mathfrak{B}(\mathbb{0}, \text{cov}(\mathbb{Z}^i \alpha - \alpha^i)^{-1} \mathbb{Z}^{-1}).$$

With respect to the integrating vector,

$$\begin{aligned} \left(\prod_{i=1}^T \frac{\mathbb{Z}^{i-1}}{\mathbb{Z}^i} \right)^{-1} &= \left(\prod_{i=1}^T \left(\prod_{j=1}^i \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \left(\prod_{j=1}^{i-1} \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \right)^{-1} \left(\prod_{i=1}^T \left(\prod_{j=1}^i \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^{i-1}}{\mathbb{Z}^i} \right)^{-1} \\ &= \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \end{aligned}$$

$$\begin{aligned} \left(\prod_{i=1}^T \frac{\mathbb{Z}^{i-1}}{\mathbb{Z}^i} \right)^{-1} &= \left(\prod_{i=1}^T \left(\prod_{j=1}^i \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \left(\prod_{j=1}^{i-1} \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \right)^{-1} \left(\prod_{i=1}^T \left(\prod_{j=1}^i \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^{i-1}}{\mathbb{Z}^i} \right)^{-1} \\ &= \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \\ &= \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \\ &= \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \\ &= \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^i}{\mathbb{Z}^i} \right)^{-1} \end{aligned}$$

as $\mathbb{Z}^i \mathbb{Z}^{-1} \mathbb{Z} = \mathbb{0}$ since $\mathbb{Z}^{-1} = \mathbb{Z}^i \mathbb{Z}^i$, $\mathbb{Z}^i = \text{diag}(\mathbb{Z}_i^i) = \prod_{j=1}^i \mathbb{Z}_j^i \mathbb{Z}_j^i$, $\mathbb{Z}^i \mathbb{Z}^i = \mathbb{Z}_i^i$, $\mathbb{Z}^i \mathbb{Z}^i \mathbb{Z} = \mathbb{Z}_i^i \mathbb{Z} = \mathbb{0}$, $\mathbb{Z}^i \mathbb{Z} = \mathbb{Z}^i = (\mathbb{Z}_1^i \dots \mathbb{Z}_i^i)^i$, $\mathbb{Z}^i \mathbb{Z}^{-1} \mathbb{Z} = \mathbb{Z}_i^i \mathbb{Z}^i = \prod_{j=1}^i \mathbb{Z}_j^i \mathbb{Z}_j^i \mathbb{Z}_j^i = \mathbb{0}$ as $\mathbb{Z}_i^i \mathbb{Z}_i^i = \mathbb{0}$ *etc.* $\left(\prod_{i=1}^T \left(\prod_{j=1}^i \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \left(\prod_{j=1}^{i-1} \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \right)^{-1}$ indicates the last $(\mathbb{Z} - \mathbb{0} = \mathbb{1})$ rows of

$\left(\prod_{i=1}^T \left(\prod_{j=1}^i \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \left(\prod_{j=1}^{i-1} \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \right)^{-1}$ and $\hat{\theta}$ is a consistent estimation of θ such that the difference between $\hat{\theta}$ and θ will only affect orders of convergence according to \mathbb{Z} . To analyze the limiting distribution of $\hat{\theta}$, we have to determine the limiting expressions of both $\left(\prod_{i=1}^T \left(\prod_{j=1}^i \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \left(\prod_{j=1}^{i-1} \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \right)^{-1}$ and $\left(\prod_{i=1}^T \left(\prod_{j=1}^i \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^{i-1}}{\mathbb{Z}^i} \right)^{-1}$. Starting with the latter expression, its limiting distribution can be analyzed using the stochastic trend specification.

$$\left(\prod_{i=1}^T \left(\prod_{j=1}^i \frac{\mathbb{Z}^{j-1}}{\mathbb{Z}^j} \right)^{-1} \right)^{-1} \left(\prod_{i=1}^T \frac{\mathbb{Z}^{i-1}}{\mathbb{Z}^i} \right)^{-1}$$

$\mathbb{Z}^{-1} \mathbb{h} (\mathbb{h}^4 \mathbb{Z}^{-1} \mathbb{h})^{-1} \mathbb{h}^4 \mathbb{Z}^{-1} \mathbb{h}) \left(\prod_{t=1}^{\tau} \mathbb{Z} \mathbb{h}_t \mathbb{h}_{t-1}^4 \right)$, each of which limiting behavior is analyzed separately. Starting with the latter expression,

$$\begin{aligned} & \frac{1}{\mathbb{Z}} \text{tr} \left((\mathbb{Z}^{-1} - \mathbb{Z}^{-1} \mathbb{h} (\mathbb{h}^4 \mathbb{Z}^{-1} \mathbb{h})^{-1} \mathbb{h}^4 \mathbb{Z}^{-1} \mathbb{h}) \left(\prod_{t=1}^{\tau} \mathbb{Z} \mathbb{h}_t \mathbb{h}_{t-1}^4 \right) \right) \\ &= \frac{1}{\mathbb{Z}} \text{tr} \left((\mathbb{h} (\mathbb{h}^4 \mathbb{Z} \mathbb{h})^{-1} \mathbb{h}^4 \left(\prod_{t=1}^{\tau} \mathbb{Z} \mathbb{h}_t \mathbb{h}_{t-1}^4 \right)) \right) \\ &\leq \frac{1}{\mathbb{Z}} \text{tr} \left(\mathbb{h} (\mathbb{h}^4 \mathbb{Z} \mathbb{h})^{-1} \sum_{t=1}^{\tau} (\mathbb{h}^4 \mathbb{Z}^{\frac{1}{2}} \mathbb{h} \left(\prod_{l=1}^{t-1} \mathbb{Z}^{\frac{1}{2}} \mathbb{h} (\mathbb{h}^4 \mathbb{h})^{-1} \mathbb{h}^4 \right)) \right) \\ &\leq (\mathbb{Z} (\mathbb{h}^4 \mathbb{Z})^{-1} \mathbb{h} \mathbb{h} (\mathbb{h}^4 \mathbb{Z} \mathbb{h})^{-1}) \text{tr} \left(\mathbb{Z}_1 \left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right) \mathbb{Z}_1^4 \right) \end{aligned}$$

It is

$$\begin{aligned} & \mathbb{Z}^4 \left(\left(\prod_{t=1}^{\tau} \mathbb{Z} \mathbb{h}_{t-1} \mathbb{h}_{t-1}^4 \right)^{-1} \mathbb{Z} \right) \\ &\leq (\mathbb{Z} (\mathbb{Z}^4 \mathbb{Z})^{-1} \mathbb{Z} \mathbb{h} \mathbb{Z}_1^{-1} \left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right)^{-1} \mathbb{Z}_1^{-1} \mathbb{h}^4 \mathbb{Z} (\mathbb{Z}^4 \mathbb{Z})^{-1} \mathbb{Z}^4 \mathbb{Z}). \end{aligned}$$

So,

$$\begin{aligned} & \mathbb{Z}(\mathbb{h}, \mathbb{Z}) \\ &\leq \text{tr} \left(\mathbb{Z}_1 \left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right) \mathbb{Z}_1^4 \right) (\mathbb{Z} (\mathbb{h}^4 \mathbb{Z})^{-1} \mathbb{h} \mathbb{h} (\mathbb{h}^4 \mathbb{Z} \mathbb{h})^{-1})^4 \\ & \quad (\mathbb{Z} (\mathbb{Z}^4 \mathbb{Z})^{-1} \mathbb{Z} \mathbb{h} \mathbb{Z}_1^{-1} \left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right)^{-1} \mathbb{Z}_1^{-1} \mathbb{h}^4 \mathbb{Z} (\mathbb{Z}^4 \mathbb{Z})^{-1} \mathbb{Z}^4 \mathbb{Z}) \\ & \quad (\mathbb{Z} (\mathbb{h}^4 \mathbb{Z})^{-1} \mathbb{h} \mathbb{h} (\mathbb{h}^4 \mathbb{Z} \mathbb{h})^{-1}) \text{tr} \left(\mathbb{Z}_1 \left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right) \mathbb{Z}_1^4 \right) \\ &\leq \text{tr} \left(\mathbb{Z}_1 \left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right) \mathbb{Z}_1^4 \right) (\mathbb{Z}_1^{-1} \left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right)^{-1} \mathbb{Z}_1^{-1} \mathbb{h} (\mathbb{h}^4 \mathbb{Z} \mathbb{h})^{-1}) \\ & \quad \text{tr} \left(\mathbb{Z}_1 \left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right) \mathbb{Z}_1^4 \right) \\ &\leq \text{tr} \left(\left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right) \right)^4 \left(\left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right)^{-1} \mathbb{Z}_{k-s} \right) \text{tr} \left(\left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right) \right)^4 \\ &\leq \text{tr} \left[\left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right) \left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right)^{-1} \left(\prod_{j=1}^{\tau} \mathbb{Z} \mathbb{h}_j \mathbb{h}_{j-1}^4 \right) \right] \end{aligned}$$

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