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Decision rules and uncertainty in the economic evaluation of health care technologies

Beslisregels en onzekerheid bij de economische
evaluatie van interventies in de gezondheidszorg

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■ Chapter 1

Introduction

Health is often regarded as the most precious good of all. This is frequently illustrated by the widespread opinion that no expense should be spared to maintain one's health. However, in most societies the awareness that health care expenditure should be controlled in one way or another is highly prevalent. In most Western countries health care expenditure expanded substantially over the past decades, not only in absolute terms but also as a proportion of the Gross Domestic Product (GDP). In 2000, The Netherlands, Switzerland and the USA spent 8.1%, 10.7 % and 13.0% of their GDP on health care. In the same countries in 1980 the expenditure for health care was 7.5%, 7.6% and 8.7%, respectively (www.oecd.org). In the face of mounting pressure to contain health care resource consumption, policy-makers are increasingly forced to consider an economics perspective when judging whether a new medical technology should be financed.

The most widely used framework to compare the costs and effects of health care interventions is cost-effectiveness analysis, where two or more interventions are compared in terms of both cost and effect in an incremental analysis. The results of the cost-effectiveness analysis are then presented as cost-effectiveness ratios, i.e. the cost per unit of effectiveness or quality-adjusted life-year (QALY) gained. A program with a low cost-effectiveness ratio yields more returns on investment than a program with a high cost-effectiveness ratio.

In the basic cost-effectiveness model, the decision as to whether a program should be funded or not rests on whether a particular cost-effectiveness ratio is acceptable, i.e. smaller than the threshold cost-effectiveness ratio used as a cut-off point for resource allocation (Weinstein, 1995). Programs with a cost-effectiveness ratio smaller than the threshold cost-effectiveness ratio are funded, while programs with a cost-effectiveness ratio larger than this threshold are not implemented. This decision rule is based on the solution to a simple optimization problem (Weinstein and Zeckhauser, 1973; Weinstein, 1995). A decision-maker with an explicit budget constraint faces a menu of programs, all of which use resources and contribute to the QALYs gained, and the objective is to maximize QALYs for any given level of resources. The optimal allocation of resources ranks programs according to their cost-effectiveness ratio and implements them starting with the most cost-effective program, until the budget is exhausted (Johannesson and Weinstein, 1993; Weinstein, 1995; Karlsson and Johannesson, 1996). The cost-effectiveness ratio of the last implemented program represents the threshold cost-effectiveness ratio used as a cut-off point for resource allocation. This classical decision rule of cost-effectiveness analysis was described by Weinstein and Zeckhauser (1973) more than three decades ago.

This decision rule has initially been proposed for the situation where any combination of programs is possible, which requires the average cost-effectiveness ratio of the programs under investigation to be calculated and compared

(Weinstein, 1995). However, for the case of mutually exclusive programs, i.e. competing alternative treatment modalities for the same disease condition, the decision rule following from the optimization problem requires that incremental cost-effectiveness ratios be calculated (Weinstein, 1995; Karlsson and Johannesson, 1996). This leads us to the concept of dominance and extended dominance. A treatment option is dominated if it is less effective and more costly compared to an alternative; such a treatment will never be adopted. A program may also be excluded by extended dominance when the incremental cost-effectiveness ratio is higher than that of a more effective treatment. This means that greater effectiveness can be achieved for the same cost by using other treatment options (Weinstein, 1995; Karlsson and Johannesson, 1996).

Karlsson and Johannesson (1996) distinguish between using a decision rule based on budget as opposed to a threshold cost-effectiveness ratio. These two approaches are inherently connected in the sense that a decision rule based on budget yields a threshold cost-effectiveness ratio, whereas one based on a threshold cost-effectiveness ratio implies a budget. However, it is perhaps more natural to assume that policy-makers hold budgets from which to fund health care programs, rather than assuming that the budget is determined *ex post* after all programs with a cost-effectiveness ratio below the threshold value are implemented. The widespread acceptance of the decision rule described above is documented by the fact that incremental cost-effectiveness analysis, with the results expressed as incremental cost-effectiveness ratios, has become the most popular analytic vehicle to compare the costs and effects of health care programs.

The classical decision rule was initially described from a deterministic perspective, i.e. it was assumed that the costs and effects of a program are certain. In recent years, however, with the increased availability of patient-level data from randomized controlled trials, there has been extensive research on how to handle uncertainty in cost-effectiveness analysis (Briggs and Gray, 1999). Since future costs and effects of health care programs are inherently uncertain, the decision rule of cost-effectiveness analysis needs to be recast in that light. Moreover, some researchers have seriously criticized the assumptions on which the classical decision rule is based (Birch and Gafni, 1992; Gafni and Birch, 1993; Birch and Gafni, 1993). These include the notion of constant returns to scale and complete divisibility. Constant returns to scale means that the cost-effectiveness ratio is independent of the size of the program, and complete divisibility means that the program can be bought in infinitely small increments. These assumptions may not always hold true in the real world.

This thesis critically appraises the assumptions of the classical decision rule of cost-effectiveness analysis, and suggests alternative approaches to choosing among health care programs when costs and effects are uncertain and resources constrained. How cost-effectiveness information should be used in

the presence of uncertainty is an important area of debate. One main focus of this thesis is the exploration of approaches that relax the assumptions of the classical decision rule of cost-effectiveness analysis. Also, the applicability of portfolio theory is considered as a means to select among health care programs when outcomes are subject to a distribution. This is followed by two practical stochastic cost-effectiveness analyses where the decision rule is discussed in light of the results of the analysis.

Areas of debate

The assumptions of the decision rule

Birch and Gafni have criticized the use of cost-effectiveness ratios as a decision rule with the argument that the assumptions on which this decision rule is based, i.e. constant returns to scale and complete divisibility, are unlikely to be met in real-world situations (Birch and Gafni, 1992; Gafni and Birch, 1993; Birch and Gafni, 1993). In other words, the linear programming approach to budget allocation may not be appropriate in practice. Birch and Gafni (1992,1993) suggest an integer programming approach to budget allocation, which handles health care programs as indivisible units, thereby relaxing the assumptions of constant returns to scale and complete divisibility. Equity is an important argument for treating health care programs as completely indivisible.

Indeed, Ubel et al. (1996) asked prospective jurors, medical ethicists and experts in medical decision-making to choose between two hypothetical screening tests for colon cancer in a low-risk population. Test 1 costs \$200,000 and prevents 1000 deaths from colon cancer; test 2 costs \$400,000 and prevents 2200 deaths from colon cancer. However, the available budget is \$200,000 and test 2 can therefore only be offered to half of the population, while test 1 can be offered to everyone in the population. But test 2 brings more benefit: 1100 deaths averted versus 1000 with test 1. The study showed that people place greater importance on equity than efficiency: 56% of the prospective jurors, 53% of the medical ethicists and 41% of the experts in medical decision-making recommended offering the less effective screening test to the whole population (Ubel et al., 1996). This clearly indicates that the assumption of complete divisibility might be problematic in reality, and that the assumption of complete indivisibility may rather reflect the decision-making behavior of people when confronted with equity considerations.

The assumption of constant returns to scale may also fail to be met in some circumstances. For example, radiation therapy of cancer patients requires high capital costs because expensive equipment has to be bought before this treatment option can be made available to patients. Investing in modern technology might be cost-effective if many patients require this therapy. However, if only a few patients need this treatment option then the program might not be

cost-effective due to the high capital costs and low number of QALYs gained. This is an example of increasing returns to scale, i.e. the cost-effectiveness ratio decreases with increasing size of the program. On the other hand, treatments that are solely based on prescription drugs may satisfy the assumption of constant returns to scale, assuming that the cost of the drug will be independent of the size of the program. However, even this assumption might be criticized since a large-scale production of a drug usually results in low costs for a marginal batch of the respective pharmaceutical (Davidoff, 2001).

The classical decision rule is equivalent to a linear programming approach to budget allocation. Birch and Gafni (1992, 1993), on the other hand, advocate a pure integer programming framework that treats programs as completely indivisible. In response to this debate, Stinnett and Paltiel (1996) have bridged these two points of view by suggesting a mixed integer programming framework. This permits the incorporation of both integer and continuous variables into the programming problem and allows the modeling of more complex scenarios, such as partial indivisibilities and non-constant returns to scale. For example, a certain implementation level of an immunization program is usually required in order to achieve herd immunity (the protection of non-immunized people by immunized people), so the decision-maker may not want to introduce an immunization program below the indicated threshold level, i.e. the program is partially indivisible. Similarly, the mixed integer programming framework allows the modeling of increasing and decreasing returns to scale. As already mentioned, a typical example of a program with an increasing return to scale is one with a large initial fixed cost followed by a constant variable cost (such a radiation therapy).

However, it should be clear that mixed integer programming requires information that is not readily available in most health care systems. The linear programming approach requires less input information but relies on assumptions that may not always hold in real-world situations. The integer programming approach requires the same information on costs and effects as the linear programming approach, but assumes complete indivisibility, an assumption that may be too restrictive in some circumstances (such as in the case of the immunization program discussed above). All approaches, however, require that the budget constraint and the costs and effects of the complete menu of programs are known. Even this information might not be available in many health care systems. This has led some researchers to suggest a more pragmatic approach to using cost-effectiveness information.

An *ad hoc* approach to deciding whether a health care technology should be implemented or not has been suggested by Laupacis et al. (1992). The authors distinguish between grade A-E technologies. Grade A technology is more effective and less costly than the alternative technology and should therefore be adopted. Grade B-D technologies are more costly (expressed in Canadian

dollars) and more effective than the existing one; a grade B technology has an incremental cost-effectiveness ratio of less than \$20,000 per QALY gained, a grade C technology has an incremental cost-effectiveness ratio between \$20,000 and \$100,000 per QALY gained, and a grade D technology has an incremental cost-effectiveness ratio of more than \$100,000 per QALY gained. Grade E technology is less effective and more costly than the alternative and should never be adopted. While the decision is clear for grade A and E technologies, the question is whether grade B-D technologies should be implemented. Laupacis et al. (1992) state that there is strong evidence for adoption of a grade B technology, moderate evidence for adoption of a grade C technology, and weak evidence for adoption of a grade D technology.

However, as Gafni and Birch (1993) argue, using a fixed value for the threshold cost-effectiveness ratio will lead to an uncontrolled growth of health care expenditures as more health care programs with a favorable cost-effectiveness ratio become available and are funded. This is because the critical ratio depends on the menu of available programs and the budget constraint. If a new technology with a favorable cost-effectiveness ratio becomes available, then resources must be deployed from the least cost-effective programs in order to fund the new program. If the new program requires as many or more resources than the least cost-effective program, then the latter will cease to be funded. In order to enter the portfolio of funded programs, any new program must now have a cost-effectiveness ratio lower than the new threshold cost-effectiveness ratio, the cost-effectiveness ratio of the last implemented program. If this link between the critical ratio, the budget constraint and the menu of available programs is ignored, an ever-increasing demand is made on resource consumption. This is inconsistent with the widely stated objective of cost-effectiveness analysis: to maximize benefits for any given level of resources.

An alternative decision rule, which is consistent with the objective of improving the efficiency of resource allocation, has been suggested by those who have criticized the approaches mentioned above (Gafni and Birch, 1993). In order to fund a new program, an already existing program must be identified that, if cancelled, releases sufficient resources to fund the new program. In addition, the health benefits gained by introducing the new program should exceed those lost by relinquishing the old program. This method is a second-best solution in the sense that more than one program in the current portfolio might satisfy these conditions. However, it represents an unambiguous improvement in the allocation of resources since it results in more health benefits without calling for additional resources. This approach forces the decision-maker to choose how to allocate resources and to think in terms of opportunity costs, i.e. the highest-valued alternative use of scarce resources.

The decision rule and uncertainty

The debate about the appropriate decision rule has so far taken place in a deterministic world where the costs and effects of health care programs are certain. In recent years, with the increasing availability of patient-level data on costs and effects from randomized controlled trials, there has been a growing body of research on statistical methods for handling uncertainty in cost-effectiveness analysis (O'Brien et al., 1994; Briggs and Gray, 1999). It soon became evident that confidence interval estimation for cost-effectiveness ratios may pose technical difficulties, due to the discontinuous distribution of the cost-effectiveness ratio, as well as problems of interpretation (Briggs and Gray, 1999). As the effect difference approaches zero, the cost-effectiveness ratio approaches infinity; when the effect difference is equal to zero, the ratio is not defined. If the joint distribution of cost and effect extends over all four quadrants of the cost-effectiveness plane, i.e. when the effect and cost difference is not statistically significant, the confidence interval is too wide as no ratio can be excluded. Moreover, the interpretation of negative cost-effectiveness ratios is ambiguous (Briggs and Gray, 1999). The magnitude of negative cost-effectiveness ratios does not provide information in the same way that positive cost-effectiveness ratios do. For example, in the southeast quadrant (ΔE positive, ΔC negative) of the cost-effectiveness plane, points that are further from the origin on a line defining a single cost-effectiveness ratio dominate those points that are closer to the origin (Glick et al., 2001). Moreover, in the same southeast quadrant, a higher cost difference for a given level of effect difference is preferable (i.e. a lower value of the ratio is preferable). On the other hand, a higher effect difference for a given level of cost difference is preferable (i.e. a higher value of the ratio is preferable).

In response to these limitations two approaches have been suggested in the literature: the cost-effectiveness acceptability curve (van Hout et al., 1994) and the net health benefit approach (Stinnett and Mullahy, 1998). The cost-effectiveness acceptability curve has probably become the most popular approach to summarize uncertainty in cost-effectiveness analyses. The cost-effectiveness acceptability curve informs the decision-maker about the probability that the intervention is cost-effective for a wide range of threshold ratios. Graphically, the cost-effectiveness acceptability curve is constructed by estimating the proportion of the joint distribution of costs and effects below the line defining the threshold ratio while that line rotates from the horizontal through to the vertical on the cost-effectiveness plane. For each specified limit of the threshold ratio, the cost-effectiveness acceptability curve provides the one-sided *p*-value for the cost-effectiveness of the intervention. Some commentators have argued that the interpretation of the cost-effectiveness acceptability curve (the probability an intervention is cost-effective given a critical ratio) is Bayesian in nature (Luce and Claxton, 1999; O'Hagan et al., 2000). However, the

frequentist approach will yield the same results as a Bayesian approach when non-informative priors are used (Briggs, 1999).

The other important development has been the introduction of the net-benefit statistic (Stinnett and Mullahy, 1998), based on the standard decision rule that a program should be implemented if its cost-effectiveness ratio is below a certain threshold value λ . The net-benefit can be expressed on the monetary scale as net monetary benefits [$NMB = (\lambda \times \Delta E) - \Delta C$] or on the health outcome scale as net health benefits [$NHB = \Delta E - (\Delta C/\lambda)$]. Programs with a NMB or NHB greater than zero should be implemented. The advantage of using the net-benefit statistic is that it provides a continuous measure of outcome that avoids the difficulties associated with ratio statistics. However, it should be noted that by using the net-benefit statistic, information on the return on investment of a specific health care program is lost. For example, assuming a λ of \$100,000 per QALY, consider program A with $\Delta C_A = \$90,000$ and $\Delta E_A = 1$ QALY. The NMB of program A is \$10,000. Now consider program B with $\Delta C_B = \$10,000$ and $\Delta E_B = 0.2$ QALY. The NMB of program B is also \$10,000. That is, both programs offer the same net monetary benefit, but the cost-effectiveness ratios of the two programs are different: \$90,000/QALY gained for program A versus \$50,000/QALY gained for program B.

Both the net-benefit approach and the cost-effectiveness acceptability curve explicitly make use of a critical ratio as a cut-off point for resource allocation. It should be noted that the critical ratio here no longer results from a solution to an optimization problem. The budget constraint is not explicit and resources may well come from departments other than the health care sector, such as education or national defense. It is usually more difficult to abandon technologies that are already implemented in order to free resources for new programs, than to prevent the implementation of technologies that have not yet passed the hurdle of inclusion in the basic insurance package. This means that more resources have to be made available by cutting the budget of other sectors of economy, by taxation or by increasing insurance premiums. This may also be one of the reasons why health insurance premiums in Switzerland (which are mandatory by law and subsidized by the government for low-income groups) have increased substantially (insurance premiums increased by 92% between 1991 and 1999 in the state Basel-Stadt) (Schopper et al., 2002).

In the absence of an explicit budget constraint for health care, the opportunity cost of health care resources is usually in areas other than health. The cost-effectiveness question then boils down to how much society is willing to pay for a QALY gained, as advocated by Weinstein (1995) and Johannesson and Meltzer (1998). Hirth et al. (2000) reviewed the value-of-life literature in order to generate a baseline estimate and a range for the value of a QALY. The authors distinguished between four different methods to assess the value of life: human capital methods, revealed preference studies based on job risk,

revealed preference studies based on non-occupational safety risks, and contingent valuation studies about WTP for reductions in risk. The estimates were expressed in 1997 US dollars. The lowest median value per QALY was observed in studies that were based on the human capital approach (\$24,777). Revealed preference job-risk studies yielded the highest median value (\$428,286), while revealed preference safety studies yielded a median value of \$93,402 and contingent valuation studies a median value of \$161,305. The wide range of estimates observed for the value of a QALY plainly indicates that a clear-cut estimate for the critical ratio cannot be determined. It is noteworthy that, with the exception of the human capital approach, all methods yielded estimates that are higher than the rules of thumb suggested by Laupacis et al. (1992).

However, the approaches described above are appropriate for societal decision-making. As Johannesson and Meltzer (1998) argue, the fixed budget as a decision rule is problematic since a fictitious total cost level for society that includes all relevant costs needs to be determined. This would not correspond to any real-world budget. Nonetheless, most decision-makers have to operate at a sub-societal level and have to meet budget constraints. It is therefore not clear how they should actually use information on cost-effectiveness and uncertainty when not all programs that are deemed cost-effective can be implemented because of limited resources. Moreover, the assumptions of constant returns to scale and complete divisibility have not yet been addressed by current approaches to handle uncertainty in cost-effectiveness analyses.

Another issue that has attracted attention is the use of portfolio theory to select between health care programs when costs and effects are uncertain (O'Brien and Sculpher, 2000). The basic idea is that by spreading the budget over many programs the risk-return characteristics of investments in health care programs can be improved. In other words, investing the budget in a mix of programs rather than individual programs yields greater expected return for the same degree of risk (assuming that the programs are not perfectly correlated). The optimal portfolio is then determined by the decision-maker's preferences over expected return and risk. However, health care finance differs from financial economics in a number of ways, which is also addressed in the present thesis.

Outline of this thesis

Chapter 2 discusses the limitations of the decision rule based on a critical ratio and builds upon the alternative decision rule described by Birch and Gafni (1992,1993). The principal idea is that all resources are already consumed by current programs. In order to introduce a new program, an already existing program must be deleted to release resources for the new program. The health benefits gained by introducing the new program should exceed those lost by deleting the old program. This decision rule is discussed in the presence of un-

certainty associated with costs and effects. The decision-making plane is then introduced as a means to communicate with policy makers and graphically present the results of the analysis, i.e. the probability that the decision rule will lead to a more efficient allocation of resources.

In chapter 3 the decision rule described in chapter 2 is extended for the situation where the decision-maker has to fund a portfolio of health care programs. Although the alternative decision rule may lead to a more efficient allocation of resources, it does not necessarily meet the decision-maker's total budget constraint. In the presence of uncertainty and a portfolio of health care programs, a decision-maker may only want to introduce a new program if the probability of exceeding the total budget lies below some threshold level. In other words, a switch of programs that is deemed worthwhile when only the programs under investigation are considered is an essential but not necessarily a sufficient condition for introducing that program. A program only qualifies for implementation if the change of programs leads to a more efficient allocation of resources and the decision-maker's total budget constraints are met.

Chapter 4 revisits the decision rule of cost-effectiveness analysis under certainty and uncertainty. It is argued that the assumption of complete divisibility and hence a linear programming approach to budget allocation is problematic since patients are not divisible. Therefore, an integer programming approach to budget allocation is suggested that handles individuals as indivisible units. It is shown that by using an integer programming approach, treatments that would have been excluded by extended dominance using the classical decision rule of cost-effectiveness analysis are indeed provided to some patients. The integer-programming framework can be extended to the situation where costs and effects are uncertain. Expected aggregate effects is defined as the objective function, which is penalized if the budget is exceeded in order to account for the opportunity costs of the additional resource use.

In chapter 5 the cost-effectiveness affordability curve is introduced. The cost-effectiveness affordability curve is an extension of the cost-effectiveness acceptability curve that presents the joint probability that an intervention is cost-effective and affordable. The need for this additional information stems from the fact that the critical ratio used for decision-making is not usually linked to an explicit budget constraint, rather it reflects a convenient round number often used by researchers to argue whether an intervention is cost-effective. However, since decision-makers at the sub-societal level are usually limited by real-world budgets, the additional information on the affordability of a program (i.e. the probability that the program lies within the budget constraint) may be relevant for deciding whether there are sufficient resources to implement the program.

Chapter 6 discusses one of the particularities of health care finance that must be considered when portfolio theory is used to select between health

care programs when economic and health outcomes are subject to a distribution. In health care finance the investment decision to spread the budget over many programs can be realized from the beginning. In health care, on the other hand, future resource use of the programs in the portfolio is uncertain. Therefore, the budget that was initially allocated to the individual programs does not necessarily correspond to the final distribution of the budget over the programs. For example, if a program turns out to use fewer resources than budgeted, the remaining resources may be allocated to programs that still require more resources. It is shown that once the budget corresponds to the expected costs of the programs in the portfolio, there will be no further benefit from diversification due to the suggested reallocation policy.

In chapter 7 the idea of a risk-adjusted measure to compare the return on investment in health care programs is developed. Return on investment is defined as the net monetary benefit over the costs of the program. The concept of capital allocation across a risky and a risk-free asset is used to construct a measure that allows us to compare the performance of mutually exclusive interventions in the presence of uncertainty associated with return on investment. The slope of the capital allocation line, defined by the return of the risk-free asset and the risk-return characteristics of the risky asset, the so-called reward-to-variability ratio, is also known in financial economics as the Sharpe Ratio. This slope informs us about the extra return we can expect per extra unit of risk: the steeper the capital allocation line, the better the performance of the program, meaning we would prefer a program with a higher reward-to-variability ratio.

Chapter 8 presents an example of a cost-effectiveness analysis where the decision as to whether the program should be funded or not is clear, since it is a dominant strategy from the societal perspective. The analysis investigates the cost-effectiveness of highly active antiretroviral therapy in HIV-infected patients in Switzerland. The study was based on a Markov model, which was evaluated probabilistically and by scenario analysis. However, since the incremental costs are positive when health care utilization alone is included in the analysis, consideration must be given to where these resources come from.

In chapter 9 the example of a cost-effectiveness analysis from the health care perspective is presented. This study represents an economic evaluation of *Mycobacterium avium* complex prophylaxis in patients taking antiretroviral triple combination therapy. The joint distribution of costs and effects are presented on the cost-effectiveness plane for different scenarios of durability of highly active antiretroviral therapy. Since the incremental costs and effects are positive, ranges for the cost-effectiveness ratios are calculated. As this intervention calls for more health care resources, the applicability of the alternative decision rule is discussed.

■ Chapter 2

Opportunity costs and uncertainty in the economic evaluation of health care interventions

Summary

Considerable methodological research has been conducted on handling uncertainty in cost-effectiveness analysis. The current literature suggests the concepts of net health benefits and cost-effectiveness acceptability curves to circumvent the technical shortcomings of cost-effectiveness ratio statistics. However, these approaches do not provide a solution for the inherent problem that the threshold cost-effectiveness ratio itself is unknown. The authors suggest analyzing uncertainty in cost-effectiveness analysis by directly addressing the concept of opportunity costs using the decision rule described by Birch and Gafni (1992) and introduce a new graphical framework (the "decision making plane") for communicating with policy makers.

Introduction

In today's economic climate it has become important to assess the costs and benefits of new and existing health care technologies. Cost-effectiveness analysis is the most widely applied analytic framework for comparing alternative health care interventions from an economics perspective. Results of cost-effectiveness analyses are usually expressed in terms of incremental cost-effectiveness ratios (ICER) which represent the ratio of the difference in mean cost to the difference in mean effectiveness between two health care strategies. Uncertainty in cost-effectiveness models has traditionally been analyzed using univariate and multivariate sensitivity analysis (Briggs and Gray, 1999). Although sensitivity analysis is useful for evaluating the robustness of the assumptions in cost-effectiveness analysis, it does not inform us about the joint uncertainty of all variables in the analysis (Sendi et al., 1999).

A paper by O'Brien et al. (1994) has stimulated a growing area of research associated with the methodological problem of how to handle uncertainty in "stochastic" cost-effectiveness analysis where patient level data are available (O'Brien et al., 1994). Various methods for estimating confidence intervals around cost-effectiveness ratios have been presented in the literature (Briggs and Gray, 1999; Polsky et al., 1997). Stinnett and Mullahy (1998) recently outlined the major limitations of using ratio statistics in cost-effectiveness analysis. The technical difficulties associated with ratio statistics become evident when the joint distribution of incremental cost and incremental effectiveness extends over more than one quadrant of the cost-effectiveness plane (Briggs and Gray, 1999; Stinnett and Mullahy, 1998). Since the ICER is a discontinuous function of the mean difference in effectiveness, it is an ill-defined parameter and has no meaning without further information about the joint distribution of incremental cost and effectiveness on the cost-effectiveness plane (Briggs and Gray, 1999; Stinnett and Mullahy, 1998; Briggs and Fenn, 1998). The statistical intractability of the ICER has led to alternative approaches for reporting uncertainty in cost-effectiveness analysis. One approach involves the concept of Net Health Benefits (NHB) (Stinnett and Mullahy, 1998) where

$$\text{NHB} = (E_1 - E_2) - (C_1 - C_2)/\lambda$$

and E_i and C_i represent the effects and costs of program i ($i=1,2$) and λ represents the threshold cost-effectiveness ratio above which an intervention would be regarded as cost-ineffective (Stinnett and Mullahy, 1998).

Use of NHB avoids the difficulties associated with ratio statistics since it provides a continuous measure of outcome. However, a major limitation of the NHB approach is that λ is not known (Stinnett and Mullahy, 1998; Briggs, 1999). In response to this limitation, Briggs (1999) uses cost-effectiveness acceptability curves, as suggested by van Hout et al. (1994), which reflect the

proportion of the joint distribution of incremental cost and incremental effectiveness with an ICER below the threshold value for all possible λ . The cost-effectiveness acceptability curve informs the policy maker, for a given λ , the probability that a strategy is cost-effective. However, the use of cost-effectiveness acceptability curves does not provide a solution to the problem that λ is subjective. It rather forces the policy maker to make his own value judgement about λ based on the range of λ for which an intervention is "cost-effective" with a specific level of probability.

In this paper we propose an alternative approach to analyzing uncertainty in cost-effectiveness analysis. The problem addressed is as follows: Given an existing budget allocated to various programs, a new program A is being considered for implementation, with an existing program B being targeted for cancellation because there are no new resources. How does one decide if implementing A and canceling B is worthwhile? In the next section we discuss the limitations of the decision rule based on a threshold cost-effectiveness ratio. We then present an alternative decision rule for a deterministic case. In "The decision making plane" we introduce the "decision making plane" as a graphical framework for analyzing the decision problem. In "Accounting for uncertainty" we extend our decision rule to account for uncertainty by taking a Bayesian perspective, and in "Discussion" we discuss the implications of our approach.

Limitations of the "critical ratio" approach

The threshold value λ reflects the shadow price per unit effectiveness (e.g. dollars per life-years saved) in the absence of a market (Weinstein and Zeckhauser, 1973; Johannesson and Weinstein, 1993; Karlsson and Johannesson, 1996). According to this decision rule, any intervention with a price per unit effectiveness above λ would not be implemented. This implies, on the other hand, that any program with an ICER below λ would be implemented. The limitations of allocating health care resources in this way have been described in detail elsewhere (Birch and Gafni, 1992, 1993; Gafni, 1996). Here we summarize our main concerns:

- I) According to Weinstein and Zeckhauser (1973) the "critical ratio" λ represents the shadow price of the constrained budget or opportunity cost of health care resources. However, under some analytical perspectives (e.g. a societal perspective) it may be difficult to determine precisely the budget constraint. In this case the value of λ cannot be determined.
- II) The approach assumes that the size of the health care budget does not affect the marginal opportunity cost of health care resources (Birch and Gafni, 1992). It assumes that the value of benefits forgone would be the same for every dollar taken from other sources and hence that the margi-

nal opportunity cost of resources is constant for all levels of resource consumption and for all settings (Birch and Gafni, 1992). Similar assumptions underlie the individual utility maximizing approach recently presented by Meltzer (2001).

- III) When λ represents the shadow price of the budget (or the opportunity cost) it should be equal to the cost-effectiveness ratio of the last program selected before the budget is exhausted (Weinstein and Zeckhauser, 1973). But like the new program under consideration, the costs and effects of the last program are uncertain (i.e. subject to a distribution). As a result (a) the "critical ratio" λ is therefore stochastic and subject to a distribution. This latter uncertainty is typically not accounted for when cost-effectiveness acceptability curves are constructed. The cost-effectiveness acceptability curve informs us about the probability a program is cost-effective for a range of deterministic λ (Briggs and Gray, 1999) and not for a distribution associated with λ ; and (b) as new programs are funded, the program that was the last to be funded also changes, and therefore the distribution of λ also changes.

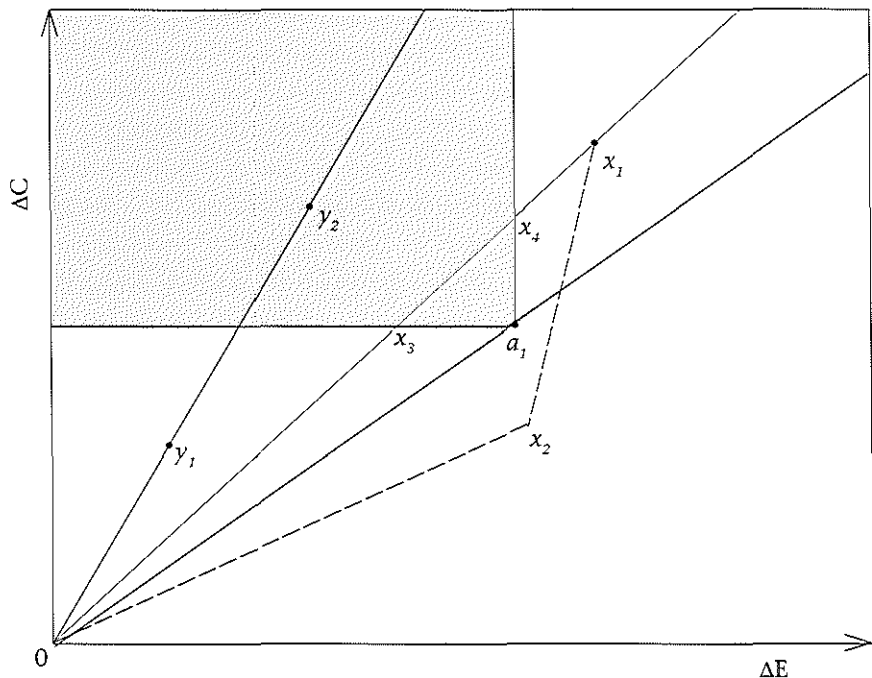


Figure 1. Return to scale and divisibility on the cost-effectiveness plane. a_1 denotes the anticipated level of a new program A. The shaded area describes different levels of programs to be cancelled to fund a_1 . The line Ox_1x_4 denotes different sizes of program X. The line Ox_1 denotes different sizes of program X under the assumption of complete divisibility and constant returns to scale. The section x_3x_4 of the line Ox_1 denotes sizes of program X where the requirements of the second-best decision rule would be met. y_1 denotes a given level of program Y with a higher cost per unit effectiveness than a_1 .

IV) The use of λ as a decision rule is based on the implicit assumption of constant returns to scale and complete divisibility of health care programs (Birch and Gafni, 1992). The difference in cost and effectiveness between two health care programs can be displayed on the cost-effectiveness plane (Figure 1). The ICER is traditionally presented as the slope of a line through the origin. Complete divisibility assumes that we can buy the program in infinitely small increments. Constant returns to scale implies that the ICER is independent of the size of the program. Constant returns to scale of program X would be reflected by the line $0x_1$ in Figure 1. However, program X described by point x_1 (Figure 1) might not exhibit constant returns to scale in the real world. For example, different sizes of the same program X might be described by the line $0x_2x_1$ (Figure 1). In this case, the slope of a line through the origin would not be the same for every point on $0x_2x_1$ which reflects the behavior of program X in terms of returns to scale. In this case the ICER depends on the particular size of the program being considered. In addition, a program could be indivisible (in part or completely) and require high capital costs so that the curve may not start at the origin of the cost-effectiveness plane. High capital costs are often needed for health care programs that necessitate expensive technologies such as CT or MRI (Karlsson and Johannesson, 1998). A program might also be indivisible because of equity consideration (Ubel et al., 1996). Policy makers may not want to implement a program without the ability of providing it to all patients even though the effectiveness and/or costs, and hence the ICER, are systematically different among identifiable groups in the population. Integer programming can be used to accommodate indivisibilities and non-constant returns to scale (Birch and Gafni, 1992, 1993). Stinnett and Paltiel (1996) refined the integer programming framework to process more complex information regarding returns to scale and divisibility. However, both approaches involve data requirements that cannot yet be satisfied in most health care systems.

An alternative decision rule

For the case of a deterministic world, a less data-hungry but feasible alternative approach with the objective of identifying unambiguous improvements in resource allocation has been presented (Birch and Gafni, 1992). The approach is a second-best solution in that it can be used to identify improvements in, but not optimization of, resource allocations. A program (or a set of programs) B is identified that, if cancelled, would free up enough resources to fund the additional costs of the new program A. If the increased outcomes associated with the new program A are greater than the outcomes forgone from canceling B, then the adoption of the new program represents a more efficient allocation of resources (Birch and Gafni, 1992). Note that the program cancelled may

not be the highest valued alternative and hence the rule does not necessarily comply with the definition of opportunity cost. For simplicity, here we limit our algorithm to identifying one program instead of a set of programs that must be cancelled to free up the additional resources required by A. Also, we assume that resources freed up from cancellation of program B represent the additional costs of A and that no infrastructural costs of B are used by A. So for program A to be implemented we need to find a program B such that

$$\Delta C(B) \geq \Delta C(A) \quad (1)$$

and

$$\Delta E(B) < \Delta E(A) \quad (2)$$

where $\Delta C(A)$ is the incremental cost of (or the additional resources required by) A compared to the cost of how the same patients would be treated if A was not available, and $\Delta C(B)$ is the incremental savings (or resources released) by canceling B (i.e. the cost of B compared to the cost of how these patients would be treated if B was not available). Similarly, $\Delta E(A)$ is the incremental effectiveness of A, and $\Delta E(B)$ the incremental effectiveness forgone by canceling B compared to the effectiveness associated with how these patients would be treated if A and B were not available. The conditions in Equation (1) and (2) can be extended to include situations where introducing A and canceling B neither increases nor decreases effects but results in resources being released for other uses. Therefore, in addition to Equation (1) and (2) we can regard the following conditions as favorable:

$$\Delta C(B) > \Delta C(A) \quad (3)$$

and

$$\Delta E(B) = \Delta E(A) \quad (4)$$

Note that by these four equations the situation where $\Delta C(B) = \Delta C(A)$ and $\Delta E(B) = \Delta E(A)$ has been excluded. In such a situation we would be indifferent between implementing program A or retaining program B. Also, note that these four equations are different from the current use of a decision rule that the incremental net benefit must be positive. The decision rule, as currently defined and used, is based on the assumptions that all programs exhibit constant returns to scale, are completely divisible, and that the marginal opportunity cost is constant for all levels of resource consumption. Moreover, this decision rule forces the decision maker to choose a specific value of λ which is very difficult to determine in real life. These assumptions are not required for the decision rule presented in this paper.

The conditions described by the four equations above can be illustrated graphically as shown in Figure 1. If A was the new program at the anticipated level a_1 (Figure 1), then any point to the North and/or West of a_1 (i.e. the shaded area) would satisfy the conditions for an improvement in efficiency. Consider X, a program that is under consideration for cancellation to release the additional resources required by program A at a_1 . Under constant returns to scale and complete divisibility, program X is described by the straight line from the origin through x_1 . Note that program X at x_1 does not satisfy the conditions for an unambiguous improvement in efficiency. It lies to the North East of a_1 , outside the shaded area, indicating that by canceling X at x_1 , enough resources are released to meet the additional resource requirements of A at a_1 , but the incremental effects of A at a_1 are less than the forgone effects of X at x_1 . However, a version of X that lies between x_3 and x_4 , would fall in the shaded area and hence meet the conditions for an unambiguous improvement in efficiency. In this case a smaller version of program X is involved which still releases enough resources to meet the additional resource requirements of A at a_1 , but the forgone effects of X between points x_3 and x_4 , are less than the additional effects of A at a_1 .

Now suppose we relax the assumptions of constant returns to scale and complete divisibility for program X such that the program is described by $0x_2x_1$. In this example there is no size of the program X that falls in the shaded area and hence meets the conditions for an unambiguous improvement in efficiency. Now consider program Y described by the straight line through the origin $0y_1$. For each size of program Y, compared to what would have happened if Y was not available, the ICER is higher than for program A at a_1 . But program Y at y_1 lies outside the shaded area. The effects forgone by canceling y_1 are exceeded by the incremental effects of A at a_1 , but there are insufficient resources released by y_1 to meet the additional resource requirements of a_1 . Information about the ICER is insufficient to address the efficiency of resource allocation because it does not include information on program size. Moreover, use of the ICER as a basis for decision-making can lead to the wrong decision being made. For example, on the basis of ICERs, a decision-maker would choose to cancel program Y at y_1 before canceling X at x_3 , since ICER for y_1 exceeds ICER for x_3 . However, in this example, only by choosing to cancel x_3 are the conditions for an unambiguous improvement in efficiency satisfied. In this case, the program with the lower ICER should be cancelled because of the absolute size of this program. The ICER combines information on costs and effects into one dimension while the cost-effectiveness plane has two dimensions (Briggs and Fenn, 1998). We therefore lose important information about the size of the program when we use the ICER as a basis for decision-making. This prevents us from being able to determine unambiguously the effects of recommendations and decisions on the efficiency of resource use. The second-best decision

rule accounts for both dimensions on the cost-effectiveness plane since the program to be deleted has to lie in the shaded *area*.

From a policy perspective, the search for programs to be cancelled might start within the budget allocated to the respective area of medicine (Gafni, 1996). For example, if in order to fund a new HIV-program no other program in the HIV-sector can be identified that satisfies the algorithm identified above, then one can look for programs in other areas (e.g. cardiovascular diseases) that might satisfy the algorithm. This policy of "first cleaning your own budget" ensures that all unambiguous improvements in efficiency are identified before departments start to look for improvements in efficiency calling on resources from other areas (Gafni, 1996). As an example of an economic evaluation that considers this political search algorithm see Elit et al. (1997). It is important to note that this search algorithm might lead to different results depending on the setting of the analysis. Implementing program A might represent an unambiguous improvement in efficiency in one setting, but not in another even though the incremental costs and effects of A are the same in both settings. This is due to the differences in the opportunity costs of the additional resources required by A in each setting.

For example, suppose the incremental costs and effects of program A (e.g. an AIDS treatment program) are the same for both settings, and described by point a_1 in Figure 1. However, the other programs available to the decision maker as potential sources for the additional resource requirements of a_1 may differ among communities, either because of differences in the total resources available to health care programs and/or differences in the incremental costs or effects of the other programs. In the first setting, a program Y (e.g. a smoking cessation program) described by y_2 in the shaded area of Figure 1 is available and satisfies the improvement in efficiency algorithm. However, in the second location, program Y, although having the same ICER as y_2 , is much smaller, as described by point y_1 . Because y_1 lies outside the shaded area it does not satisfy the improvement in efficiency algorithm. Hence the introduction of the AIDS treatment program would represent an unambiguous improvement in efficiency in only the first location.

In the following section we present an approach to graph the results of a cost-effectiveness analysis based on the decision rule mentioned above and then extend this approach by taking uncertainty into account.

The "decision making plane"

The cost-effectiveness plane presents information on the joint distribution of incremental cost and incremental effectiveness (Briggs and Gray, 1999). It does not, however, inform us about the opportunity cost of programs under consideration. To overcome this limitation we suggest a different graphical presentation that we call the "decision making plane". This framework incorporates information on both the incremental costs and incremental effects of the new program (i.e., A) and the program to be cancelled (i.e., B). To clarify this issue, we can rewrite Equation (1) and (2) for an unambiguous improvement in efficiency as

$$\Delta C(A) - \Delta C(B) \leq 0 \quad (1a)$$

and

$$\Delta E(A) - \Delta E(B) > 0 \quad (2a)$$

and Equation (3) and (4) as:

$$\Delta C(A) - \Delta C(B) < 0 \quad (3a)$$

and

$$\Delta E(A) - \Delta E(B) = 0 \quad (4a)$$

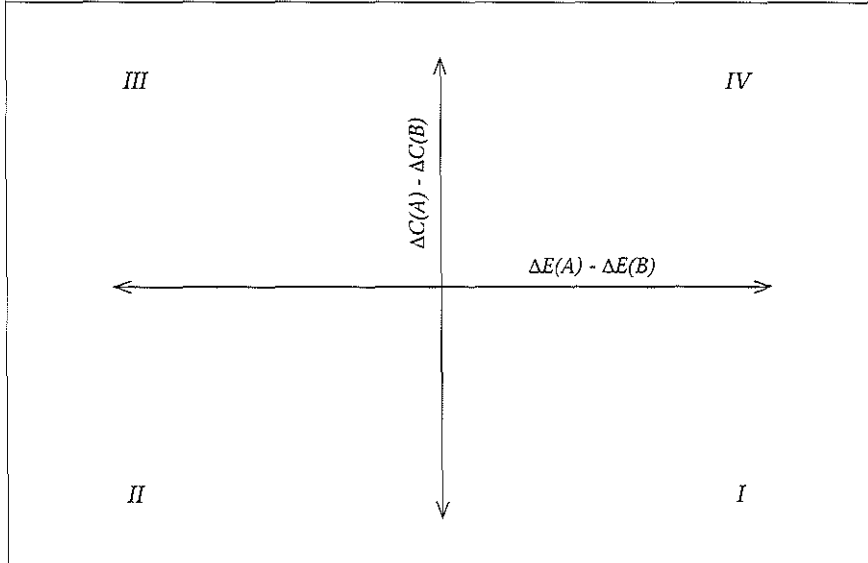


Figure 2. The decision making plane

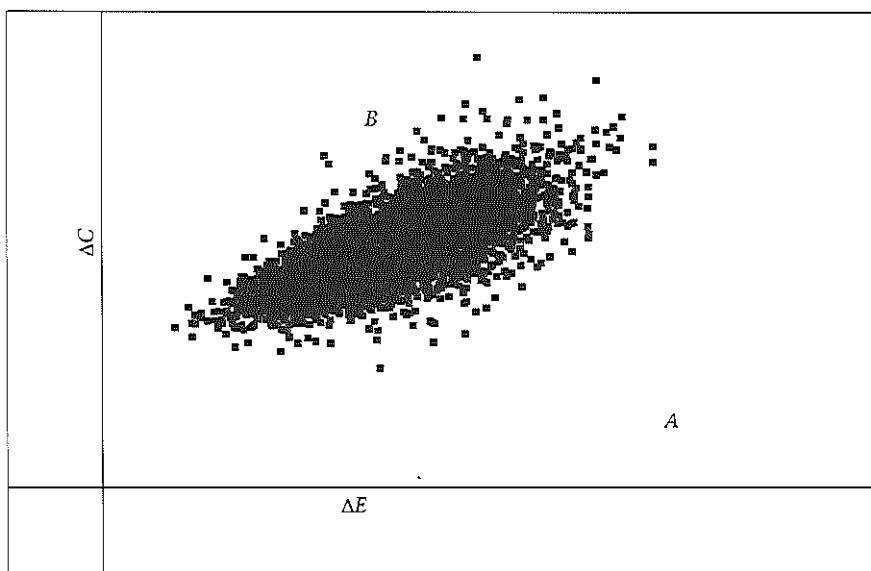


Figure 3. Posterior joint distribution of a program B (squares) which needs to be cancelled to fund the new program A (dots)

Similar to the cost-effectiveness plane, we can now construct a plane with four quadrants and assign $\Delta C(A) - \Delta C(B)$ to the vertical axis and $\Delta E(A) - \Delta E(B)$ to the horizontal axis (Figure 2). Quadrant I is consistent with a more efficient allocation of resources (i.e. a situation where replacing program B with A results in a net gain in health effects without the need for additional resources). Quadrant II reflects conditions where there is a reduction in health effects but a net saving of resources. Quadrant III represents the condition where there is an increase in resource consumption and a reduction in health effects. Quadrant IV reflects conditions where there is an increase in both health effects and resource consumption. Any evaluation yielding results that completely fall into quadrant I (including the horizontal and vertical axes with the exception of the origin) satisfies the efficiency improvement algorithm. The decision making plane therefore has the advantage of making the benefits forgone of not implementing A by canceling program B explicit.

Accounting for uncertainty

The second-best decision rule has so far been described from a deterministic perspective (Birch and Gafni, 1992). We now consider costs and effects as stochastic parameters and take a Bayesian approach. Under a Bayesian approach, parameters of interest are ascribed a distribution that reflects the uncertainty associated with their true value. Several authors have suggested that Bayesian methods be used to handle uncertainty in cost-effectiveness analysis (Briggs, 1999; Claxton, 1999; Heitjan et al., 1999). Grieve (1998) argues that the interpretation of cost-effectiveness acceptability curves requires a Bayesian

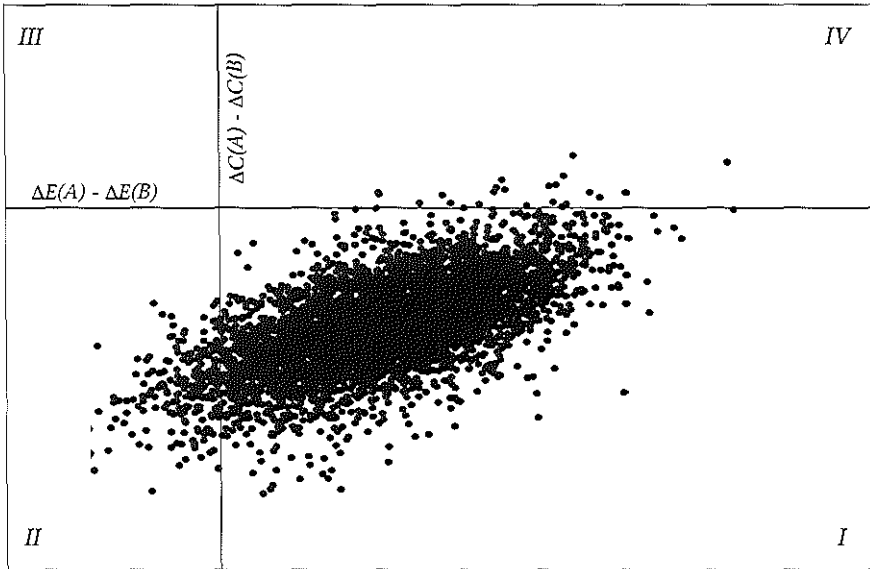


Figure 4. Posterior joint distribution of introducing program A and cancelling program B on the decision making plane

approach because the cost-effectiveness acceptability curve shall inform us about the *probability* an intervention is "cost-effective" for a wide range of λ . Briggs (1999) shows how to apply Bayesian methods to cost-effectiveness studies based on clinical trials in the absence of any pretrial statistical information on the distribution of costs and effects (i.e. a situation of non-informative prior information), and so provide a probabilistic interpretation of cost-effectiveness acceptability curves that cannot be generated under a frequentist approach. Although the methodological literature reflects an increasing interest in Bayesian approaches to technology assessment (Briggs, 1999; Claxton, 1999; Heitjan et al., 1999; Grieve, 1998), real-world examples are still rare. For a recent practical work-up within a modeling framework see Sendi et al. (1999).

For demonstration purposes we use a hypothetical example based on joint distributions of costs and effects from a published Bayesian cost-effectiveness model for treating HIV-infected patients (i.e. posterior joint distributions) (Sendi et al., 1999). Imagine we were interested in introducing a new program A for the treatment of the HIV-infected population. The approximation of the posterior joint distribution of incremental costs and incremental effects of program A are shown in Figure 3 (dots). According to the improvement in efficiency algorithm we must find an appropriate program preferably within the budget allocated to the HIV-sector to release sufficient resources to satisfy the additional resource requirements. Let us assume that we are successful in identifying program B that satisfies the algorithm (i.e. will be cancelled in order to implement A). The approximation of the posterior joint distribution of

incremental costs and effects of canceling B is also shown in Figure 3 (squares). The assessment of the impact of introducing A and canceling B is performed as follows:

- a. Draw a set of values from the posterior distribution $f(\Delta C(A), \Delta E(A) | \text{data})$
- b. Draw a set of values from the posterior distribution $f(\Delta C(B), \Delta E(B) | \text{data})$
- c. Compute $\Delta C(A) - \Delta C(B)$ and $\Delta E(A) - \Delta E(B)$

The algorithm above is based on the assumption that $(\Delta C(A), \Delta E(A))$ and $(\Delta C(B), \Delta E(B))$ are statistically independent. If this cannot be maintained *a priori*, then making draws from the joint distribution $f(\Delta C(A) - \Delta C(B), \Delta E(A) - \Delta E(B) | \text{data})$ and then computing the differences $\Delta C(A) - \Delta C(B)$ and $\Delta E(A) - \Delta E(B)$ would be more appropriate. This process is repeated a large number of times and results in an approximation of the posterior joint distribution $f(\Delta C(A) - \Delta C(B), \Delta E(A) - \Delta E(B) | \text{data})$ as shown in Figure 4. We can now estimate the following posterior probabilities:

- (1) The probability that introducing A and canceling B increases effectiveness without exceeding the resource constraint. We estimate this probability by the proportion of results (i.e. from (c) above) that fall in quadrant I.
- (2) The probability that introducing A and canceling B decreases effectiveness and does not exceed the resource constraint. We estimate this probability by the proportion of results that fall in quadrant II.
- (3) The probability that introducing A and canceling B decreases effectiveness and exceeds the resource constraint. We estimate this probability by the proportion of results that fall in quadrant III.
- (4) The probability that introducing A and canceling B increases effectiveness and exceeds the resource constraint. We estimate this probability by the proportion of results that fall in quadrant IV.

The new program A should be implemented and B cancelled if the approximation of $f(\Delta C(A) - \Delta C(B), \Delta E(A) - \Delta E(B) | \text{data})$ entirely falls in quadrant I. However, the posterior joint distribution may extend over more than one quadrant as in our example (Figure 4). Using data from the HIV-study, the estimated probabilities that introducing program A and canceling B will yield outcomes that lie in quadrant I, II, III, and IV are 0.950, 0.045, 0.000, 0.005 respectively. Note that because the four quadrants exhaust all possible outcomes the probability estimates in the four quadrants must sum up to one. These probabilities can be interpreted as follows: there is a 95% chance that implementing A and canceling B will lead to an unambiguous improvement in efficiency. However, there is a 5% chance that the decision will lead to a position outside quadrant I.

It is now up to the decision-maker to process this information and judge

whether he will accept the risk of other possible outcomes. The decision-maker may well exhibit different preferences for inefficiencies occurring in quadrant II, III or IV. Note that the decision making plane informs us of both the size and nature of different risks. For example, there is a 4.5% cent chance that the total health effects are reduced but resources remain unused at the end of the year (quadrant II). In contrast, there is a 0.5% cent chance that insufficient resources are released to support the new program. In this case the program will run out of resources during the year and hence be unable to produce the full anticipated effects unless additional resources can be found from elsewhere. However, consideration would need to be given to the opportunity costs of these additional resources.

Discussion

This paper addresses the difficulties associated with using a particular value of λ as a decision rule. Alternative approaches such as integer programming or mixed integer programming techniques have been suggested in the literature (Birch and Gafni, 1992; Stinnett and Paltiel, 1996). The practical application of optimization techniques in health services research have recently been demonstrated by Granata and Hillman (1998). The authors used data on costs and effects from published economic evaluations and simulated the reallocation of resources under different budgets to maximize population effectiveness. However, the authors used linear programming techniques and accepted the assumptions underlying the current practice of cost-effectiveness analysis. Moreover, uncertainty was not incorporated in their study.

We outline the advantage of using the decision rule as described by Birch and Gafni (1992) and introduce a new graphical framework for explaining the idea behind a more efficient allocation of resources in this way. We do not assume that there are unused resources available or that there is a stream of additional resources available at a constant opportunity cost. Instead we take the position that the budget is used up by existing programs. A new program, therefore, cannot be implemented unless resources are freed up by eliminating existing programs. The action of canceling existing programs in order to fund new programs would only be justifiable from an economics perspective where it leads to a more efficient allocation of resources. This forces us to think about the opportunity costs of the new program. We would not want to introduce the new program if we were unable to find at least one existing program that would do less good than the new program using the same or less resources.

The decision-making plane helps us visualize the effects forgone of not implementing a new program in this way. Any point in quadrant I including the lines (with the exception of the origin) is consistent with a more efficient allocation of resources.

Under conditions of uncertainty, however, the joint distribution may

extend over more than one quadrant. In this case the advantage of a Bayesian approach to incorporating uncertainty becomes apparent. We are interested in the *probability* that our decision of deleting an existing program to fund a new program will fail to provide an unambiguous improvement in efficiency reflected in quadrants II-IV. A Bayesian framework therefore coincides with this way of thinking (Briggs, 1999; Claxton, 1999; Heitjan et al., 1999; Spiegelhalter et al., 1999).

A clinical trial yields data for a particular intervention of interest (i.e., program A). For possible candidate programs for cancellation (i.e., B) there may or may not be data available from other clinical trials. In addition, trial data may differ between settings of the clinical trial. Modeling might therefore be unavoidable since different "local distributions" are usually not produced within clinical trials (Buxton et al., 1997). We also feel that it is important that investigators share their data from clinical trials in order to enable comparison of programs.

For the sake of simplicity, we have limited our algorithm to identifying a single program to be eliminated. However, this could be extended, for example, to include a set of programs to be cancelled to fund the new program. Under uncertainty a simulation approach would result in an approximation of a posterior joint distribution for $f(\Delta C(A) - (\Delta C(B_1) + \dots + \Delta C(B_n)), \Delta E(A) - (\Delta E(B_1) + \dots + \Delta E(B_n)) | \text{data})$ where the programs to be cancelled are $i=1+\dots+n$. While this adds little to the computational burden of the exercise, it might increase the burden associated with identifying those programs. Moreover, our approach might be difficult in cases where information on outcomes is not readily available for those programs that are potential candidates for cancellation.

If the posterior joint distribution extends over more than one quadrant, then we must ask whether we are willing to accept the risk of "bad" outcomes. Since it seems reasonable to assume that we will not always find posterior joint distributions that are limited to quadrant I, we must find ways to handle such situations. One possibility would be to limit this risk to an arbitrary level, say 0.05, similar to the arbitrary decision of accepting a 5% Type I error in hypothesis testing. Decision-makers, however, may be risk-averse or risk-seeking and may have varying preferences for outcomes in the different quadrants on the decision making plane. Whether and how such preferences can be assessed should be subject to further research.

■ Chapter 3

Optimizing a portfolio of health care programs in the presence of uncertainty and constrained resources

Summary

Much research has been devoted to handling uncertainty in cost-effectiveness analysis. The current literature suggests summarizing uncertainty in cost-effectiveness analysis using acceptability curves or net health benefits. These approaches, however, focus only on uncertainty associated with costs and effects of the programs under consideration. In the real world, most decision-makers have to fund a portfolio of health care programs. Therefore, a more comprehensive approach would include in the analysis the uncertainty of costs and effects of all programs supported by the fixed budget. This paper extends the decision rule described by Birch and Gafni (Journal of Health Economics, 1992) within the context of a portfolio of programs when costs and effects are uncertain and resources constrained.

Introduction

Cost-effectiveness acceptability curves (van Hout et al., 1994) and net health benefits (Stinnett and Mullahy, 1998) or net monetary benefits (Tambour et al., 1998) have been introduced as ways of incorporating uncertainty associated with costs and effects in cost-effectiveness analysis. In both approaches a threshold cost-effectiveness ratio is applied. A program with a cost-effectiveness ratio above the threshold ratio is not accepted while a program with a cost-effectiveness ratio below the threshold ratio is accepted. It has been argued that the use of a fixed ratio as a decision rule can lead to an uncontrolled growth of expenditures as more programs with an acceptable cost-effectiveness ratio become available and are funded (Gafni and Birch, 1993). Furthermore, even if the threshold cost-effectiveness ratio is allowed to vary according to the budget, its use is based on the assumptions of constant returns to scale (constant cost-effectiveness ratio for different sizes of the program), complete divisibility of programs (program can be bought in [infinitely] small increments), and constant marginal opportunity costs (Birch and Gafni, 1992, 1993; Weinstein, 1995).

An alternative decision rule (which relaxes the assumptions mentioned above) with the goal of increasing health outcomes without calling for additional resources has been suggested by Birch and Gafni (1992). In order to implement a new program, an already existing program must be identified and cancelled that releases enough resources to fund the new program. Furthermore, the health gains forgone by deleting a program should be smaller than those gained by introducing the new program. This decision rule results in an unambiguous improvement of the allocation of resources (Birch and Gafni, 1992). The decision rule is a second-best solution in the sense that more than one program might satisfy the conditions described above. On the other hand, the advantage of this decision rule is that it is not as data-hungry as mathematical programming techniques used for the optimization of resource allocation (Birch and Gafni, 1992; Stinnett and Paltiel, 1996). It is therefore suitable for situations where data on costs and effects are scarce, which is currently the case in most health care systems.

The decision rule has first been described for the case of a deterministic world (Birch and Gafni, 1992). In a separate paper we have illustrated the application of the decision rule when costs and effects of health care programs are uncertain (Sendi et al., 2002). However, the approach assumes that information on costs and effects of the specific programs under consideration are sufficient to guide policy makers. In the real world, most decision-makers have to fund a portfolio of health care programs. The decision-maker should therefore include, in her evaluation, the uncertainty associated with costs and effects of all health care programs supported by the fixed budget. In this paper we extend the decision rule described by Birch and Gafni (1992) within the

context of a portfolio of programs when costs and effects are uncertain and resources constrained. In the next section we review the decision rule under certainty and uncertainty. In "Stochastic dominance and affordability" we analyze the decision rule from the perspective of stochastic dominance and affordability. In "A portfolio of multiple programs" we embed the decision rule within a portfolio of multiple programs. In the last section we conclude with a discussion of our approach.

The decision rule under certainty and uncertainty

The decision rule starts with the premise that scarce resources are already used up by programs which are implemented (Birch and Gafni, 1992,1993; Gafni and Birch, 1993). Therefore, in order to introduce a new program, resources must be deployed from existing programs. That is, some additional resources need to be found in order to support the resource requirements of new program *A* over the resources used by current program *a*. These resources can be found by replacing existing program *B* with program *b* that requires less resources. More formally, the decision rule can be expressed as follows. Let *B* be an existing program to be deleted and *A* the new program to be implemented. By deleting program *B*, the patients who used to receive treatment *B* now receive treatment *b*. Similarly, by introducing program *A*, the patients who used to receive treatment *a* now receive treatment *A*. Program *A* and program *a* are mutually exclusive. Similarly, program *B* and program *b* are mutually exclusive. We denote with lowercase letters programs, which are both less expensive and less effective than the alternative program. We write $C_A > C_a$, $C_B > C_b$, $E_A > E_a$ and $E_B > E_b$ where C_i is the total cost and E_i the total effect of program $i=A,a,B,b$. We denote the incremental costs and effects of program *A* compared to program *a* as $\Delta C(A) = C_A - C_a$ and $\Delta E(A) = E_A - E_a$. Similarly, we denote the incremental costs and effects of program *B* compared to program *b* as $\Delta C(B) = C_B - C_b$ and $\Delta E(B) = E_B - E_b$. The decision rule is satisfied if the following conditions are met:

$$\Delta C(A) - \Delta C(B) \leq 0 \quad (1)$$

and

$$\Delta E(A) - \Delta E(B) > 0 \quad (2)$$

For example, let's assume that $\Delta C(B)$ is \$10'000'000 and $\Delta C(A)$ is \$9'000'000. Further, let us assume that $\Delta E(B)$ is 4'000 life-years and $\Delta E(A)$ is 5'000 life-years. Canceling program *B* and shifting the released resources to program *A* results in a gain of 1'000 life-years, and a leftover of \$1'000'000 for other uses. The decision rule is also satisfied if the following conditions are met:

$$\Delta C(A) - \Delta C(B) < 0 \quad (3)$$

and

$$\Delta E(A) - \Delta E(B) = 0 \quad (4)$$

For example, let's assume that $\Delta C(B)$ is \$10'000'000 and $\Delta C(A)$ is \$9'000'000. Further, let's assume that $\Delta E(B)$ is 5'000 life-years and $\Delta E(A)$ is 5'000 life-years. Canceling program *B* and shifting the released resources to program *A* results in a leftover of \$1'000'000 for other uses, without compromising overall health outcomes. Note that we have excluded the situation where

$$\Delta C(B) = \Delta C(A) \quad (5)$$

and

$$\Delta E(B) = \Delta E(A) \quad (6)$$

In such a situation we would be indifferent between retaining program *B* and implementing program *A*.

The decision rule can be extended to account for uncertainty associated with costs and effects of health care programs. Under uncertainty, we can write conditions (1) and (2) in terms of the joint probability

$$P(\Delta C(A) - \Delta C(B) \leq 0, \Delta E(A) - \Delta E(B) > 0) \quad (7)$$

Similarly, conditions (3) and (4) can be written as

$$P(\Delta C(A) - \Delta C(B) < 0, \Delta E(A) - \Delta E(B) = 0) \quad (8)$$

Since the events

$$(\Delta C(A) - \Delta C(B) \leq 0, \Delta E(A) - \Delta E(B) > 0)$$

and

$$(\Delta C(A) - \Delta C(B) < 0, \Delta E(A) - \Delta E(B) = 0)$$

are mutually exclusive,

$$P[(\Delta C(A) - \Delta C(B) \leq 0, \Delta E(A) - \Delta E(B) > 0)$$

$$\cup (\Delta C(A) - \Delta C(B) < 0, \Delta E(A) - \Delta E(B) = 0)]$$

$$= P(\Delta C(A) - \Delta C(B) \leq 0, \Delta E(A) - \Delta E(B) > 0)$$

$$+ P(\Delta C(A) - \Delta C(B) < 0, \Delta E(A) - \Delta E(B) = 0). \quad (9)$$

Under uncertainty, (9) summarizes the probability that the conditions of the decision rule are met.

The probability that the conditions of the decision rule are not met are then simply its complement

$$1 - P(\Delta C(A) - \Delta C(B) \leq 0, \Delta E(A) - \Delta E(B) > 0)$$

$$- P(\Delta C(A) - \Delta C(B) < 0, \Delta E(A) - \Delta E(B) = 0). \quad (10)$$

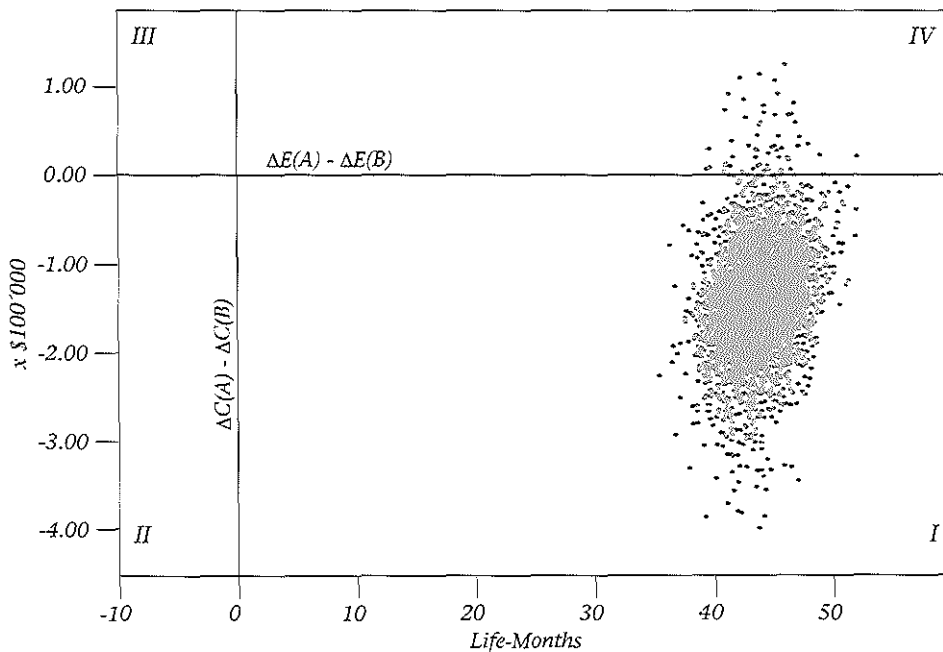


Figure 1. The decision making plane

In a separate paper we have introduced the decision making plane as a means to graphically present the results of the decision rule (Sendi et al., 2002). Figure 1 presents an example of the decision-making plane in which $\Delta E(A) - \Delta E(B)$ is assigned to the horizontal axis and $\Delta C(A) - \Delta C(B)$ to the vertical axis. These two axes divide the plane into four quadrants. The joint probability density function of interest is $f(\Delta C(A) - \Delta C(B), \Delta E(A) - \Delta E(B))$. The proportion of the density function lying in quadrant I reflects the probability that the conditions of the decision rule are met. For a more technical description we refer the reader to the Appendix.

When applying the approach described above, one must specify the acceptable probability that the conditions of the decision rule are not satisfied (Sendi et al., 2002). This could be limited to an arbitrary level, say 5%, similar to accepting a 5% Type I error in hypothesis testing. Alternatively, the decision-maker could be asked to determine the probability she is willing to accept that the algorithm would not result in an unambiguous improvement of the allocation of resources. However, the major drawback of the approach described above is that it is limited to the four programs (i.e., program A, a, B and b) under consideration. In the next section we propose an alternative way of handling uncertainty in economic evaluation that can be extended to include multiple health care programs in the analysis.

Stochastic dominance and affordability

Stochastic dominance (Whitmore and Findlay, 1978) is a useful alternative concept for handling uncertainty in economic evaluation and is complementary to the approach described above. Here, in contrast to the approach described in the previous section, we analyse uncertainty surrounding health outcomes and costs of health care programs separately. We separate costs and effects in order to be able to compare health outcomes of different portfolios using the concept of stochastic dominance, and to compare costs using the concept of affordability, which will be explained below. The decision rule shifts the distribution of health effects towards more health outcomes and therefore usually results in a situation where we have stochastic dominance with respect to health outcomes. Stochastic dominance allows one to evaluate mutually exclusive choices between different portfolios of health care programs in the presence of uncertainty. The advantage of stochastic dominance rules is that little information on the decision maker's utility function is required. First order stochastic dominance (FSD) includes the class of utility functions whose member functions are strictly increasing. This includes decision-makers whose utility is monotonically increasing in health outcomes regardless of whether they are risk-neutral, risk-seeking or risk-averse. We will discuss FSD by analyzing the situation described in section 2 using the same hypothetical data set.

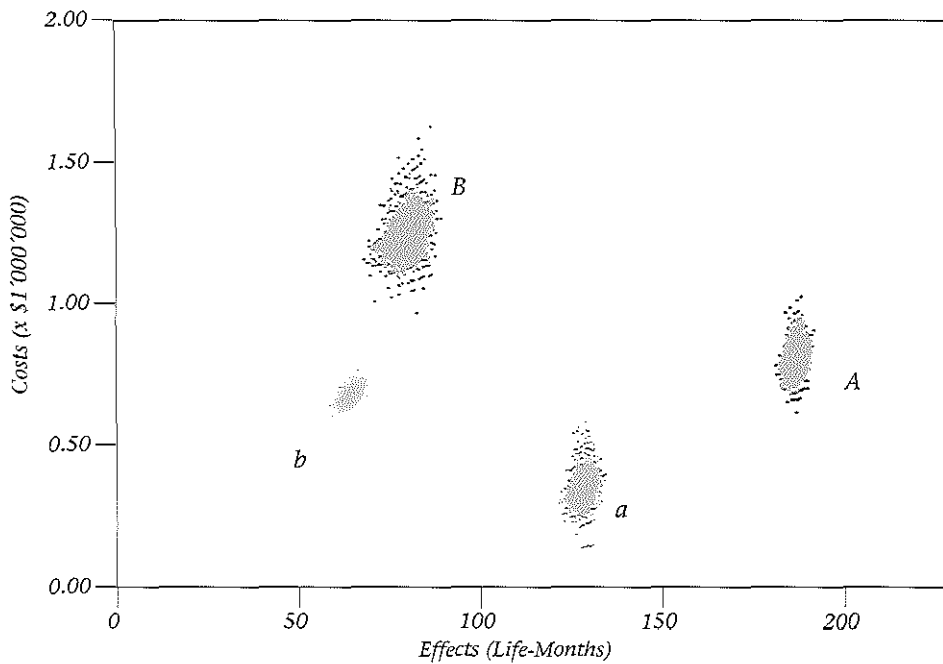


Figure 2. Joint distribution of costs and effects of four individual programs

Let $PF[x,y]$ denote a portfolio with two independent health care programs x and y . Note that in this section we analyze "reduced" portfolios (i.e., portfolios with two programs) in order to illustrate the complementary nature of the approach to the one described in the previous section. Portfolios comprising more than two programs will be dealt with in the next section. Let the current portfolio be $PF[a,B]$ and the portfolio after the application of the decision rule $PF[A,b]$. Let C_{a+B} and E_{a+B} denote the costs and effects of $PF[a,B]$. Further, let C_{A+b} and E_{A+b} denote the costs and effects of $PF[A,b]$. The joint distributions $f(C_i, E_i)$, $i=A,a,B,b$ are shown in Figure 2. All hypothetical distributions in this paper are generated from a published cost-effectiveness model (Sendi et al., 1999). The joint distributions $f(C_{a+B}, E_{a+B})$ and $f(C_{A+b}, E_{A+b})$ can be approximated using resampling techniques:

1. Draw a set of values from the joint distributions $f(C_i, E_i)$, $i=A,a,B,b$
2. Calculate C_{a+B} , C_{A+b} , E_{a+B} and E_{A+b}
3. Repeat k number of time [k usually ≥ 1000]

We can now check whether FSD in health outcomes is present. The rule is that if F and G are the cumulative distributions of two options, then F dominates G by FSD if $F(x) \leq G(x)$ for all x (Whitmore & Findlay, 1978) where the weak inequality (\leq) must be a strict inequality for at least one value of x . That is, the cumulative probability of $X \leq x$ for F (for a random variable X at a specific value of x) is equal to or smaller than the cumulative probability of

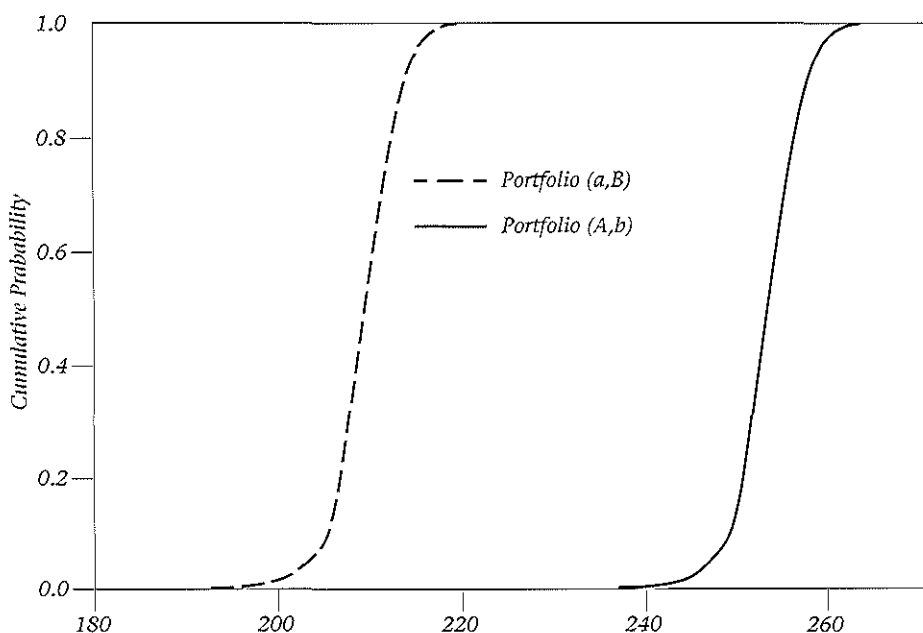


Figure 3a. Cumulative distribution function (CDF) of health outcomes of the reduced portfolios.

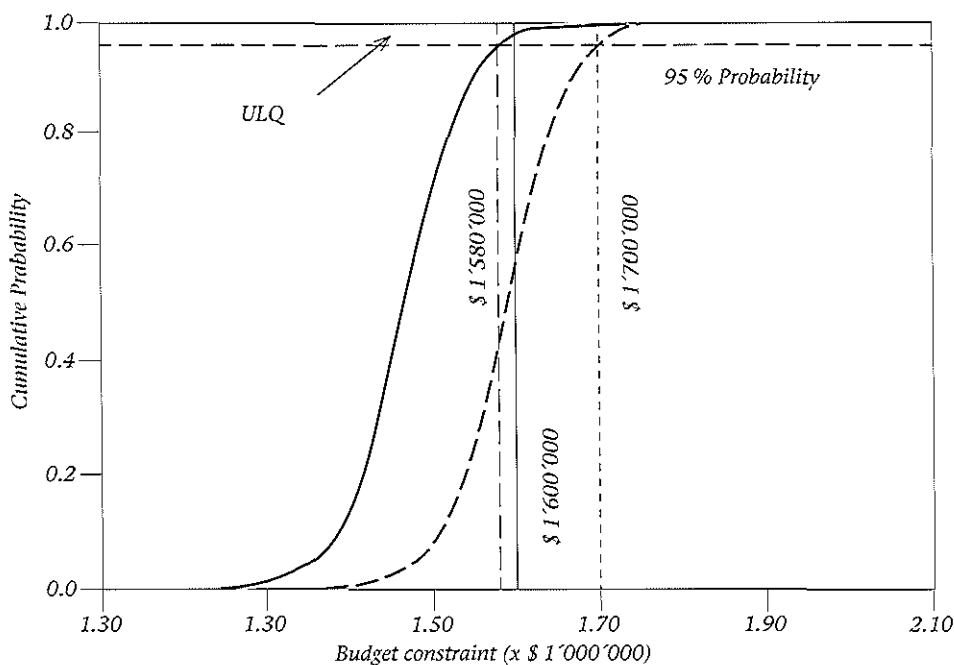


Figure 3b. Cumulative distribution function of costs of the reduced portfolios. ULQ denotes upper left quadrant; vertical dotted line: budget level \$1'700'000; vertical solid line: budget level \$1'600'000; vertical broken line: budget level \$1'580'000; horizontal broken line: the decision-maker's probability constraint of exceeding the budget (5%).

$X \leq x$ for G . This is equivalent to the cumulative probability $X > x$ being higher for F than G . In order to evaluate whether $PF[A, b]$ dominates $PF[a, B]$ in terms of health outcomes by FSD, we need to evaluate whether $F_{A+b}(E) \leq F_{a+B}(E)$, where E denotes the health outcomes (e.g. life-years). $F_{A+b}(E)$ and $F_{a+B}(E)$ denote the cumulative distributions of E_{A+b} and E_{a+B} respectively. $PF[A, b]$ dominates $PF[a, B]$ if $F_{A+b}(E) \leq F_{a+B}(E)$ for all values of E and is strictly less for at least one E . That is, the cumulative distribution function $F_{A+b}(E)$ must never lie above $F_{a+B}(E)$ and must be below $F_{a+B}(E)$ for at least one value of E . $\hat{F}_{A+b}(E)$ and $\hat{F}_{a+B}(E)$ are approximations of $F_{A+b}(E)$ and $F_{a+B}(E)$ which are found by counting the proportion of samples below or equal to E for all E (using a set 5000 simulated values). The two cumulative distribution functions (CDF) are shown in Figure 3a. $PF[A, b]$ dominates $PF[a, B]$ because the CDF of portfolio $PF[A, b]$ is to the right of the CDF of $PF[a, B]$ without any overlap. A decision-maker should therefore prefer $PF[A, b]$ over $PF[a, B]$.

We now analyze the uncertainty surrounding the costs of the two portfolios using the concept of affordability. We use the term "portfolio affordability curve" in order to denote the cumulative distribution of the total costs of a portfolio. Decision-makers might prefer more practical information in terms of probabilities associated with exceeding various budgetary constraints before they decide to reallocate resources. The portfolio affordability curve allows one to summarize this information in a straightforward manner by describing the probability that a given portfolio is affordable (i.e., lies within the budget constraint). The portfolio affordability curve for $PF[a, B]$ is approximated by $\hat{F}_{a+B}(C)$, and the portfolio affordability curve for $PF[A, b]$ is approximated by $\hat{F}_{A+b}(C)$. These two curves are shown in figure 3b. As can be seen, the curve for the portfolio $PF[A, b]$ lies above and to the left of the curve for the portfolio $PF[a, B]$.

For a decision-maker faced with a budget constraint of e.g. \$1'700'000 with an acceptable risk of exceeding the budget of 5% we can define four quadrants in Figure 3b. We can see two important effects of the decision rule by comparing the two portfolio affordability curves. First, if the budget constraint is kept constant in our hypothetical example (e.g. vertical dotted line at \$1'700'000 in Figure 3b), then replacing portfolio $PF[a, B]$ with $PF[A, b]$ leads to an increased probability of satisfying the budget constraint (from 95% to 99%). This is shown in Figure 3b by the intersection of the vertical dotted line at \$1'700'000 with the two portfolio affordability curves. The distance between the two intersections reflects the difference of 4% probability. Second, if the decision-maker is willing to accept the risk of exceeding the budget by 5% for both portfolios (horizontal broken line at 0.95 in Figure 3b), then the required budget for the second portfolio is lower than before, i.e. it shifts from \$1'700'000 (denoted by the vertical dotted line in Figure 3b) to \$1'580'000 (denoted by the vertical broken line in Figure 3b). These figures correspond to the intersection of the horizontal broken line at 0.95 with the two portfolio affordability curves.

This means that the decision-maker could invest the difference of \$120'000 in other health care programs since the budget requirements of the new portfolio are lower than the budget requirements of the old portfolio.

Information about the decision maker's risk-tolerance of exceeding a given budget (reflected by a horizontal line in Figure 3b at the respective risk level) in combination with the actual size of the budget (reflected by a vertical line in Figure 3b at the respective budget level) allows one to guide policy makers. With these two pieces of information four quadrants can be defined. If the portfolio affordability curve crosses the upper left quadrant (including the origin), then the requirements of the decision-maker are satisfied. The upper left quadrant reflects the situation where the risk of exceeding a given budget is lower than the decision-maker's acceptable risk. In cases where the portfolio affordability curve of a particular portfolio does not cross the upper left quadrant, the decision rule might help us to achieve this goal. This can be seen in Figure 3b. The portfolio affordability curve of the portfolio $PF[a,B]$ does not cross the upper left quadrant if we take \$1'600'000 as the budget (vertical solid line in Figure 3b) and 5% as the acceptable risk of exceeding the budget (horizontal broken line at 0.95). The decision rule, i.e. switching from portfolio $PF[a,B]$ to portfolio $PF[A,b]$, results in a shift of the portfolio affordability curve to the left so that the portfolio affordability curve now crosses the upper left quadrant. This indicates that the requirements of the decision maker are satisfied by the new portfolio $PF[A,b]$.

It is important to note that the approach described in the second section (i.e., the decision making plane approach) and the approach described in this section (i.e., the portfolio affordability approach) are complementary and do answer different questions as described below. We used the same hypothetical data set for the calculations in section two and section three. The decision making plane allowed us to estimate the probability $P(C_{A+b} > C_{a+B})$, which was 2%. Note that $C_{A+b} > C_{a+B}$ is equivalent to $\Delta C(A) > \Delta C(B)$, i.e. $[(C_A - C_a) > (C_B - C_b)] = [(C_A + C_b) > (C_a + C_B)]$. The portfolio affordability curve allows one to estimate the probabilities $P(C_{a+B} \leq BC | BC)$ and $P(C_{A+b} \leq BC | BC)$, where BC denotes the budget constraint. That is, although $P(C_{A+b} \leq BC | BC) \geq P(C_{a+B} \leq BC | BC)$ for all BC as shown in Figure 3b, it happens with 2% probability that $C_{A+b} > C_{a+B}$ when applying the decision rule (Figure 1). In other words, the approach using the decision making plane answers the question of what is the probability that the decision rule does not lead to a more efficient allocation of resources. The approach using the portfolio affordability curve, on the other hand, informs us, for a given budget constraint, what the probability is that this budget is exceeded.

A portfolio of multiple programs

In the above section we analyzed the decision rule by using two programs per portfolio (i.e., programs *A* and *b* versus programs *a* and *B*) in order to compare the approach with the one described in section two (i.e., the decision making plane approach). In the previous section the budget constraint was limited to the "reduced" portfolio. The portfolio approach can be extended to include more than two programs per portfolio. Decision-makers, say at the hospital level, generally hold a common pool of budget for multiple programs and are usually interested in the probability that their whole portfolio is within a given budgetary constraint. The "reduced" portfolio approach does not account for the costs and the associated uncertainty of the remainder of the programs in the portfolio. Because the budget constraint is for the total portfolio costs (i.e., the costs of all the programs), a decision-maker needs to analyze the distribution of the total costs of all the programs (and not just a subset). In this section the budget constraint applies to the "full" portfolio. Consider a scenario where a decision maker is currently funding $PF[1-7,a,B]$. The joint distribution of costs and effects of these nine individual programs in the current portfolio are shown in Figure 4 together with the joint distributions for programs *A* and *b*. The joint distributions for programs 1-7 are not labeled in order to keep the graph less busy.

Let us assume that a new more effective and more expensive program *A* becomes available which will replace program *a* (Figure 4). Since the decision-maker's budget is constrained, additional funds in order to support program

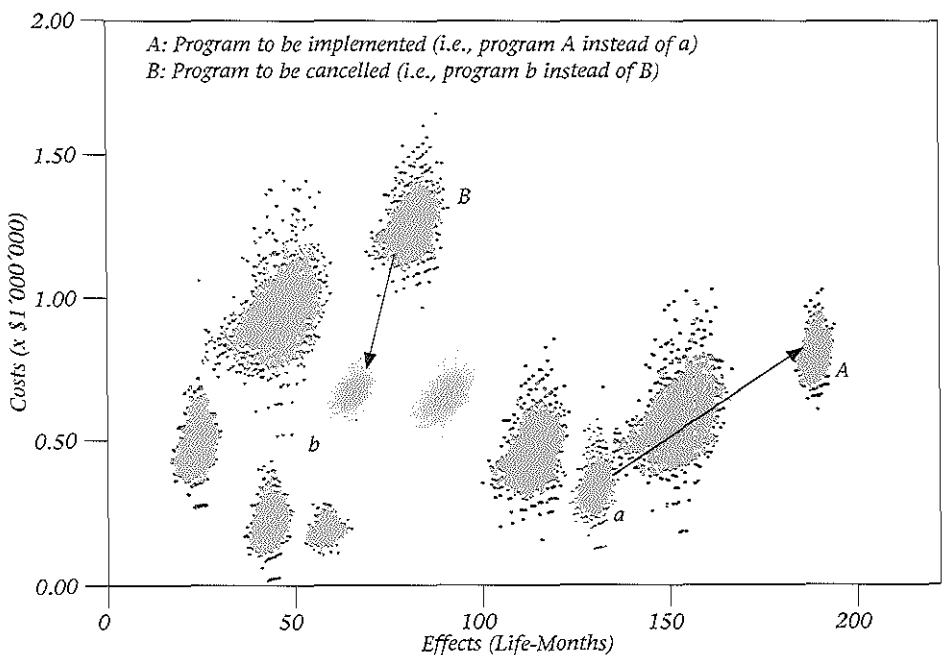


Figure 4. Joint distribution of costs and effects of eleven individual programs

A can only be made available by deleting current programs in the portfolio. The decision-maker could use stochastic integer programming to optimize the portfolio if he knew the costs and effects that would result if each of the programs in the current portfolio were cancelled. That is, we do not assume that canceling a program in the current portfolio results in zero costs and zero effects. If this assumption would hold, the question to be asked could be reduced to what combination of current programs falls within the budget constraint (subject to a given level of risk of going over budget) and results with the highest total outcome. However, in order to mimic a real-world situation, we assume that the decision-maker does not know, for all programs in the current portfolio, what costs and effects would result if the respective programs were cancelled. But our decision-maker, having the decision rule in mind, is able to find the required information for one program B in her current portfolio (i.e., the joint distribution of costs and effects of program b). By replacing program B with program b and shifting the released resources to meet the additional resource requirements of program A over current program a we shall increase the probability of achieving a higher overall health outcome without increasing the risk of exceeding the budget constraint. The new portfolio is then $PF[1-7,A,b]$.

In order to compare the two portfolios $PF[1-7,a,B]$ and $PF[1-7,A,b]$ we need to compute the corresponding distributions for total costs and total effects. This can be accomplished non-parametrically using simulation techniques. We assume that all programs are independent. Let C_i and E_i be the costs and

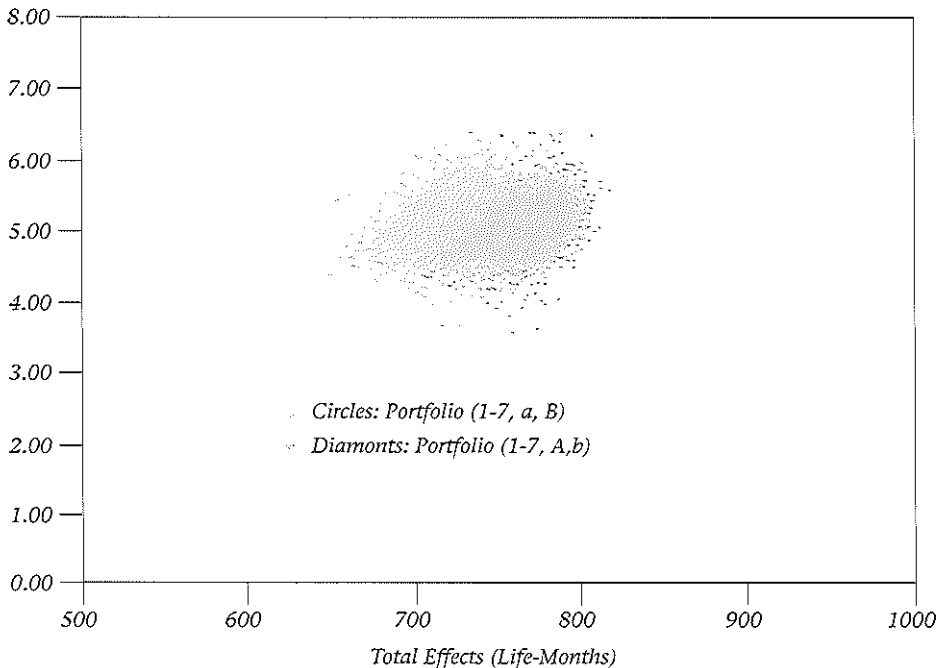


Figure 5. Joint distribution of total costs and total effects of two portfolios

effects of program $i=1,2,\dots,n$ describing a portfolio with n individual programs:

1. Draw a sample from the joint distribution $f(C_i, E_i)$ for $i=1,2,\dots,n$.
2. Calculate $C_{\text{portfolio}} = \sum_{i=1}^n C_i$ and $E_{\text{portfolio}} = \sum_{i=1}^n E_i$
3. Repeat k number of times [k usually ≥ 1000] to approximate the joint distribution $f(C_{\text{portfolio}}, E_{\text{portfolio}})$.

This procedure allows us to include the additional uncertainty associated with costs and effects in programs 1-7. For the first portfolio $PF[1-7,a,B]$, which is the portfolio before applying the decision rule, we include in the sampling procedure the joint distributions of costs and effects of programs 1-7 and programs B and a . This approximates the joint distribution of total costs and effects of the portfolio $PF[1-7,a,B]$ as depicted in Figure 5. For the second portfolio $PF[1-7,A,b]$, which is the portfolio after the application of the decision rule, we include in the sampling procedure programs 1-7 and programs A and b . The joint distribution of total costs and effects of the second portfolio $PF[1-7,A,b]$ is also shown in Figure 5. As we can see, by applying the decision rule, the joint distribution of the portfolio shifts to the southeast on a plane where total costs are plotted against total effects. This means that the probability of achieving more health outcomes is increased while the risk of exceeding the budget constraint is decreased. That is, the goal of increasing total effectiveness without the need of increasing the budget is met.

The impact of the decision rule on total effectiveness is also shown in Figure 6a. The new portfolio is stochastically dominant over the old portfolio. Furthermore, the portfolio affordability curve (Figure 6b) for $PF[1-7,A,b]$ lies to the left of the one for $PF[1-7,a,B]$, indicating that the required budget decreased at the same 5% risk-level of exceeding the budget (denoted by the intersection of the horizontal broken line in figure 6b with the two portfolio affordability curves). Or alternatively, that the probability of exceeding a given budget constraint decreased (indicated by the intersection of the vertical broken line in Figure 6b with the two portfolio affordability curves). Note that the inclusion of the uncertainty of those programs in the portfolio which are not subject to the decision rule leads to similar figures as described in the above section. This is because we expect the decision rule to have the same effect in terms of changes of overall costs and effects in a "full" portfolio of programs although the relative magnitude of the effect will be smaller. However, decision-makers (e.g. hospital managers) may know the total costs rather than the total health outcomes associated with their portfolio. In such a situation we could assess the impact of the decision rule using the "full" portfolio ap-

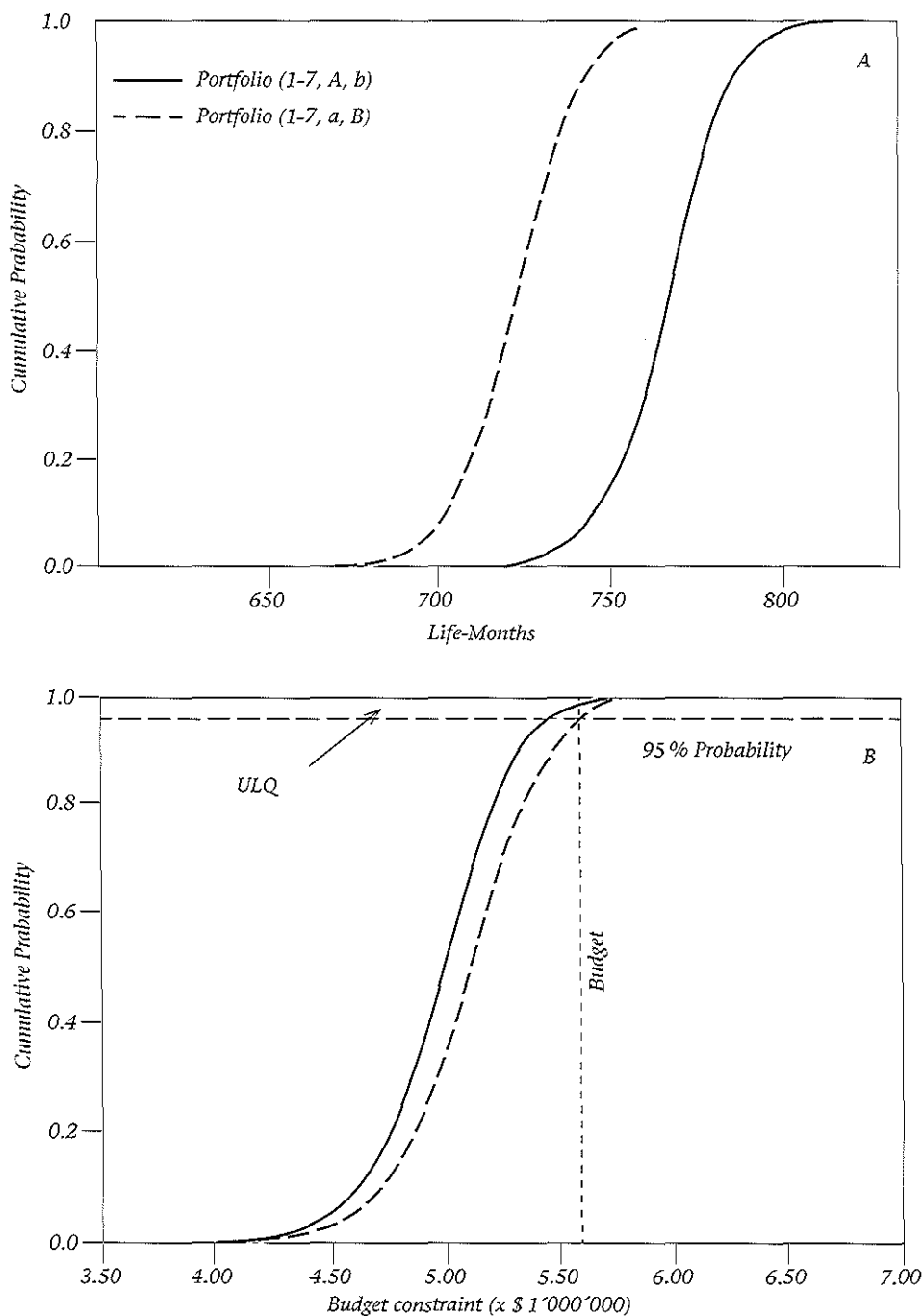


Figure 6. Cumulative distribution function (CDF) of health outcomes (Figure 6A) and costs (Figure 6B) of the full portfolios

proach for costs (since the constraint is on total costs) and the "reduced" portfolio approach for health outcomes, assuming that programs are independent. However, any interdependence between programs would require modification of the equations for the assessment of both outcomes and costs.

Note that the "full" portfolio approach is needed in order to assess whether a reallocation of resources meets the decision-maker's probability threshold for exceeding the total budget. This information is not provided by the "reduced" portfolio approach, which ignores the impact of the decision rule on total expenses. A switch of programs, which might be deemed worthwhile from the "reduced" portfolio perspective, does not necessarily need to meet the decision-maker's constraints when total costs are considered. That is, only the portfolio affordability curve for the "full" portfolio informs us whether the requirements of the decision-maker in terms of containing total costs are satisfied.

Finally, in addition to analyzing the distributions of overall health outcomes and total costs, we could impose the additional constraint that $P(E_{A \rightarrow b} < E_{a \rightarrow B}) = 0$. This would correspond to the probability of any outcome falling in quadrant II and quadrant III of the decision making plane being zero (which was the case in our hypothetical example, see Figure 1). This additional constraint prevents that replacing program *a* and program *B* by program *A* and program *b*, respectively, would result in a reduction of health outcomes.

Discussion

In the real world, decision makers usually have to operate a portfolio of health care programs, are limited by budgetary constraints and face uncertainty associated with costs and effects of all health care programs. Moreover, the availability of information on all programs in a health care system is imperfect so that lack of data is a common problem. We have suggested a framework for handling such a situation by embedding the decision rule described by Birch and Gafni (1992) within a portfolio of multiple programs in the context of maximizing health outcomes from available health care resources.

The decision-maker's budget and probability constraints are central in our paper. In order to determine whether the requirements of the decision-maker are met, we need information about the available budget and the decision-maker's risk-tolerance. There are different options to determine this risk-level. First, one could use an arbitrary threshold such as a 5%-risk level of exceeding the budget. Second, one could elicit the risk-level by asking the decision-maker. Different decision-makers might accept different risk-levels of exceeding the budget. Finally, the risk level could be derived from the current portfolio. The current portfolio has a risk of going over budget associated with it. By choosing that portfolio the decision-maker has implicitly consented to accept that level of risk. In addition to the probability of going over budget, the de-

cision-maker might also be interested in the magnitude of deviation from the budget at the respective risk-level. Although not discussed in this paper, this information might influence the decision-maker's risk-tolerance in the sense that a low risk of a high deviation might be less acceptable than a high risk of a low deviation.

The upper left quadrant (on a plane where we plot the portfolio affordability curve) defined by the budget and the acceptable risk of exceeding the budget can be used to build up/modify portfolios of health care programs. The decision-maker can successively add programs to the portfolio as long as the portfolio affordability curve crosses the upper left quadrant. Once the portfolio affordability curve of the portfolio does not cross the upper left quadrant, the investment is not within the prescribed boundaries anymore. Health outcomes can then only be increased by reallocating resources. The use of the algorithm delineates the fact that the decision-maker has reached a point where she cannot add programs to her portfolio anymore without downsizing/deleting other programs. If different sizes of programs were to be considered in the analysis, then the respective distributions of costs and effects would be needed (which might not be readily available in practice). However, by changing the composition of the portfolio according to the decision rule she can make more efficient use of the available resources.

In conclusion, where information is available on the distribution of costs and effects of those programs under consideration, the approach presented in this paper offers a feasible method of making more efficient use of available resources. In particular, the decision rule can be used to inform policy makers faced with uncertainty associated with costs and effects and constrained resources. The information needed to optimize the portfolio until it meets the requirements of the decision maker is the size of the budget and the acceptable risk of going over budget. Although the information requirements may not be currently satisfied, the research required to generate such information may be a small price to pay to achieve a more efficient use of health care resources.

Appendix

A Technical note on the decision rule under uncertainty

The proportion of the density function $f(\Delta C(A) - \Delta C(B), \Delta E(A) - \Delta E(B))$ lying in quadrant I of the decision making plane (Figure 1) reflects the probability that the conditions of the decision rule are met. This is given by the solution to the double integral

$$\int_0^{\infty} \int_{-\infty}^0 f(\Delta C(A) - \Delta C(B), \Delta E(A) - \Delta E(B)) d(\Delta C(A) - \Delta C(B)) d(\Delta E(A) - \Delta E(B)). \quad (A.1)$$

The probability that the decision rule does not result in an unambiguous improvement of the allocation of resources is reflected by the double integral

$$1 - \int_0^{\infty} \int_{-\infty}^0 f(\Delta C(A) - \Delta C(B), \Delta E(A) - \Delta E(B)) d(\Delta C(A) - \Delta C(B)) d(\Delta E(A) - \Delta E(B)). \quad (A.2)$$

Depending on the actual probability density function, this integral can be calculated algebraically, or estimated numerically or by simulation from the density function. In our examples we have used the simulation method based on the assumption of joint normality. Let M denote the total number of samples approximating $f(\Delta C(A) - \Delta C(B), \Delta E(A) - \Delta E(B))$ and m the number of samples satisfying the decision rule. The hypothetical example in Figure 1 is based on $M = 5000$ set of values approximating the distribution $f(\Delta C(A) - \Delta C(B), \Delta E(A) - \Delta E(B))$. If $m[(\Delta C(A) - \Delta C(B) \leq 0, \Delta E(A) - \Delta E(B) > 0) \cup (\Delta C(A) - \Delta C(B) < 0, \Delta E(A) - \Delta E(B) = 0)]$ represents the number of times that the two mutually exclusive events $(\Delta C(A) - \Delta C(B) \leq 0, \Delta E(A) - \Delta E(B) > 0)$ and $(\Delta C(A) - \Delta C(B) < 0, \Delta E(A) - \Delta E(B) = 0)$ occurred among M draws, then the estimated probability that the decision rule is satisfied is

$$\frac{m[(\Delta C(A) - \Delta C(B) \leq 0, \Delta E(A) - \Delta E(B) > 0) \cup (\Delta C(A) - \Delta C(B) < 0, \Delta E(A) - \Delta E(B) = 0)]}{M} = \frac{m(\Delta C(A) - \Delta C(B) \leq 0, \Delta E(A) - \Delta E(B) > 0) + m(\Delta C(A) - \Delta C(B) < 0, \Delta E(A) - \Delta E(B) = 0)}{M} \quad (A.3)$$

and the estimated probability that the decision rule is not satisfied is

$$1 - \frac{m[(\Delta C(A) - \Delta C(B) \leq 0, \Delta E(A) - \Delta E(B) > 0) + m(\Delta C(A) - \Delta C(B) < 0, \Delta E(A) - \Delta E(B) = 0)]}{M} \quad (A.4)$$

In the example in Figure 1, the estimated probability that the decision rule is satisfied is 0.98, and the estimated probability that it is not satisfied is 0.02 = (1-0.98). Note that the samples are limited to quadrant I and IV which simplifies the estimation of the probability that the decision rule is satisfied to

$$\frac{m(\Delta C(A) - \Delta C(B) \leq 0)}{M} \quad (A.5)$$

■ Chapter 4

Revisiting the decision rule of cost-effectiveness analysis under certainty and uncertainty

Summary

The classical decision rule of cost-effectiveness analysis uses a threshold cost-effectiveness ratio as a cut-off point for resources allocation. One assumption of this decision rule is complete divisibility of health care programs. In this article we argue that health care programs cannot be completely divisible since individuals are not divisible. Consequently, instead of a linear programming approach, an integer programming approach to budget allocation is suggested. The integer programming framework can be extended to include uncertainty in the analysis. An objective function (expected aggregate effects) is maximized subject to the constraint that the probability of exceeding the budget is limited to an arbitrary level (e.g., 0.05). In case the budget is exceeded, the objective function is penalized in order to account for the opportunity costs of the additional resource requirements.

Introduction

Cost-effectiveness analysis is increasingly being used to inform policy and decision makers in the health care field. It is usually assumed that the goal of cost-effectiveness analysis is to maximize health outcomes for a given budget. Under the assumption of complete divisibility of programs, the decision rule algorithm follows from a linear programming problem (Weinstein and Zeckhauser, 1973; Stinnett and Paltiel, 1996). According to this decision rule, an optimal allocation of resources is achieved by ordering programs according to their cost-effectiveness ratio and successively implementing them, starting with the most cost-effective program, until the budget is exhausted (Johannesson and Weinstein, 1993; Weinstein, 1995; Karlsson and Johannesson, 1996). The cost-effectiveness ratio of the last implemented program, then, represents the critical ratio used as a cut-off point for resources allocation. This decision rule of cost-effectiveness analysis has been hashed and rehashed by different authors (Weinstein, 1995; Karlsson and Johannesson, 1996; Johannesson and Weinstein, 1993; Birch and Gafni, 1992, 1993; Gafni and Birch, 1993).

Arguably, the assumption of perfect divisibility is not realistic in practice. It can be unethical to introduce a new treatment for only a fraction of the eligible patients, while the remaining patients receive an 'old' treatment which is less effective. However, ethics aside, complete divisibility is an assumption that will never be met in practice since individuals are not divisible. The decision rule may therefore lead to suboptimal budget allocation decisions as we will show in this paper. Consequently, an integer programming approach where individuals represent indivisible units is more appropriate to formulate the budget allocation problem. We extend the integer programming approach to include uncertainty in the analysis. Hereby the objective function is maximized subject to the constraint that the probability of exceeding the budget is limited to an arbitrary level. We then introduce the idea of penalizing the objective function in situations where the budget is exceeded in order to account for the opportunity costs of the additional resource requirements.

Note that in this paper we shall not question the assumption of constant returns to scale, which is also needed for the decision rule to be valid. Whether the assumption of constant returns to scale is met in a specific situation is an empirical question. For example, the assumption of constant returns to scale will not be met when programs have high capital costs (e.g. radiation therapy in oncology), but it may be met when patients undergo treatments that are solely based on prescription drugs (e.g. antibiotic treatment of infectious diseases). Thus, if the whole health care budget is not subject to the allocation process, but for example only the budget for pharmaceuticals, then the assumption of constant returns to scale may be appropriate. This situation might for instance occur in The Netherlands, where the health care budget is divided into separate compartments with one specifically for pharmaceuticals.

The decision rule under certainty

Consider the hypothetical example in Table 1. There are three patient groups (v, w, z) and in each patient group there are 1000 patients. The treatments provided in each patient group (i.e., [V1, V2, V3, V4] in patient group v, [W1, W2, W3] in patient group w, and [Z1, Z2, Z3, Z4] in patient group z) are mutually exclusive. The incremental cost-effectiveness ratios after the exclusion of treatments V2, W2, and Z2 by extended dominance are also shown in Table 1. According to the decision rule, we would start providing treatment V1 (which has the lowest cost-effectiveness ratio), and then continue providing treatments with an increasingly higher cost-effectiveness ratio until our budget is exhausted. We can reformulate our optimization problem as follows:

$$\text{maximize: } \sum x_i e_i \quad (1)$$

$$\text{subject to: } 0 \leq x_i \leq 1000 \text{ (for all } i; x_i = \text{integer}), \quad (2)$$

$$\sum x_i c_i \leq C, \quad (3)$$

$$\sum x_i \leq 1000 \text{ (for } i \in V), \quad (4)$$

$$\sum x_i \leq 1000 \text{ (for } i \in W), \quad (5)$$

$$\sum x_i \leq 1000 \text{ (for } i \in Z), \quad (6)$$

where e_i and c_i denote the effects and costs of treatment i per patient, C denotes the budget, x_i denotes the number of patients to whom treatment i is provided, and V , W , and Z denote sets of mutually exclusive treatments. Note that the decision variable x_i must be an integer since patients are not divisible.

Excel Solver (Excel 97 for Windows) was used to solve this optimization problem. We maximized the aggregate effects (the value of the objective function (1)) subject to the constraints (2) – (6). The results for different budget levels are shown in Table 2. Under some budgetary constraints, treatments that would have been excluded under the decision rule are indeed provided to some patients. This is because, for obvious reasons, patients are not divisible.

For example, at a budget level of \$1'000'000, 1000 patients receive treatment V3, 712 patients receive treatment W1, 288 patients receive treatment W3, 4 patients receive treatment Z1, and 996 patients receive treatment Z3. The aggregate effects are 65856 and the total budget is exhausted. In contrast, using a simple linear model assuming complete divisibility, 1000 patients would receive treatment V3, 1000 patients would receive treatment Z3, 714.3 patients would receive treatment W1 and 285.7 patients treatment W3. The aggregate effects would then be 65857 and the budget would be exhausted. However, we cannot treat 0.7 or 0.3 patients, i.e. patients are not divisible.

Table 1. Cost per patient (C), effect per patient (E), and incremental cost-effectiveness ratio per patient ($\Delta C / \Delta E$) for hypothetical treatment alternatives in three different patient groups (v; w; z)

Treatment	C	E	$\Delta C / \Delta E$	$\Delta C / \Delta E^a$
V1	200	20	10	10
V2	300	25	20	
V3	400	32	14	17
V4	500	35	33	33
W1	200	11	18	18
W2	250	13	25	
W3	550	28	20	21
Z1	100	8	13	13
Z2	200	12	25	
Z3	300	18	17	20
Z4	400	20	50	50

^a After exclusion of treatment alternatives by extended dominance

Table 2. Number of patients to be treated in each treatment group in order to maximize aggregate effects subject to the budget constraint.

Budget ^b	Number of patients per treatment ^a											Aggregate effects ^c
	V1	V2	V3	V4	W1	W2	W3	Z1	Z2	Z3	Z4	
100	500											10000
200	1000											20000
300	1000							1000				28000
400	500		500					1000				34000
500			1000					1000				40000
600			1000		500			1000				45500
700			1000		1000			1000				51000
800			1000		1000			500		500		56000
900			1000		1000					1000		61000
1000			1000		712		288	4		996		65856
1100			1000		426	3	571			1000		70713
1200			1000		142	1	857			1000		75571
1300			500	500			1000			1000		79500
1450				1000			1000				1000	83000

^a There are 1000 patients per treatment group

^b Budget in \$1000

^c $\sum x_i e_i$

Providing W1 to 714 patients and W3 to 286 patients would exceed the budget by \$100. Providing W1 to 715 patients and W3 to 285 patients results in aggregate effects of 65845 and a leftover budget of 250\$, clearly a suboptimal allocation of resources. As another example, consider the budget levels \$1'100'000 and \$1'200'000 in Table 2. Treatment W2 is provided to some patients in order

to maximize aggregate effects (i.e., it would be impossible to use the complete budget otherwise). Treatment W2 would have been excluded by extended dominance if we were to apply the classical decision rule of cost-effectiveness analysis.

The decision rule under uncertainty

In the previous section we suggested an integer programming approach to budget allocation since individuals are not divisible. The approach can be extended to include uncertainty in the analysis. Consider the hypothetical data shown in Table 3. The mean costs and variance and mean effects and variance associated with treating a patient are shown for each treatment option. We assume normal distributions for costs and effects for demonstration purposes. However, the optimization approach is also possible with non-normal distributions (e.g. when costs follow a skewed distribution). We assume that costs and effects for each treatment option are correlated ($\rho=0.7$). Our optimization problem can be formulated as:

$$\text{maximize:} \quad E(\sum x_i c_i - h), \quad (7)$$

$$\text{where } h = \begin{cases} 0 & \text{if } \sum x_i c_i \leq C, \\ (\sum x_i c_i - C)/\beta & \text{if } \sum x_i c_i > C, \end{cases}$$

$$\text{subject to:} \quad 0 \leq x_i \leq 1000 \quad (\text{for all } i; x_i = \text{integer}), \quad (8)$$

$$P(\sum x_i c_i > C) \leq 0.05, \quad (9)$$

$$\sum x_i \leq 1000 \quad (\text{for } i \in V), \quad (10)$$

$$\sum x_i \leq 1000 \quad (\text{for } i \in W), \quad (11)$$

$$\sum x_i \leq 1000 \quad (\text{for } i \in Z), \quad (12)$$

where the objective function (7) is the expected penalized aggregate effect. When costs are uncertain, we cannot stay within the budget with certainty. However, we can add a constraint and limit the probability of exceeding the budget to an arbitrary level, say 0.05 as defined in (9). Nonetheless, when the budget is exceeded we need to consider the opportunity costs of the additional resource requirements. We therefore include a penalty function h in our optimization model. When the budget is exceeded (i.e., $\sum x_i c_i > C$), the health outcomes lost by deriving resources from other sectors is modeled by $(\sum x_i c_i - C)/\beta$. Constant marginal opportunity costs would be reflected by a constant value of β . However, β may increase or decrease as $\sum x_i c_i - C$ varies, reflecting increasing

Table 3. Mean costs and variance (μ_c , σ_c^2) and mean effects and variance (μ_e , σ_e^2) associated with treating a patient.

Treatment	μ_c	σ_c^2	μ_e	σ_e^2	ρ^a
V1	200	40	20	4	0.7
V2	300	40	25	4	0.7
V3	400	40	32	4	0.7
V4	500	40	35	4	0.7
W1	200	40	11	4	0.7
W2	250	40	13	4	0.7
W3	550	40	28	4	0.7
Z1	100	40	8	4	0.7
Z2	200	40	12	4	0.7
Z3	300	40	18	4	0.7
Z4	400	40	20	4	0.7

^aThe correlation of costs and effects per treatment alternative is denoted by ρ .

or decreasing marginal opportunity costs of the additional resource requirements. In our analysis we used a constant value of $\beta=10$ for simplicity.

Simple optimization packages such as Excel Solver cannot solve optimization problems in the presence of distributions. We used RISKOptimizer (Palisade Corp., Newfield, NY, USA), a more advanced optimization tool which combines simulation with genetic algorithms (see Goldberg, 1989) to find an optimal solution. The optimization starts with a simulation using an initial combination of the decision variables (i.e., the x_i 's): the distribution of costs and effects of the treatment options are sampled a large number of times and the spreadsheet is recalculated. At the end of each simulation the constraint (9) must be met, otherwise the trial solution is discarded. Note that (9) is a constraint that is evaluated at the end of a simulation, while the other constraints are range constraints and must be met before a simulation is performed. The value of the statistic of interest (i.e., (7)) is calculated from the distribution generated by the simulation. This statistic is then used to select the next set of decision variables using genetic algorithms. This process is repeated a large number of times and leads to an optimal solution which maximizes $E(\sum x_i e_i - h)$. This simulation optimization was performed for four budget levels (Table 4). Since the simulation optimization could theoretically run for years until the best solution is found, we needed to define a stopping condition for efficiency reasons. The simulation optimization was stopped if it took longer than 2 hours or if no improvement was found in the last 100 simulations (default setting in RISKOptimizer). The results of the analysis for the four budget levels are shown in Table 4. The number of patients to be treated in each treatment group in order to maximize $E(\sum x_i e_i - h)$ vary with the budget level and include all treatment options.

Our approach assumes that decision-makers are risk-neutral towards health and risk-averse towards costs (Al, 2001). Decision-makers, however, may be risk-averse towards health and may prefer a lower value of $E(\sum x_i e_i - h)$ if the variance could be reduced. For example, at a budget level of \$1'000'000, a decision-maker may prefer to minimize $VAR(\sum x_i e_i - h)$ as long as $E(\sum x_i e_i - h)$ is no less than 40'000. This changes the optimization problems to:

$$\text{minimize:} \quad VAR(\sum x_i e_i - h), \quad (13)$$

$$\text{where } h = \begin{cases} 0 & \text{if } \sum x_i c_i \leq C, \\ (\sum x_i c_i - C)/\beta & \text{if } \sum x_i c_i > C, \end{cases}$$

subject to:

$$0 \leq x_i \leq 1000 \text{ (for all } i; x_i = \text{integer}) \quad (14)$$

$$P(\sum x_i c_i > C) \leq 0.05, \quad (15)$$

$$E(\sum x_i e_i - h) \geq D, \quad (16)$$

$$\sum x_i \leq 1000 \text{ (for } i \in V), \quad (17)$$

$$\sum x_i \leq 1000 \text{ (for } i \in W), \quad (18)$$

$$\sum x_i \leq 1000 \text{ (for } i \in Z), \quad (19)$$

where D represents the aspiration level for $E(\sum x_i e_i - h)$. The results of the simulation optimization are shown in Table 5. The trial solution found lowers $VAR(\sum x_i e_i - h)$ to 898'704 at a value of 41'300 for $E(\sum x_i e_i - h)$.

Table 4. Number of patients to be treated in each treatment group in order to maximize expected penalized aggregate effects $E(\sum x_i e_i - h)$ subject to the constraint that the probability of exceeding the budget is ≤ 0.05 .

	Number of patients per treatment ^a												
Budget ^b	V1	V2	V3	V4	W1	W2	W3	Z1	Z2	Z3	Z4	$E(\sum x_i e_i - h)$	$VAR(\sum x_i e_i - h)$
100		11		6	1			698	7			6'179	1'929'321
500	56	807	7	11	10	357	3	698	7	9	93	33'387	4'848'804
1000	56	808	107	29	61	381	558	663	112	87	138	56'914	6'543'364
1500				895			1000			9	991	82'493	11'950'849

^a There are 1000 patients per treatment group

^b Budget in \$1000

Table 5. Number of patients to be treated in each treatment group in order to minimize the variance of penalized aggregate effects $VAR(\sum x_i e_i - h)$ subject to the constraint that the probability of exceeding the budget is ≤ 0.05 and that the expected penalized aggregate effect $E(\sum x_i e_i - h) \geq 40'000$.

	Number of patients per treatment ^a													
Budget ^b	V1	V2	V3	V4	W1	W2	W3	Z1	Z2	Z3	Z4	$E(\sum x_i e_i - h)$	$VAR(\sum x_i e_i - h)$	
1000	56	391	107	29	61	381	425	297	112	175	138	41300	898704	

^a There are 1000 patients per treatment group

^b Budget in \$1000

Discussion

In this paper we have argued that health care programs can technically never be treated as completely divisible because patients are not divisible. Consequently, the usual decision rule of cost-effectiveness analysis may lead to suboptimal budget allocation decisions at the margin. However, as Weinstein (1995) argues, the linear programming approach may be seen as a reasonable approximation to the integer programming approach under deterministic assumptions. Whether this is true when costs and effects are stochastic is an area for future research.

Birch and Gafni (1992, 1993) discussed the issue of divisibility at the level of programs, i.e. they described the optimization problem assuming that a program is either completely implemented or not at all. Stinnett and Paltiel (1996) suggested a mixed integer programming approach to handle partial indivisibilities in the sense that a threshold implementation level must be met before a program is (partially or completely) implemented. This approach can, for example, be used to model partial indivisibilities because of ethical reasons or capital costs. However, the issue that programs are partially indivisible because individuals are indivisible has not been addressed yet. This is modeled by constraining the decision variables (i.e., number of patients) in the optimization model to be integers. When using an integer programming approach, treatments that would have been excluded by extended dominance or that would not have been provided under the assumption of complete divisibility (i.e., using a linear programming approach) may now be provided to some patients.

The integer programming approach can be extended to handle uncertainty of costs and effects at the patient level. Current methods for handling uncertainty in cost-effectiveness analysis (such as net health benefits or cost-effectiveness acceptability curves) (Stinnett and Mullahy, 1998; van Hout et al., 1994) are descriptive and hence do not *per se* provide any guidance as to how the budget should be allocated (Al, 2001). The decision-maker's preferences over uncertain costs and effects are explicitly or implicitly needed in decision-making (Al, 2001). A pragmatic approach is to maximize expected health outcomes subject to the constraint that the probability of exceeding the budget is limited to an arbitrary level (e.g., 0.05). However, decision-makers such as insurance companies may also be risk-averse towards health outcomes (Al, 2001). The decision-maker might then want to minimize uncertainty surrounding health outcomes subject to the constraint that an aspiration level for health outcomes is met. This is similar to the portfolio approach by O'Brien and Sculpher (2000) where a tradeoff is made between maximizing expected returns and minimizing uncertainty. However, O'Brien and Sculpher (2000) based their framework on the effectiveness-cost ratio, which might become problematic if the effectiveness-cost ratio takes on negative values. Moreover,

the variance of the effectiveness-cost ratio may often not be defined. Our optimization approach, in contrast, handles costs and effects separately and also includes the correlation between the two in the analysis.

An interesting recent attempt to address the decision-maker's problem is the stochastic league table approach (Hutubessy et al., 2001). Stochastic league tables provide information about the probability of inclusion in the optimal mix of programs at different budget levels. However, in their original paper Hutubessy et al. (2001) modeled uncertainty of costs and effects at the program level and not individual level. Furthermore, the information contained in stochastic league tables is probabilistic. Simulation optimization, in contrast, provides decision-makers with a clear-cut decision of how to allocate a given budget by determining the number of patients to be treated in each treatment group.

■ Chapter 5

Affordability and cost-effectiveness: decision-making on the cost-effectiveness plane

Summary

Much recent research interest has focused on handling uncertainty in cost-effectiveness analysis and in particular the calculation of confidence intervals for incremental cost-effectiveness ratios (ICERs). Problems of interpretation when ICERs are negative have led to two important and related developments: the use of the net-benefit statistic and the presentation of uncertainty in cost-effectiveness analysis using acceptability curves. However, neither of these developments directly addresses the problem that decision-makers are constrained by a fixed-budget and may not be able to fund new, more expensive interventions, even if they have been shown to represent good value for money. In response to this limitation, the authors introduce the "affordability curve" which reflects the probability that a program is affordable for a wide range of threshold budgets. The authors argue that the joint probability an intervention is affordable and cost-effective is more useful for decision-making since it captures both dimensions of the decision problem faced by those responsible for health service budgets.

Introduction

The inclusion of economic outcomes in clinical trials is now common (Drummond, 1994) and the analysis of such trials has encouraged much research into statistical methods for so-called stochastic cost-effectiveness analysis (Mullahy and Manning, 1995; Coyle, 1996; Siegel et al., 1996). The problem of estimating confidence limits for cost-effectiveness ratios has received much attention and the most important of the recent developments in this area are the use of the net-benefit statistic to avoid the problems associated with ratio statistics (Stinnett and Mullahy, 1998) and the use of cost-effectiveness acceptability curves to summarize uncertainty on the cost-effectiveness plane (van Hout et al., 1994). Both these approaches employ a critical threshold value of the ICER that represents the maximum society is willing to pay for health gain in order to distinguish between what is and what is not cost-effective.

The use of such a critical threshold for the purposes of decision-making in cost-effectiveness analysis is widespread; however, there is no consensus on what exactly the value of this critical ratio might be. Speculative suggestions have been made as to what thresholds might be appropriate (Goldman et al., 1992; Laupacis et al., 1992), but these have received much criticism and it is suggested that commonly used thresholds may owe more to being convenient round numbers than to being a valid statement concerning the value of health (Weinstein, 1995; Garber and Phlebs, 1997)

More generally, the use of such thresholds for decision-making in cost-effectiveness analysis has been criticized on the basis that they will lead to an uncontrolled growth in health care expenditure (Gafni and Birch, 1993). The problem is that in using such thresholds, no explicit consideration is given to the fact that health systems are resource constrained and that decision-makers hold budgets, which must be balanced.

In the next section we introduce an example of the posterior joint distribution of incremental costs and effects from a published Bayesian cost-effectiveness model that evaluated a prophylactic agent against opportunistic infections in HIV-positive individuals (Sendi et al., 1999). Using this example we illustrate the problem of using a threshold decision rule in cost-effectiveness analysis and argue that recent developments for handling uncertainty in cost-effectiveness analysis are of limited value to decision-makers because of their failure to explicitly address the resource constraints of the decision-making process. We then introduce the "affordability curve" and "cost-effectiveness affordability curve" in order to provide this additional information to decision-makers in a way that may help them to interpret the results of stochastic cost-effectiveness analyses. A final section offers some concluding comments.

Conventional approaches to handling and presenting uncertainty

The cost-effectiveness (CE) plane (Anderson et al., 1986; Black, 1990) is now a generally accepted method of presenting the results of cost-effectiveness analyses. In particular the presentation of uncertainty as a region in the cost-effectiveness space is widely employed (van Hout et al., 1994; Hunink et al., 1998). Just such a region is illustrated in Figure 1, representing a parametric fit to a large scale Monte Carlo evaluation of the posterior joint distribution of costs and effects of preventing an opportunistic infection in HIV-infected subjects (Sendi et al., 1999).

Cost-effectiveness acceptability curves are used to summarize the uncertainty on the cost-effectiveness plane. They show the probability that an intervention is cost-effective for a wide range of threshold (or ceiling) ratios (represented in Figure 1 by R_c – the slope of the line passing through the origin that bisects the plane into the cost-effective and cost-ineffective halves). It can be thought of geometrically as the region of the cost-effectiveness plane lying below and to the right of the line with slope R_c as that slope varies from zero towards infinity. We take a Bayesian viewpoint since the natural interpretation of cost-effectiveness acceptability curves, the probability that an intervention is cost-effective given the data, requires a Bayesian perspective (Briggs, 1999). The cost-effectiveness acceptability curve in Figure 2 is derived by plotting the proportion of the joint density located on the acceptable side of the line through the origin with slope R_c as this line rotates from the horizontal through to the vertical.

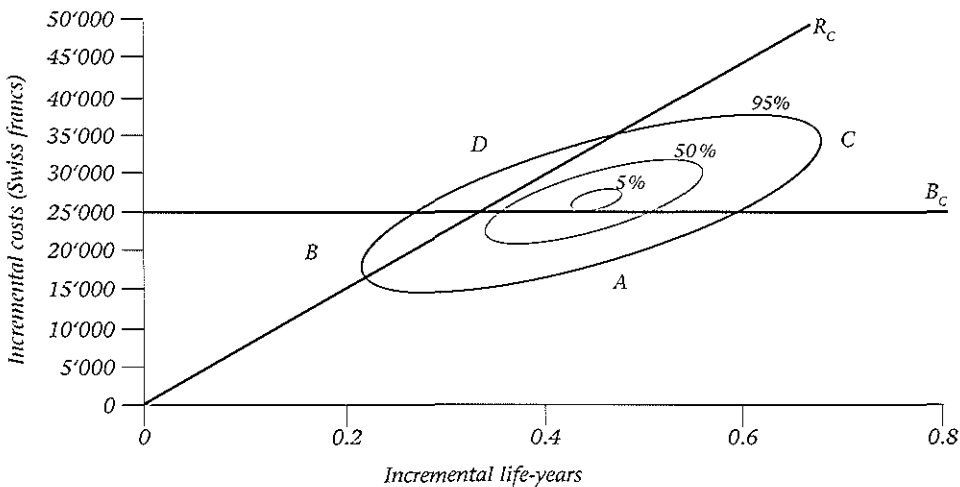


Figure 1. Joint density of incremental costs and effects for a prophylactic agent for reducing opportunistic infections in HIV-infected patients shown on the CE plane. Ellipses covering an estimated 5%, 50% and 95% of the joint density are presented together with lines representing the ceiling ratio R_c and the budget constraint B_c .

The advantage of cost-effectiveness acceptability curves over confidence intervals for ICERs is that they unambiguously quantify the probability an intervention is cost-effective for different R_c and they directly address the study question of whether the intervention under evaluation is cost-effective. However, they still do not sufficiently address the decision-making problem with respect to the resources required to fund the new program under consideration. The fundamental problem is that important information about the size of the program is being lost by using a one-dimensional measure of outcome, the ceiling ratio R_c , to summarize a two-dimensional object, namely the joint distribution of incremental costs and effects. To see the problem, note that an infinite number of programs can be found for every possible ICER. For example, a program A with incremental costs of \$100 producing 1 additional life-year has the same cost-effectiveness ratio as a program B with incremental costs of \$1,000 and incremental effects of 10 life-years. If both programs cannot be funded in smaller increments (i.e., are not divisible), the ICER alone is clearly insufficient for decision-making. Indivisibilities of programs are often encountered in programs with high capital costs such as in the fields of radiation oncology and neurosurgery. Furthermore, even at the level of the individual, the treatment under consideration might reflect indivisible units. For example, immunosuppressed HIV-infected patients have to take their medication for the rest of their lifetime – it does not make sense to fund the treatment for a limited number of days.

Note that it is possible for different joint distributions to lead to identical cost-effectiveness acceptability curves – just as different magnitudes of cost and effect differences can produce the same ratio. These joint distributions would vary in terms of incremental costs and effects, but would have the same correlation between costs and effects and the same coefficients of variation (the ratio of the standard deviation to the mean). The cost-effectiveness acceptability curve, therefore, does not provide any information about the additional resources required in order to implement a new program – however, this is usually critical for decision making within a resource limited health system. In the next section, we suggest an alternative approach to analyzing uncertainty in cost-effectiveness analysis in order to include information concerning possible budget constraints.

The affordability and cost-effectiveness affordability curves

Just as the ceiling ratio R_c separates the cost-effectiveness plane in two areas where the intervention is cost-effective (area A and C in Figure 1) and cost-ineffective (area B and D in Figure 1), the plane can also be divided into affordable and non-affordable areas. A budget constraint can be represented by

a horizontal line on the CE plane (labeled B_c in Figure 1); below this line (areas A and B in Figure 1) is where the intervention is affordable and above this line (area C and D) indicates the intervention is not affordable. Employing an estimate of the number of individuals that are candidates for treatment allows the construction of an affordability curve, i.e. a curve that plots the probability the intervention is affordable, as a function of the budget constraint B_c . This approach produces additional and important information for decision-makers and is a helpful tool for communicating with policy-makers, more helpful than the cost-effectiveness acceptability curve alone. One can think of the affordability curve as the area of the joint distribution of incremental costs and effects below the ceiling budget (area A and B), accounting for the size of the program (number of individuals), as the horizontal line described by B_c moves from the top down to the horizontal axis of the cost-effectiveness plane. Such an affordability curve for 1,000 individuals and the joint distribution of incremental costs and effects (Figure 1) is shown in Figure 3.

In addition, the ceiling ratio R_c and the ceiling budget B_c in combination can be used to distinguish between four areas on the cost-effectiveness plane (Figure 1):

- i) area A where the program is both affordable and cost-effective;
- ii) area B where the program is affordable but cost-ineffective;
- iii) area C where the program is not affordable but cost-effective; and,
- iv) area D where the new program is neither affordable nor cost-effective.

Area A reflects the most desirable outcome while area D the least desirable. In the presence of limited resources, areas A and B (program is affordable) are of most interest. Most policy-makers, we believe, would be interested in area A for different levels of the ceiling ratio R_c and the budget constraint B_c . To account for this, we can construct a set of "cost-effectiveness affordability curves". Such a set of curves would describe the probability that the treatment under consideration is both affordable and cost-effective (area A) as a function of R_c for different values of B_c . Figure 4 demonstrates such a set of "cost-effectiveness affordability curves" for different budget constraints with the acceptability curve of Figure 2 as the limiting case where there is no constraint on the available budget.

The decision rules of cost-effectiveness analysis have been widely explored in the literature. Weinstein (1995) has argued that the theoretically correct method for obtaining the relevant ceiling ratio is from the shadow price of an explicit budget constraint, while Karlsson & Johannesson (1996) have suggested that either the ceiling ratio is obtained from the budget constraint or the budget is determined from a fixed value for the ceiling ratio. In practical application, however, it is often the case that a fixed decision rule is applied

in a constrained budget situation and the strength of the approach described above is that it unambiguously quantifies the location of the joint distribution of incremental costs and effects on the CE plane.

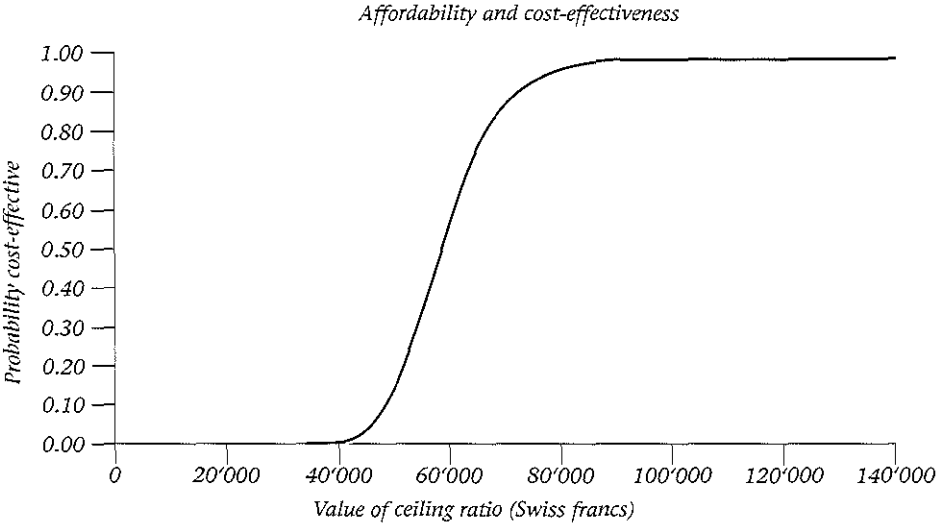


Figure 2. Cost effectiveness acceptability curve showing the probability that the intervention is cost-effective as a function of the ceiling ratio.

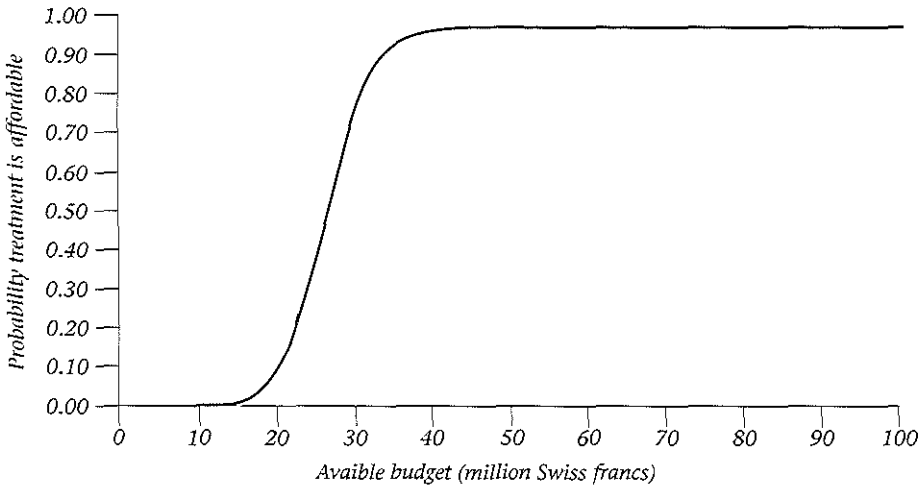


Figure 3. An affordability curve showing the probability that the intervention is affordable (for 1000 patients) as a function of the budget constraint B_c .

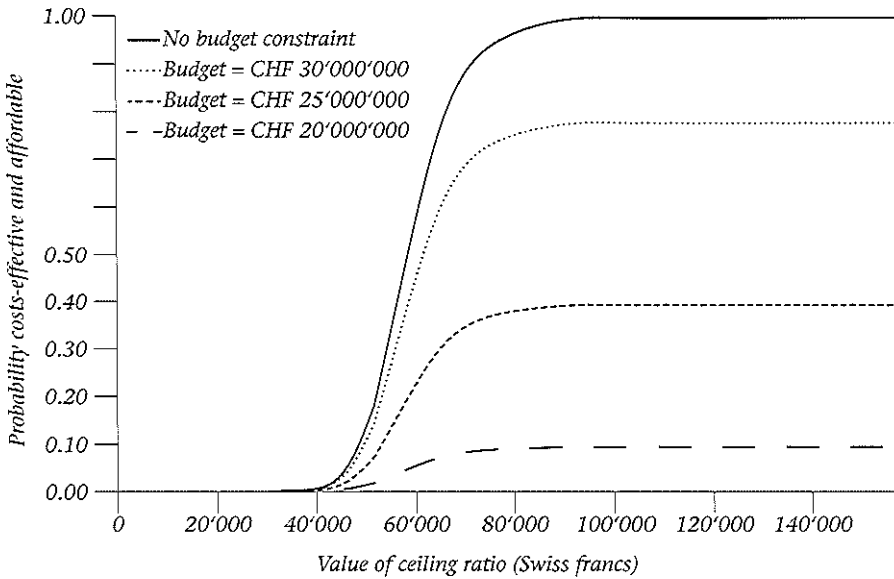


Figure 4. A cost-effectiveness affordability curve showing the probability that an intervention is simultaneously cost-effective and affordable (for 1000 patients) as a function of the ceiling ratio and the budget constraint.

The approach described in this paper is based on several assumptions. First, the approach assumes that there is a stream of additional resources available at a constant marginal opportunity cost. Furthermore, the approach assumes that the cost-effectiveness of the program is independent of its size. Similarly, it is assumed that affordability is not related to cost-effectiveness – if a therapy were highly cost-effective, but not affordable, it is likely that some other intervention would be displaced which would impact on the relevant ceiling ratio for decision-making. Finally, we assumed that the program is indivisible in order to estimate affordability curves. In circumstances where the assumptions of constant returns to scale and constant marginal opportunity costs do not hold, an alternative method for handling uncertainty in cost-effectiveness analysis has been suggested (Sendi et al., 2002).

Conclusion

Recent developments in handling and presenting uncertainty in cost-effectiveness analysis have not addressed the issue of a resource constrained health care system where decision makers hold budgets from which to fund new health care interventions. In order to address this problem, we propose the use of affordability curves to directly quantify the problem of resource constraints. We believe that this sort of information is especially important for analyses from the system and third party payer's perspective (rather than the societal pers-

pective) where the budget for the treatment under consideration is often given and therefore easier to determine. We believe that in times of scarcity of health care resources, information about both cost-effectiveness and affordability is likely to produce more useful information for policy makers.

■ Chapter 6

Portfolio theory and cost-effectiveness analysis: a further discussion

Summary

Background: Portfolio theory has been suggested as a means to improve the risk-return characteristics of investments in health care programs through diversification when costs and effects are uncertain. This approach is based on the assumption that the investment proportions are not subject to uncertainty and that the budget can be invested *in toto* in health care programs.

Methods: In the present paper we develop an algorithm that accounts for the fact that investment proportions in health care programs may be uncertain (due to the uncertainty associated with costs) and limited (due to the size of the programs). The initial budget allocation across programs may therefore be revised at the end of the investment period to cover the extra costs of some programs with the leftover budget of other programs in the portfolio.

Results: Once the total budget is equivalent to or exceeds the expected costs of the programs in the portfolio, the initial budget allocation policy does not impact the risk-return characteristics of the combined portfolio, i.e. there is no benefit from diversification anymore.

Conclusion: The applicability of portfolio methods to improve the risk-return characteristics of investments in health care is limited to situations where the available budget is much smaller than the expected costs of the programs to be funded.

Introduction

The classical decision rule of cost-effectiveness analysis where programs are ranked according to the expected cost-effectiveness ratio and successively implemented, starting with the program with the most favorable cost-effectiveness ratio (i.e., highest expected return), until the budget is exhausted, represents a situation where the decision maker is assumed to be risk-neutral (Al, 2001; O'Brien and Sculpher, 2000). This is consistent with Arrow and Lind's argument that risk should be irrelevant in public investment decisions because of the ability of spreading risk over many consumers (Arrow and Lind, 1970). However, risk-spreading may be limited in countries where health insurance is provided in the private market since the financial burden to some individuals may be substantial (Zivin and Bridges, 2002). Moreover, even in countries where the financial burden is spread across all individuals such as in Switzerland where basic health insurance is compulsory by law, the health outcomes experienced by the individuals are not transferable (Zivin, 2001; Ben Zion and Gafni, 1983). For example, patients with diabetic retinopathy cannot "share" with others their loss of visual acuity. Others have argued that decision-makers may operate at a subsocietal level and have to meet budgetary constraints and outcome performance targets at the same time (O'Brien and Sculpher, 2000). Therefore, the probability of exceeding the budget and/or a shortfall in health outcomes is of great importance to many decision-makers. Hence, the uncertainty associated with return on investment should be accounted for when selecting health care programs.

Much research interest has focused on methods for handling uncertainty in cost-effectiveness analysis (van Hout et al., 1994; Briggs and Gray, 1999; Briggs et al., 2002; Briggs, 2001; Sendi and Briggs, 2001). O'Brien and Sculpher (2000) have recently started the discussion as to how portfolio theory can be used to rank health care programs with different risk-return parameters. The decision-maker's preferences over expected return and risk, and the principle of diversification to reduce uncertainty, may be borrowed from portfolio theory and applied in health care finance (O'Brien and Sculpher, 2000). However, these concepts have so far been presented as a method to deal with uncertainty in costs and effects without explicit consideration of the size of the budget and the resource requirements of the programs in the portfolio.

In health care finance, the investment proportions in the different programs may be limited by the size of the programs. This is very different from the situation in financial economics where the investment decision with regard to the mix of risky assets is performed initially and the budget is usually spent *in toto*. Moreover, in health care finance, the investment proportions are usually uncertain due to the uncertainty associated with the costs of the programs, as opposed to certain in financial economics. Health care programs may happen to need more or less resources than initially budgeted. In such

a situation the decision-maker may want to use the remainder of the budget of some programs to cover the additional expenses of other programs at the end of the year. The applicability of portfolio methods in health care therefore needs to be recast in that light.

This paper demonstrates the limitations of the applicability of portfolio theory in health care finance that may result as a consequence of these distinct characteristics. In the next section we briefly review traditional portfolio theory. We then suggest an algorithm that accounts for the fact that decision-makers may eventually want to reallocate the budget between programs at the end of the year. We then demonstrate our concept using a hypothetical example and conclude by discussion of our approach.

Portfolio theory reviewed

The principle of diversification can best be described using a portfolio of two risky assets (Bodie et al., 2002). These are easy to analyze and demonstrate the principles and considerations that apply to portfolios of many assets. Instead of analyzing the risk and return parameters of bonds and stocks, we consider health care programs as risky assets. Return on investment in financial economics is usually expressed in percentages. To be in line with this convention, we define return on investment in a health care program r as

$$r = \frac{E\lambda - C}{C} \quad (1)$$

where C is the cost of the program, E the health benefit of the program (e.g. expressed as QALYs), and λ the decision-maker's willingness to pay for a QALY. The numerator of the equation above is equivalent to the net monetary benefit (NMB) (Tambour et al., 1998; Stinnett and Mullahy, 1998). Moreover, our measure of return is simply a linear transformation of the effectiveness-cost ratio as defined by O'Brien and Sculpher (O'Brien and Sculpher, 2000):

$$r = \frac{E\lambda}{C} - 1 \quad (2)$$

with the difference that we used absolute costs and effects rather than incremental costs and effects since in the presence of uncertainty constrained optimization does not lead to a straightforward decision rule as under certainty (which is based on calculating incremental costs and effects) (Al, 2001; Sendi and Al, 2003). However, Since E and C are stochastic variables, we do not elaborate on algebraic methods to estimate confidence intervals for our measure of return as the same well-known difficulties associated with ratio statistics would be encountered that led to a bewildering number of methods for estimating a confidence interval for the cost-effectiveness ratio (Briggs and Gray, 1999). In this paper we will rather rely on computer intensive resampling methods to assess the variability in return.

Now, let us consider two health care programs A and B. Program A offers an expected return r_A of 10% with a standard deviation σ_A of 3%, and program B offers an expected return r_B of 15% with a standard deviation σ_B of 5%. Denote the proportion invested in program A by w_A and the remainder, $1-w_A$, invested in program B by w_B . The rate of return of the combined portfolio r_p is

$$r_p = w_A r_A + w_B r_B \quad (3)$$

The expected rate of return of the two-program portfolio is defined as

$$E(r_p) = w_A E(r_A) + w_B E(r_B) \quad (4)$$

and the variance of the portfolio comprising the two health care programs is defined as

$$\sigma_p^2 = w_A^2 \sigma_A^2 + w_B^2 \sigma_B^2 + 2w_A w_B \rho_{AB} \rho_A \rho_B \quad (5)$$

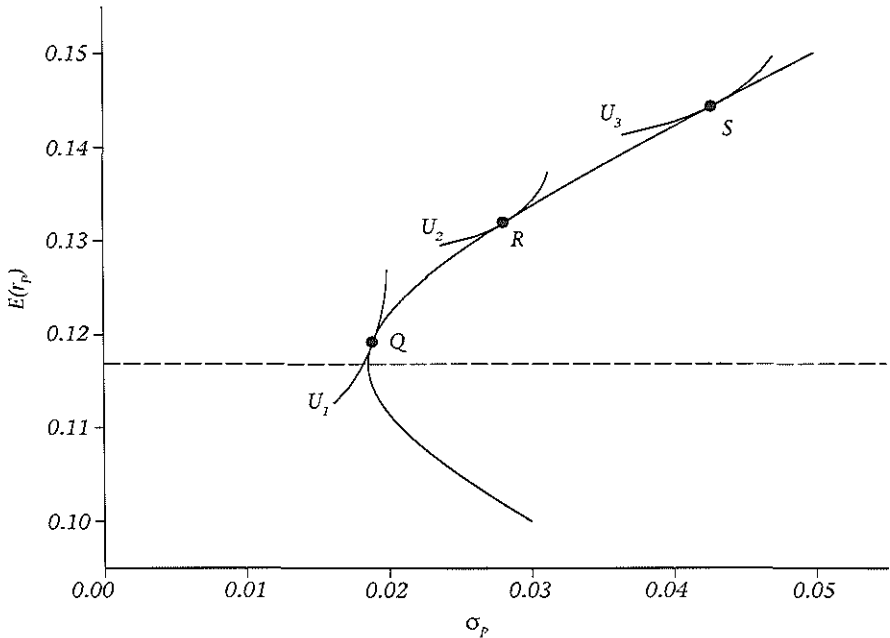


Figure 1. The optimal risky portfolio for three decision-makers with different risk postures. $E(r_p)$ denotes portfolio expected return, σ_p denotes portfolio standard deviation. Utility increases with more return and less risk. R is the optimal risky portfolio for a decision-maker with indifference curve U_2 ; Q is the optimal risky portfolio for a more risk-averse decision-maker with indifference curve U_1 ; S is the optimal risky portfolio for a more risk-seeking decision-maker with indifference curve U_3 .

We can see from Equation (5) that the standard deviation of the combined portfolio, given the standard deviation of the individual programs, increases when the correlation coefficient ρ_{AB} is higher. The smaller ρ_{AB} , the more effective the reduction in total risk will be.

A *portfolio opportunity set* shows all risk-return combinations that can be constructed by varying the investment proportions. Figure 1 shows such an investment opportunity set assuming that the correlation between the return of program A and B as specified above is -0.5. The section of the curve that lies above the minimum variance portfolio (indicated by the intersection of the horizontal broken line with the portfolio opportunity set) is called the *efficient frontier*. An investor typically chooses a portfolio that lies on the efficient frontier since for every combination of w_B and w_A that lies below the minimum variance portfolio there exists a combination of w_B and w_A above the minimum variance portfolio that offers more returns for the same degree of risk. The investor has then to decide on the proportions to invest in program A and B. This is accomplished by superimposing the investor's indifference map (i.e., a set of indifference curves) on the efficient frontier. An indifference curve connects all points on the risk-return plane that offer the same level of utility to a decision-maker. Since we assume that decision-makers prefer more expected return and less risk, indifference curves that lie in the North-West of the indifference map indicate a higher level of utility. The indifference curve that is tangent to the efficient frontier therefore reflects the combination of w_B and w_A with the highest utility. Such a curve is shown for three different investors in Figure 1. The slope of the indifference curve measures the rate at which a decision maker is willing to engage in a riskier investment (indicated on the horizontal axis) in return for an increase in expected return (indicated on the vertical axis), while holding utility constant. The steeper the slope of the indifference curve is, the more expected return is needed to compensate for an increase in an additional unit of risk. The slope of the indifference curve depends on the decision-maker's risk-tolerance. An investor with indifference curve U_2 would choose portfolio R. A more risk-averse investor with a steeper indifference curve U_1 would choose portfolio Q. And a risk-seeking investor with indifference curve U_3 would choose portfolio S. The indifference map of a decision-maker is difficult to construct in practice. However, different methods are available to elicit the decision-maker's risk-posture, which are described in detail elsewhere (e.g. Bodie et al., 2002).

Stochastic costs and budget allocation

We have so far simply adopted the portfolio methods in health care finance. However, there are some important differences to note between budget allocation in health care finance and budget allocation in financial economics. In financial economics, the proportion of the budget used by the different risky assets is not uncertain. Let us say we want to invest 50% of our budget in Microsoft stocks and 50% in Intel stocks. In financial economics, we can completely spend our budget as contemplated. We can do so because our budget is usually much smaller than the value of all available shares of a stock on the market (Bodie et al., 2002). This is different from the situation in health care finance where resource use is uncertain and the investment proportions limited by the size of the programs. Note that the uncertainty of return on investment in financial economics stems from the variability of the market value of risky assets. In health care finance, on the other hand, the uncertainty of return on investment results from the variability associated with both resource use and health outcomes. Because resource use is uncertain, the proportion of the budget used by health care programs is also uncertain. Hence, we do not know beforehand whether our budget will be completely consumed or whether a part of the budget will be left at the end of the year. This has important implications for the applicability of portfolio theory in health care finance and the principle of diversification is not applicable without modification. We therefore need an algorithm to handle this distinct characteristic in health care finance.

When resource use is uncertain, the proportion of the budget initially allocated to a program does not necessarily correspond to the proportion of the budget that is actually consumed by that program. This usually occurs when a program turns out to use fewer resources than budgeted. If there are other programs in the portfolio that turn out to need a larger proportion of the budget at the end of the year, it makes sense to shift the remaining budget of the first program to these latter programs to cover the extra costs. If there is still some leftover after this reallocation, then that unused part of the budget may be seen as an investment in a risk-free asset, e.g. money market instruments. We can formulate this budget allocation policy more formally for a situation in which we have a portfolio of two health care programs. As already mentioned in the previous section, a portfolio of two health care programs is straightforward to analyze and the same concepts and principles also apply to portfolios comprising multiple programs.

We define the rate of return of the combined portfolio r_p as:

$$r_p = \begin{cases} \text{if } C_A > B_A \text{ and } C_B > B_B \rightarrow \frac{B_A}{B_T} r_A + \frac{B_B}{B_T} r_B \\ \text{if } C_A < B_A \text{ and } C_B < B_B \rightarrow \frac{C_A}{B_T} r_A + \frac{C_B}{B_T} r_B \\ \quad + \frac{B_T - C_A - C_B}{B_T} r_C \\ \text{if } C_A < B_A \text{ and } C_B > B_B \rightarrow \frac{C_A}{B_T} r_A + \\ \quad \begin{cases} \text{if } C_B - B_B > B_A - C_A \rightarrow \frac{B_B + B_A - C_A}{B_T} r_B \\ \text{if } C_B - B_B < B_A - C_A \rightarrow \frac{C_B}{B_T} r_B + \frac{B_T - C_A - C_B}{B_T} r_C \end{cases} \\ \text{if } C_A > B_A \text{ and } C_B < B_B \rightarrow \frac{C_B}{B_T} r_B + \\ \quad \begin{cases} \text{if } C_A - B_A > B_B - C_B \rightarrow \frac{B_A + B_B - C_B}{B_T} r_A \\ \text{if } C_A - B_A < B_B - C_B \rightarrow \frac{C_A}{B_T} r_A + \frac{B_T - C_A - C_B}{B_T} r_C \end{cases} \end{cases}$$

We have distinguished four situations that might occur in a two-program portfolio when resource use is uncertain:

1. The costs of both program A (C_A) and B (C_B) exceed the budget initially allocated to these programs (B_A denotes the budget for program A and B_B denotes the budget for program B). In this case we calculate portfolio return as described in Equation (3) where B_A/B_T and B_B/B_T represent the respective investment proportions (B_T denotes the total budget), i.e. B_A/B_T corresponds to w_A and B_B/B_T to w_B in Equation (3).
2. The costs of both program A (C_A) and B (C_B) are lower than the budget initially allocated to these programs. In this case there is some budget left at the end of the year. This leftover budget can be seen as an investment in a risk-free asset, which yields a certain rate of return r_C . Portfolio return is then calculated by multiplying the three investment proportions with the respective rate of return. The investment proportions are C_A/B_T for program A and C_B/B_T for program B. The investment proportion for the risk-free asset is the remainder $(B_T - C_A - C_B)/B_T$.
3. The costs of program A (C_A) are lower than the budget initially allocated to this program, but the costs of program B (C_B) exceed the budget. In this case we reallocate the budget not used by program A to program B at the end of the year. The investment proportions of program A and B are then

C_A/B_T and $(B_B + B_A - C_A)/B_T$ respectively. However, there is the possibility that the budget not used by program A exceeds the resource requirements of program B. In that case the investment proportions are C_A/B_T for program A, C_B/B_T for program B, and $(B_T - C_A - C_B)/B_T$ for the risk-free asset.

4. The costs of program B (C_B) are lower than the budget initially allocated to this program, but the costs of program A (C_A) exceed the budget. In this case we reallocate the budget not used by program B to program A at the end of the year. The investment proportions of program B and A are then C_B/B_T and $(B_A + B_B - C_B)/B_T$ respectively. However, there is the possibility that the budget not used by program B exceeds the resource requirements of program A. In that case the investment proportions are C_A/B_T for program A, C_B/B_T for program B, and $(B_T - C_A - C_B)/B_T$ for the risk-free asset.

Note that the costs of program A and B are uncertain. This renders those investment proportions, which include C_A and C_B in their derivation, also uncertain. Only in those instances where $C_A > B_A$ and $C_B > B_B$ is true with certainty, the investment proportions are certain, because B_A/B_T and B_B/B_T are not subject to a distribution (i.e., B_A , B_B and B_T are not random variables). Therefore, portfolio theory as described previously can only be applied in health care finance when the initial investment proportions are certain, which occurs when $P(C_A > B_A, C_B > B_B)$ is one or close to one.

Note that our approach implies that the budget is allocated across programs at the beginning of the year before future costs and effects are observed. However, we specify in advance at the beginning of the year how we would handle any remaining budget *if* it was not completely used up by the respective program, e.g. to cover *eventual* extra costs that accrued to other programs in the portfolio. Whether the respective programs actually will or will not exceed the budget is of course not known *a priori* and therefore uncertain. Our algorithm therefore represents a dynamic budget allocation policy in the presence of uncertainty about the future state of the world. In the following section we will demonstrate our algorithm using a hypothetical example.

Table 1. Mean costs and standard deviation (μ_C , σ_C) and mean effects and standard deviation (μ_E , σ_E) for two health care programs.

Program	μ_C	σ_C	μ_E	σ_E	ρ^*
A	10'000'000	500'000	115	10	0.6
B	20'000'000	2'000'000	250	10	0.7

*The correlation of costs and effects per treatment alternative is denoted by ρ . Effects of the two programs are also correlated with $\rho = 0.5$

A hypothetical example

Consider the two health care programs shown in Table 1. Mean costs and effects and standard deviation of costs and effects are shown. Let the correlation between costs and effects be 0.6 for program A and 0.7 for program B. Moreover, the effects of the two health care programs are negatively correlated with a coefficient of -0.5 . Note that any correlation between the rate of return of health care programs results from the correlation of costs and effects between and within the programs under consideration. Hence, it is more appropriate to model this latter correlation matrix than the resulting correlation between the rates of returns. In Table 2 we also show the NMB and the return statistics of program A and B.

We can calculate the return on investment and standard deviation for a given budget level and different initial investment proportions using simulation and the algorithm described in the previous section as follows:

- take a sample of costs (C_A and C_B) and effects (E_A and E_B) from the respective distributions and calculate portfolio return (r_p) using the algorithm described above;
- repeat the previous step a large number of times;
- compute the mean and standard deviation of the resulting distribution of portfolio return;
- repeat steps a-c for each budget level and initial budget allocation policy.

Table 2. Expected net monetary benefit $E(NMB)$ and standard deviation and expected return $E(r)$ and standard deviation for two health care programs.

Program	$E(NMB)^1$	σ_{NMB}	$E(r)$	σ_r
A	1'500'166	807'106	14.99%	8.03%
B	4'999'906	1'488'631	25.93%	10.06%

The values in this table were estimated using simulation (10'000 iterations) and truncated normal distributions (costs and effects truncated at zero) from Table 1

¹assuming $\lambda = \$100'000/QALY$

We performed this simulation exercise using a value of \$100'000 per QALY for the ceiling ratio. Moreover, we used a fixed value of 5% for r_f , i.e. the return of the risk-free asset.

The results of our simulation exercise are shown in Figure 2 and Figure 3. The analysis was conducted for the budget levels \$10'000'000, \$20'000'000, and \$30'000'000. As we can see in Figure 2A, at the budget level \$10'000'000, expected portfolio return decreases as a larger proportion of the budget is allocated to program A. Moreover, at the same budget level, portfolio standard deviation decreases with increasing diversification of the budget between program A and B, and increases again as the portfolio becomes less

diversified (Figure 2B). Plotting portfolio expected return against portfolio standard deviation for all investment proportions allows us to construct the portfolio opportunity set as shown in Figure 3.

As we can see in Figure 2A, at the budget level \$20'000'000, expected portfolio return gradually decreases as a larger proportion of the budget is initially allocated to program A. However, when the budget initially allocated to program A exceeds \$10'000'000 (i.e., mean costs of program A), there is no change in the risk-return characteristics of the portfolio (Figure 2A and 2B). Program A consumes on average \$10'000'000 and the remainder will be reallocated to program B. Increasing the initial proportion allocated to program A has no effect because this does not impact the actual resource requirements of program A (Figure 2A and 2B). For example, the policy of initially allocating \$12'000'000 to program A and \$8'000'000 to program B offers the same risk-return characteristics as allocating \$18'000'000 to program A and \$2'000'000 to program B. The possible risk-return combinations of the combined portfolio at the budget level \$20'000'000 are shown in Figure 3.

If we further increase the total budget to \$30'000'000, which corresponds to the total expected costs of program A and B, we see that the risk-return characteristics are identical for all initial budget allocation policies (Figure 2A and 2B). That is, the portfolio opportunity set collapses to a single point on the risk-return plane (Figure 3). Varying the investment proportions has no effect on the risk-return characteristics of the combined portfolio. This is because, no matter how the budget is initially allocated, our algorithm ensures that program A receives on average \$10'000'000 and program B \$20'000'000, which corresponds to their average resource requirements.

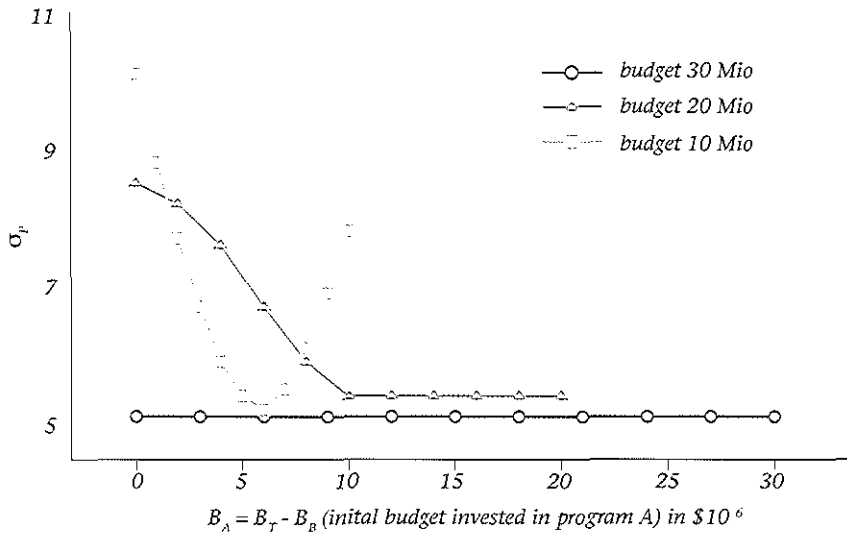
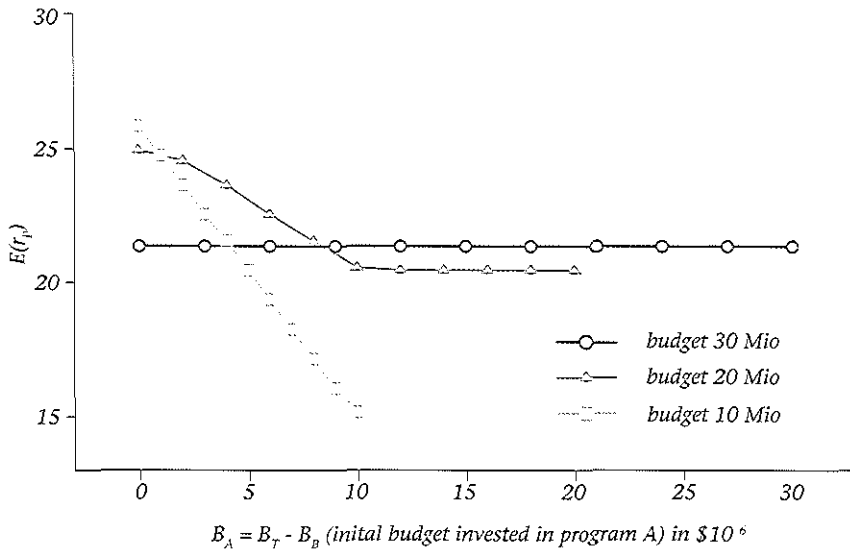


Figure 2A. Portfolio expected return as a function of initial budget allocation.

Figure 2B. Portfolio standard deviation as a function of initial budget allocation.

B_A denotes the budget allocated to program A; B_B denotes the budget allocated to program B; B_T denotes the total budget; $E(r_p)$ denotes portfolio expected return in percentage, σ_p denotes portfolio standard deviation in percentage

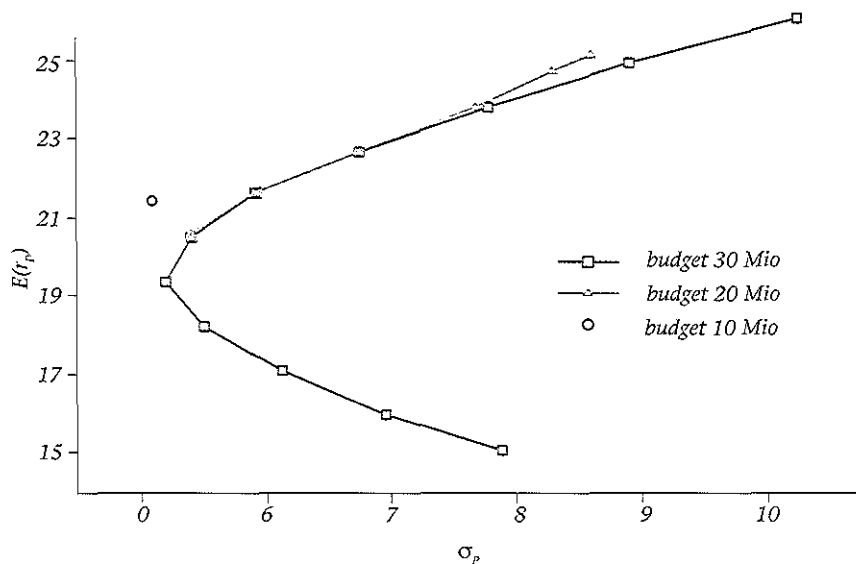


Figure 3. Portfolio opportunity set for three different budget levels.

$E(r_p)$ denotes portfolio expected return in percentage; σ_p denotes portfolio standard deviation in percentage

Discussion

The use of portfolio theory in health care finance has been discussed by a number of authors (O'Brien and Sculpher, 2000; Bridges et al., 2002). However, the applicability of the tools of portfolio analysis in health care, in particular the principle of diversification, may be limited due to the limited size of health care programs and the uncertainty associated with resource requirements. The most important difference between budget allocation in health care finance and budget allocation in financial economics is that the investment proportions in health care finance are usually uncertain and limited, as opposed to certain and usually unlimited in financial economics. Because resource use of health care programs is uncertain, the investment proportions are also uncertain. Programs may therefore happen to need more or less resources than initially budgeted. In such a situation the decision-maker may want to use the remainder of the budget of some programs to cover the additional expenses of other programs at the end of the year. Our algorithm ensures that resources not used by the respective programs are reallocated to those programs in need of more resources.

An important result of this budget allocation policy is that it does not matter how the budget is initially divided up between the programs when the total budget is as large as the expected costs of all the programs in the portfolio. The question of whether the principle of diversification is relevant in health care finance then arises. It may be argued that one usually wishes to budget health care programs so that the whole program can be financed.

However, when the budget corresponds to the expected costs of the portfolio, there is a 50% chance that we will need more resources, which might already be seen as an unacceptable figure in practice. But note that there is already no benefit from diversification anymore at this budget level. The implication for decision-makers is that the initial budget allocation and hence the principle of diversification does not matter in these situations.

The applicability of portfolio theory in health care may prove difficult because of other limitations as well. Information on the correlation of costs and effects between an intervention and up-stream or down-stream interventions are usually not available from randomized controlled trials as these mostly only focus on the intervention of interest. In addition, portfolio theory assumes that programs can be implemented partially (assumes complete divisibility) and that the return on investment is independent of the size of the program (constant returns to scale). Partial implementation would imply that, for example, half of the HIV-infected population would be treated with new medications whereas the other half would get the less effective cheaper therapy. Such a policy is certainly problematic because of ethical reasons (Ubel et al., 1996). Constant return to scales would imply that, for example, buying radiation equipment to treat cancer patients would be equally cost-effective when only 10 cancer patients are treated per year compared to 1000 patients. However, in case of large capital costs, health care programs usually exhibit an increasing return to scale (Birch and Gafni, 1992). The limitations of the assumptions of complete divisibility and constant returns to scale are further described in detail elsewhere (Sendi and Al, 2003; Sendi et al., 2002; Birch and Gafni, 1992, 1993; Gafni and Birch, 1993).

In conclusion, the applicability of portfolio methods to improve the risk-return characteristics of investments in health care is limited to situations where the available budget is much smaller than the expected costs of the programs to be funded. The advantage of diversification disappears once the total budget corresponds to or exceeds the expected costs of the programs in the portfolio. The development of methods that address the limitations of traditional portfolio analysis in health care should be a research priority.

■ Chapter 7

A risk-adjusted approach to comparing the return on investment in health care programs

Summary

The league table approach to rank ordering health care programs according to the incremental cost-effectiveness ratio is a common method to guide policy makers in setting priorities for resource allocation. In the presence of uncertainty, however, ranking programs is complicated by the degree of variability associated with each program. Confidence intervals for cost-effectiveness ratios may be overlapping. Moreover, confidence intervals may include negative ratios and the interpretation of negative cost-effectiveness ratios is ambiguous. We suggest to rank mutually exclusive health care programs according to their rate of return which is defined as the net monetary benefit over the costs of the program. However, how does a program with a higher expected return but higher uncertainty compare to a program with a lower expected return but lower risk? In the present paper we propose a risk-adjusted measure to compare the return on investment in health care programs. Financing a health care program is treated as an investment in a risky asset. The risky asset is combined with a risk-free asset in order to construct a combined portfolio. The weights attributed to the risk-free and risky assets are chosen in such a manner that all programs under consideration exhibit the same degree of uncertainty. We can then compare the performance of the individual programs by constructing a risk-adjusted league table of expected returns.

Introduction

In a league table health care programs are ranked according to their incremental cost-effectiveness ratio in order to guide prioritization in resource allocation (Chapman et al., 2000, Drummond et al., 1993, Mason et al., 1993). In the presence of uncertainty, however, rank ordering programs according to their cost-effectiveness ratio is complicated by the degree of uncertainty associated with each program. Confidence intervals of cost-effectiveness ratios for different programs may be overlapping. Moreover, confidence intervals may include negative ratios and the interpretation of negative cost-effectiveness ratios is ambiguous (Briggs and Fenn, 1998). The question of how health care programs should be ranked when costs and effects are uncertain naturally emerges.

O'Brien and Sculpher (2000) recently outlined the concept of portfolio theory as a method for choosing between health care programs with different risk-return trade-offs. Decision-makers are assumed to be risk-averse and prefer higher returns for a given level of risk. In addition, the decision-maker's utility function is assumed to be strictly concave, i.e. that the indifference curves for (risk, return) pairs exhibit a diminishing marginal rate of substitution between reduced risk and increased expected return. Following this approach, one posits health care programs on the risk-return space and superimposes the decision-maker's indifference map. Health care programs that lie on a higher-valued indifference curve (or iso-utility curve) are ranked higher than those located on a lower-valued indifference curve. This procedure allows one to rank health care programs, in the presence of uncertainty, according to the decision-maker's utility function. However, although the authors' approach is based on sound economic principles, some practical problems arise. First, the decision-maker's indifference map is difficult to measure in practice. Second, the authors used the inverse of the cost-effectiveness ratio as their measure of return. The advantage of using the inverse of the cost-effectiveness ratio is that it provides a more intuitive meaning to analysts who are used to conduct economic evaluations of health care technologies. However, when the concept of capital allocation across a risky asset (e.g. a health care program) and a risk-free asset (e.g. time deposits) shall be used, then it is perhaps more convenient to have a common benchmark which can be used to compare the return on investments across economic disciplines (e.g. in financial economics and health care finance). Finally, the concept of diversification assumes that partial implementation is possible. From an ethical viewpoint, it might be seen as highly problematic to offer to some patients the newer and better treatment while others may receive the "old" therapy. Policy makers may therefore want to implement only one alternative of a set of mutually exclusive programs.

In the present paper we introduce an alternative approach to ranking mutually exclusive health care programs when costs and effects are uncertain using standard portfolio theory as developed by Markowitz more than fifty

years ago. In the next section we suggest an alternative measure of return. In "Capital allocation across a risky and a risk-free asset" we highlight the capital allocation decision between risky and risk-free assets as a basis for modifying the risk-return parameters of a portfolio. In "A risk-adjusted measure of performance" we use this principle to measure portfolio performance and rank mutually exclusive health care programs. Finally, we conclude by a discussion of our approach.

Measuring return on investment

In portfolio performance evaluation we typically measure return on investment r as the terminal value of an asset V_e after a specific time interval subtracted by the amount invested at the beginning of the interval, V_i , and then dividing this difference by the amount invested V_i :

$$r = \frac{V_e - V_i}{V_i} \quad (1)$$

Intermediate cash flows are typically added to the terminal value. For example, if we invest \$100 in an asset and end up with \$110 at the end of the year, then the return on this investment is $(\$110 - \$100)/\$100 = 0.1$ or 10%. Return on investment in financial economics is typically expressed in percentages.

Now, let us consider the financing of a health care program as an investment decision. We denote the amount invested in a program A as C_A (the cost of program A) and the benefits of program A in monetary terms as $E_A \lambda$ where E_A is the health outcome of program A (expressed as quality-adjusted life-years: QALYs) and λ the decision-maker's willingness to pay for a QALY. We define return on investment in program A (r_A) as:

$$r_A = \frac{E_A \lambda - C_A}{C_A} \quad (2)$$

Our measure of return is expressed in percentages and therefore builds a bridge for the comparison of investments in the health care sector with financial investments. Note that the numerator of the expression (2) is equivalent to the net monetary benefit (NMB) of program A:

$$NMB_A = E_A \lambda - C_A \quad (3)$$

The net monetary benefit of a program is similar to the net health benefit approach introduced by Stinnett and Mullahy (1998) with the difference that the net benefit is expressed in monetary terms rather than health outcomes. Note, however, that λ represents here the decision-maker's willingness to pay for a QALY and not an incremental QALY. Since we regard the financing of a health care program as an investment decision, it is perhaps more natural to express

the net benefit of a program on the monetary scale.

In the presence of uncertainty, ranking health care programs according to the rate of return is complicated by the degree of uncertainty associated with each program. How does a program with a higher expected return but higher uncertainty compare to a program with a lower expected return but lower risk? We will use principles of portfolio theory, in particular the concept of capital allocation, in order to describe the risk-return trade-off of a portfolio comprising a health care program (i.e. a risky asset) and a risk-free asset.

Capital allocation across a risky and a risk-free asset

Portfolio managers usually search for the best possible trade-off between risk and expected return. An investor typically selects a combination of risky assets (such as stocks and bonds) and a risk-free asset (such as money market instruments, e.g. time deposits or Treasury bills). The capital allocation decision is the choice of the proportion of the money to invest in risky assets and risk-free assets. The financing of a health care program can be seen as an investment in a risky asset, since costs and effects are uncertain. Denote the risk-free asset as F and the health care program as A. For a given budget, we invest the proportion y in program A and the proportion $1-y$ in the risk-free asset F. Denote the return on program A by r_A , the expected return on program A by $E(r_A)$, and its standard deviation by σ_A . We denote the risk-free rate of return as r_F . The rate of return of the combined portfolio C, denoted r_C , is defined as:

$$r_C = yr_A + (1 - y)r_F \quad (4)$$

The expected value $E(r_C)$ of the complete portfolio's rate of return is

$$E(r_C) = yE(r_A) + (1 - y)r_F = r_F + y[E(r_A) - r_F] \quad (5)$$

and the standard deviation of the complete portfolio, denoted σ_C , is

$$\sigma_C = y\sigma_A \quad (6)$$

That is, the standard deviation of the complete portfolio is proportional to both the standard deviation of the risky asset and the proportion invested in it. Note that the interpretation of (4) is that the rate of return of the complete portfolio is based on the risk-free rate r_F and an expected risk-premium which depends on $E(r_A) - r_F$ and the decision-maker's exposure to the risky asset (i.e., program A), denoted by y .

Let us now look at a numerical example. Consider program A with costs and effects as described in Table 1. We assume that costs and effects are correlated with $\rho = 0.7$. The expected return on A is $E(r_A) = 9.94\%$ and the standard

deviation is $\sigma_A = 9.27\%$ (Table 2). Let us assume a risk-free rate of return of 5%. The risk premium on the risky asset is therefore $E(r_A) - r_f = 4.94\%$. We assume that decision-makers (at the societal and subsocietal level) are risk-averse and only accept a positive risk-premium (O'Brien and Sculpher, 2000; Zivin, 2001).

Table 1. Mean costs and standard deviation (μ_C, σ_C) and mean effects and standard deviation (μ_E, σ_E) for three health care programs.

Program	μ_C	σ_C	μ_E	σ_E	ρ^*
A	10'000'000	100'000	110	10	0.7
B	20'000'000	1'000'000	250	50	0.7
C	30'000'000	2'000'000	380	150	0.7

*The correlation of costs and effects per treatment alternative is denoted by ρ .

Table 2. Expected net monetary benefit $E(NMB)$ and standard deviation and expected return $E(r)$ and standard deviation for three health care programs.

Program	$E(NMB)^a$	σ_{NMB}	$E(r)$	σ_r	S^b	$E(r) \text{ adjusted}^c$
A	1'000'031	932'860	9.94%	9.27%	0.53	9.94%
B	5'000'138	4'360'709	24.44%	21.23%	0.92	13.49%
C	8'243'509	13'363'411	25.74%	43.72%	0.47	9.40%

The values in this table were estimated using simulation (100'000 iterations) and truncated normal distributions (costs and effects truncated at zero) from Table 1

^aassuming $\lambda = \$100'000$

^bReward-to-variability ratio, assuming a risk-free rate of 5%

^cExpected return adjusted for risk (program A used as benchmark)

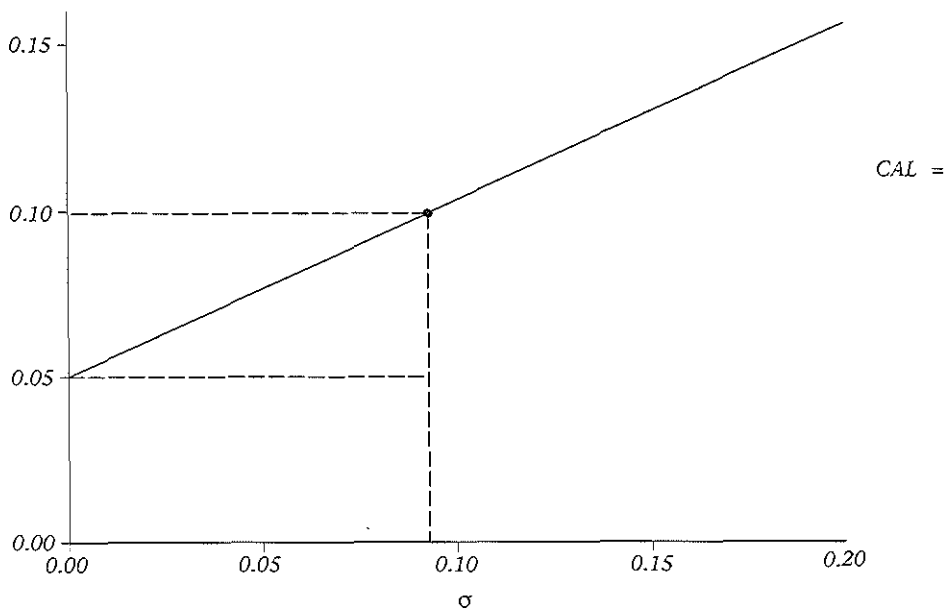


Figure 1. The capital allocation line

Our complete portfolio will have an expected return of $E(r_c) = 5 + \gamma(9.94-5)$ and a standard deviation of 9.27γ . Next, we plot the characteristics of the complete portfolio on the risk-return plane (Figure 1). The risk-free asset appears on the vertical axis of $E(r)$ at 0.05 (5%) because there is no uncertainty associated with it (i.e., the standard deviation is zero). The risky asset (program A) is plotted with an expected return of 9.94% (0.0994) and a standard deviation of 9.27% (0.0927). If a decision-maker invests all his money in health care program A, then $\gamma = 1$ and the complete portfolio is program A. If an investor puts all his money in the risk-free asset, then $\gamma = 0$ and the complete portfolio is F. In situations where the investor chooses $0 < \gamma < 1$, the complete portfolio is described by points on the line between the risk-free asset F and the risky asset A (Figure 1). The slope of this line is defined as

$$S = \frac{E(r_A) - r_F}{\sigma_A} \quad (7)$$

and is called the "Sharpe Ratio" or reward-to-variability ratio. It shows the expected excess return (risk premium) per unit risk (volatility). That is, increasing the proportion invested in health care program A increases the expected return at the rate 4.95% (which is the risk premium) and it also increases the standard deviation at the rate 9.27%. Therefore, the extra return per extra risk is $4.95/9.27 = 0.53$. If we rearrange equation (6) so that $\gamma = \sigma_c/\sigma_A$ and replace γ by σ_c/σ_A in equation (5), we get the equation for the line with intercept F and slope S:

$$E(r_c) = r_F + \frac{E(r_A) - r_F}{\sigma_A} \sigma_c \quad (8)$$

We call this the capital allocation line. It shows all risk-return combinations, i.e. the investment opportunity set, from which the investor can choose. Until now we have assumed that $0 \leq \gamma \leq 1$, i.e. that the investor either lends a fraction of his money ($0 \leq \gamma < 1$) or invests his whole capital in program A ($\gamma = 1$). However, the investor can also borrow money and invest it in program A. This situation is described by the points on the line beyond program A, assuming that the investor can borrow at a risk-free rate of 5%. For example, if the investor has \$100'000 and borrows another \$100'000 in order to invest \$200'000 in program A, then $\gamma = \$200'000/\$100'000 = 2$. This is called a short position in the risk-free asset and $1-\gamma = -1$. Note that the complete portfolio with $\gamma = 2$ still has the same reward-to-variability ratio (i.e., the slope of the line does not change). The technique of modifying the standard deviation of the complete portfolio by borrowing or lending money will be used in the next section to compare the performance of different risky assets.

A risk-adjusted measure of performance

The comparison of the rate of return of different health care programs is complicated by the degree of uncertainty associated with it. For example, consider the three health care programs described in Table 1. Their expected NMB and expected rate of return is shown in Table 2. If we were to rank the programs according to the $E(NMB)$, we would prefer program C over program B, and program B over program A (which offers the lowest expected NMB). The same holds true if, for example, we were to rank these three programs according

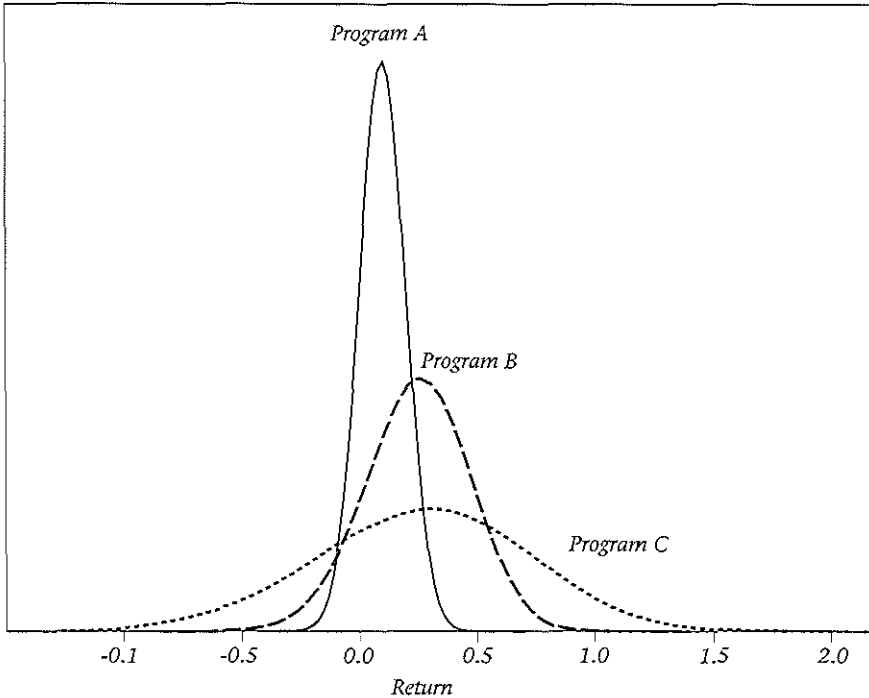


Figure 2. Distributions of the rate of return of three health care programs

to their expected rate of return. But note that ranking programs according to their expected rate of return assumes that we are risk-neutral. Investors are usually risk-averse, i.e. they require a positive risk premium. This is consistent with Arrow and Lind's argument that costs can be spread over many consumers whereas health effects are distributed among few individuals since they are not transferable (Arrow and Lind, 1970). For a societal decision-maker, therefore, risk aversion towards health effects is reasonable. The distributions of the rate of return of the three health care programs are shown in Figure 2 and the respective standard deviations are shown in Table 2.

Taking the analysis a step further, investors are assumed to prefer higher returns, *ceteris paribus*. That is, an investor prefers to invest in an asset with a steeper capital allocation line, i.e. more expected returns for the same degree of risk. We can therefore compare the reward-to-variability ratios (or Sharpe

Ratios) of the different health care programs, which are shown in Table 2. Note that the ranking of the three programs now changes, we prefer program B over program A, and program A over program C. This situation is also depicted in Figure 3 where the investment opportunity set for each health care program in combination with a risk-free asset is shown. The slope of the capital allocation line is for program B > A > C.

An alternative risk-adjusted approach to compare return on investment is to determine what the expected returns of the three programs should have

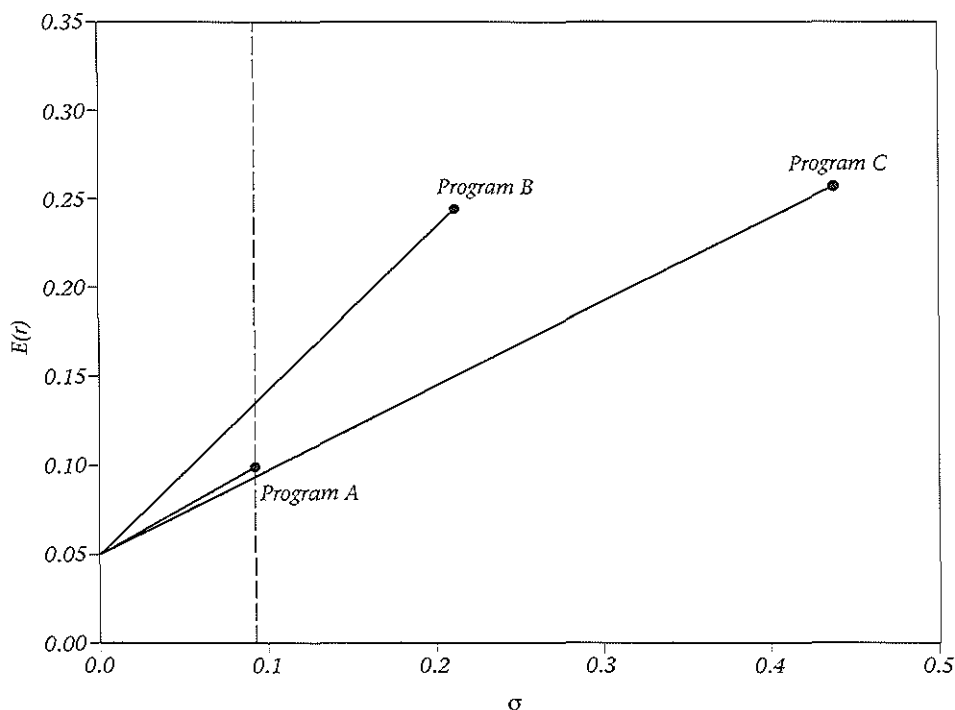


Figure 3. Capital allocation lines of three complete portfolios.

been if all portfolios had had the same degree of uncertainty. We can change a portfolio's standard deviation by lending or borrowing money at a risk-free rate of 5%, i.e. by shifting wealth between the risky and risk-free asset. Let us take program A ($\gamma = 1$) as the benchmark to which we would like to compare the other two programs. The expected return and standard deviation of program A are shown in Table 2. The capital allocation line of the complete portfolio comprising program B and a risk-free asset is described by the following equation:

$$E(r_C^B) = r_F + \frac{E(r_B) - r_F}{\sigma_B} \sigma_C^B \quad (9)$$

This equation indicates the average return, $E(r_C^B)$, that would have been earned by either borrowing or lending at a risk-free rate to such a degree that the

resulting standard deviation was σ_C^B . Hence, setting σ_C^B equal to σ_A in equation (9) measures the return an investor would have earned if the portfolio had been altered using the risk-free rate through borrowing or lending in order to match program A's standard deviation. This approach leads to a risk-adjusted return of 13.49% (Table 2). The same procedure can be used to assess the risk-adjusted return on a portfolio comprising program C and a risk-free asset:

$$E(r_C^C) = r_f + \frac{E(r_C) - r_f}{\sigma_C} \sigma_C^C \quad (10)$$

Setting σ_C^C equal to σ_A in equation (9) measures the return an investor would have earned if the portfolio had been altered using the risk-free rate through borrowing or lending in order to match program A's standard deviation. The risk-adjusted return is then 9.40% (Table 2). Note that these values are indicated by the intersection of the vertical broken line with the three solid lines describing the investment opportunity sets of the three portfolios in Figure 3. The choice of the program serving as a benchmark does not change the ranking of programs. We could have also used program B as the benchmark. In that case we would have borrowed or lent money to such a degree that the standard deviation of a portfolio comprising program A and the risk-free asset would have matched program B's standard deviation. And we would have borrowed or lent money to such a degree that the standard deviation of a portfolio comprising program C and the risk-free asset would have matched program B's standard deviation. In portfolio performance evaluation the difference in expected return between the benchmark and a risk-adjusted portfolio is known as the M-squared (M^2). The M^2 -measure has been introduced by the Nobel Prize winner Francis Modigliani and his granddaughter Leah (Bodie et al., 2002). Both approaches, the Sharpe Ratio (reward-to-variability ratio) and the M^2 -measure lead to the same rank-ordering of programs.

Discussion

In this paper we have introduced the idea of applying measures commonly used for portfolio performance evaluation to the ranking of mutually exclusive health care programs. It should be remembered that the rule of calculating incremental cost-effectiveness ratios for mutually exclusive programs follows from a linear programming problem under certainty (Birch and Gafni, 1992). Under uncertainty, however, the optimization problem usually does not lead to such a straightforward decision rule (Al, 2001; Sendi and Al, 2003). Rather, the decision-maker's preferences over uncertain costs and health effects are needed for decision-making (Al, 2001). In addition, health care programs are usually indivisible because of ethical reasons, i.e. it would be problematic to offer to some patients the better treatment while other would still receive the old or even no treatment (Sendi et al., 2004; Sendi and Al, 2003; Sendi

et al., 2002). In the presence of indivisibility of programs, the calculation of incremental costs and effects becomes obsolete (Birch and Gafni, 1992,1993). Finally, the premise in our approach was that the investor chooses that single program among a set of mutually exclusive programs that offers the highest reward-to-variability ratio. We therefore used absolute costs and effects rather than incremental costs and effects in our calculations.

Our measure of return can be seen as a pragmatic approach in response to these limitations. An advantage of using NMB/C as a measure of return is that the resulting unit corresponds to what is commonly used in portfolio theory. This allows us to build a bridge between financial investments and health care finance and consider investment decisions from a much broader perspective. One might object that the exact value of λ , and hence NMB, is not known. However, as is the case for the NMB and cost-effectiveness acceptability curves (van Hout et al., 1994; Stinnett and Mullahy, 1998), the reward-to-variability ratio may be calculated for a wide range of λ . A further objection to using NMB/C might be that, as is the case for the inverse of the cost-effectiveness ratio, this measure of return might become potentially unstable if the denominator C approaches zero. However, note that this is only a relevant issue when incremental cost estimates (denominator if the inverse of the cost-effectiveness ratio is used) or incremental effect estimates (denominator if the cost-effectiveness ratio is used) are used. In our study, however, we considered total program costs and effects, which are usually substantial.

Having defined an appropriate measure of return, the next step is to deal with the uncertainty associated with it. In portfolio theory capital allocation entails the fraction of the money invested in a risky asset (y) and risk-free asset ($1-y$). Knowing the parameters of the risky asset (mean and standard deviation of return) and the risk-free asset (return), we can construct the investment opportunity set of a portfolio, i.e. all possible combinations resulting from different values for y . This is a straight line on the risk-return plane defined by the risk-free rate of return (intercept) and the expected return-risk parameters of the risky asset. The slope of this line, the reward-to-variability ratio, reflects the extra return per extra risk. The steeper the line, the more expected return we get per unit increase in risk. We can compare the performance of the different health care programs by comparing their reward-to-variability ratios. Alternatively, we can lend or borrow money (i.e., vary y) to such a degree that the standard deviation of return is the same for all programs. We then simply rank the programs according to their risk-adjusted expected return. Both approaches lead to the same rank ordering of programs.

Similar to O'Brien and Sculpher (2000) and Bridges et al. (2002) we use principles of portfolio theory. Bridges et al. (2002) recently suggested an extended formulation of portfolio that considers population effects as aggregated effects from individuals where synergies between treatments are

possible. In our study, however, we applied the concepts of capital allocation and portfolio performance evaluation. We also assumed that investors prefer higher returns and less risk. However, the investor's precise utility function is not needed in order to rank mutually exclusive health care programs. The investor's utility function would only be needed if we were to determine the point on the capital allocation line (i.e., the value of y) with the highest utility. But note that the reward-to variability ratio (and hence the ranking of programs) does not depend on y .

In the present paper we assumed that the complete portfolio includes a risk-free asset and a risky asset, i.e. that the risky asset reflects a single program. This is in line with the ethical argument that only one of mutually exclusive interventions should be implemented because of equity considerations. The parameters of the risky asset, however, could actually themselves be based on a mix of health care programs. In the presence of a comprehensive menu of health care programs, the mix of programs which offer the highest expected return for any given level of risk form the so-called efficient frontier (O'Brien and Sculpher, 2000). The point of tangency of the capital allocation line with the efficient frontier is called the optimal risky portfolio since no other mix of programs offers a higher reward-to-variability ratio. The performance of an individual program could, for example, be compared with the performance of the optimal risky portfolio, a well-diversified portfolio of risks serving as a benchmark. In order to determine the portfolio with the highest utility, in contrast, one would need to determine the point on the efficient frontier which is tangent to the highest valued indifference curve. But this requires that the decision-maker's preferences over expected return and risk are known. However, the elicitation of these preferences might not be an easy task. Furthermore, it assumes complete divisibility, i.e. that not all patients with the same medical indication get the same treatment. Decision-makers may therefore appreciate the information of how the *individual* programs performed relative to each other or some benchmark portfolio. Finally, it should be noted that we did not address the issue of how portfolio theory can be used to rank health care programs that are not mutually exclusive. This will be subject to future research.

It should be noted that there is one important difference between the situation in financial economics and health care finance. In financial economics, we are usually not limited in the number of e.g. stocks we would like to buy since an investor's budget is usually smaller than the total value of all available shares of a specific stock. In other words, if an investor wants to invest \$10'000'000 in a risky asset and \$10'000'000 in a risk-free asset, he can do so and $y = 0.5$. In health care finance, arguably, a program size beyond 100% is not possible. Consider the same investor who wants to invest \$10'000'000

in health care program A and \$10'000'000 in a risk-free asset. Since the cost of program A is normally distributed (with mean \$10'000'000 and standard deviation \$100'000), there is a 50% chance that the cost of program A will be lower than \$10'000'000. That is, we may not end up investing the total amount of \$10'000'000 in program A. In other words, the fraction invested in program A (the risky asset) is itself subject to a distribution, which depends on the cost of program A. If the cost of program A, C_A , happens to be more than \$10'000'000, then $\gamma = 0.5$. If C_A happens to be less than \$10'000'000, then $\gamma = C_A / \$20'000'000$. On the other hand, if we had \$1'000'000 and wanted to completely finance program A, we could borrow at a risk-free rate and $\gamma = C_A / \$1'000'000$. Since C_A is uncertain, γ is also subject to a distribution. In that case we will most likely end up with a short position in the risk-free asset. However, the fact that γ is subject to a distribution in health care finance does not affect the relevance of the analysis for ranking health care programs. Note that although the value of γ may be uncertain, the reward-to-variability ratio is not, since the slope S of the capital allocation line as defined in (7) does not include γ .

An interesting approach for including risk in league tables has recently been suggested by Hutubessy et al. (2001). The probability of inclusion in the optimal mix of programs for different budget levels is then displayed in a so-called expansion path. However, the authors' approach is different in the sense that they provide the probability of an intervention being chosen in the optimal mix of programs in the presence of uncertainty. Our approach, in contrast, borrows methods from financial economics and takes a standard approach for risk-adjusting the returns from an investment.

In conclusion, we believe that methods developed in financial economics offer a valuable source of knowledge for dealing with uncertainty in health care finance. Measuring return on investment is a natural approach to rank ordering health care programs. In the presence of uncertainty, risk-adjusted expected returns may be helpful to guide policy and decision makers in setting priorities for resource allocation.

■ Chapter 8

Cost-effectiveness of highly active antiretroviral therapy in HIV-infected patients

Summary

Background: Highly active antiretroviral therapy (HAART) has become the most important strategy for treating HIV-infection in developed countries. However, access to HAART might vary under different funding policies. The Swiss health care system provides unrestricted access to HAART for all patients who need these newer combination therapies. This study investigated the impact of this funding policy on the society and health care system.

Methods: A cost-effectiveness analysis with natural history data and productivity estimates was based on the Swiss HIV Cohort Study. A random sample of patient charts was used to estimate health care costs. In addition to a base-case scenario, a pessimistic and an optimistic scenario of natural disease history was developed. Costs were expressed in 1997 Swiss Francs (100 CHF correspond to about 43 £) and effects as projected years of life gained.

Results: In the analysis limited to health care costs, on the basis of projected survival in each scenario, the cost effectiveness ratio was CHF 33,000 (base-case), CHF 14,000 (optimistic), and CHF 45,000 (pessimistic) per year of life gained. When changes in productivity were included, cost savings occurred in the base-case and optimistic scenarios. The cost effectiveness ratio was CHF 11,000 per year of life gained in the pessimistic scenario.

Conclusions: HAART increases expected survival and health care costs. However, when productivity gains are included, society will probably save costs or pay a low price for substantial health benefits. The study provides strong arguments, from a societal perspective, to continue the current policy of providing unrestricted access to HAART in Switzerland. The presented results also suggest that this policy could be of interest for other developed countries. Decision makers in developed countries where access to HAART is limited should re-evaluate their policy for the benefit of the society at large.

Introduction

Highly active antiretroviral therapy (HAART) reduces morbidity and mortality in individuals infected with HIV (Palella et al., 1998; Egger et al., 1997). In developed countries, antiretroviral three-drug regimens including a protease inhibitor have become the recommended standard for treating HIV-positive patients (CDC, 1998). Although substantial health care resources are used to fund the widespread use of these newer combination therapies (Perdue et al., 1998), the acquisition costs for HAART may be offset by a decline of expensive in-patient care, increased quality of life, and increased job productivity as a consequence of a decline in morbidity and mortality (Johannesson and Meltzer, 1998). The Swiss health care system, because of equity considerations, provides unrestricted access to all necessary medications and medical procedures in HIV-positive patients. This funding policy allows the consequences of providing HAART to all patients in need of this potent antiretroviral regimen to be estimated within a setting without eligibility restrictions for basic health care. This study illustrates the consequences of a health care policy that might be of interest for other developed countries.

The cost effectiveness analysis was conducted from both the Swiss societal and health care perspectives. The societal perspective is the most relevant since it captures the important effects of HAART on costs outside the health care system (Drummond et al., 1997). If HAART is found to be desirable from a societal perspective, the health care perspective informs about the eventual resources required to fund this program (Birch and Gafni, 1992). In times of scarcity of health care resources, this information is valuable, since policy makers could then identify and cancel less-efficient programs to guarantee the widespread use of HAART without exceeding a given budget.

Methods

This cost effectiveness analysis was performed on the basis of data extracted from the Swiss HIV Cohort Study (SHCS) (Ledergerber et al., 1994). The SHCS is one of the world largest cohort studies on HIV disease with over 9000 enrolled patients since 1988. Patients have regular follow-up visits every six months. The mean age of patients enrolled in the SHCS is 33 years. This was the starting age of an HIV-infected individual used in our analysis.

In Switzerland, HAART was introduced in 1996 (Egger et al., 1997). In the presented analysis a cohort of HIV-infected patients receiving HAART was used that reflected the SHCS during the period 1996-1997. This cohort was stratified by CD4-cell count and history of an AIDS-defining disease, as defined by the European classification of AIDS (Ancelle-Park et al., 1995). The strategy of providing HAART was compared with the strategy of providing no antiretroviral therapy (NART). Therapy regimens other than HAART are no longer recommended (CDC, 1998) and the NART as a comparison strategy demonstrates the

full consequences of not spending any money on antiretroviral drugs.

Effects were defined as the number of life-years gained (Wright and Weinstein, 1998). The definition of costs depends on the viewpoint of the analysis (Drummond et al., 1997). For the health care perspective, only costs to the Swiss health care system were included. The broader societal perspective also incorporated estimates of productivity in HIV-infected individuals (health care costs minus productivity gains) (Johannesson and Meltzer, 1998). Stemming from the societal perspective of the study, lifetime morbidity and mortality cost estimates were captured within a modeling framework. The horizon of the analysis exceeds the data available on follow-up from clinical trials of HAART and is consistent with the current practice in such cases (Drummond et al., 1997).

In the analysis from the health care perspective, an annual discount rate of 4% (range 2.5% - 8%) was used to agree with the discounting practice of major Swiss insurance companies (SUVA, personal communication, 1998) (Krahn and Gafni, 1993). In the analysis from the societal perspective, we used an annual discount rate of 3.5 % (range 2% - 3.5%) to reflect the interest rate in Swiss government bonds (Krahn and Gafni, 1993). Costs were calculated on the basis of 1997 Swiss Francs (100 CHF corresponds to about 43 £).

Estimates of effects

Specialized software (DATA 3.0.17, TreeAge, MA, USA) was used to develop a Markov model describing the natural history of an HIV-infected individual over a sequence of six-month intervals (Sonnenberg and Beck, 1993). Three broad categories of health states were defined: No AIDS, AIDS and death. The No AIDS and AIDS states were stratified into three CD4 count categories as shown in Figure 1. A patient currently in a No AIDS state is at risk of dying from non-AIDS related causes or developing an AIDS-defining disease.

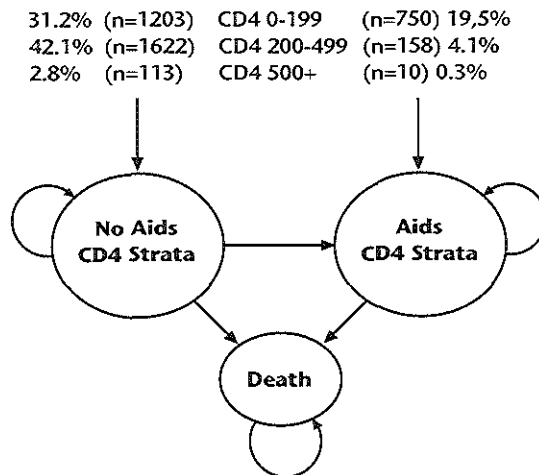


Figure 1. State transition diagram representation of the Markov model. The initial size and distribution of the simulated cohort corresponding to the Swiss HIV Cohort Study (1996-1997).

A patient with AIDS is at risk of dying from AIDS or non-AIDS related causes.

Maximum likelihood estimates on the basis of the SHCS data were computed for (i) the risk of developing AIDS, (ii) the risk of dying from AIDS, (iii) the risk of dying from non-AIDS related causes, and (iv) the risk of switching from one of three CD4 cell count strata to another. All events with the exception of death from non-AIDS related causes were conditioned upon the patient's current CD4 cell count. Patients enrolled in the SHCS with at least one follow-up after January 1, 1991 (database of January 1998 was used) were included. Observations over six months from patients taking potent antiretroviral combination therapy, including a proteinase inhibitor, were pooled to calculate the maximum likelihood estimates for the HAART strategy (1476 observations). Saquinavir was excluded because of the low bioavailability of the hard capsules (Mitsuyasu et al., 1998). Saquinavir soft capsules were not yet available in Switzerland. The percentage of the remaining proteinase inhibitors prescribed were then 64.9% for indinavir, 29.4% for zidovudine, 5.7% for nelfinavir. Six-month observations from patients without any antiretroviral therapy were used to compute the maximum likelihood estimates for the NART strategy (10,798 observations).

Because HAART was introduced in 1996 (Egger et al., 1997) and evidence about its durability is not available, and also because we are uncertain about the precision of our estimates, a pessimistic and optimistic scenarios were constructed in addition to the base-case scenario. Since the maximum likelihood estimates constructed are success/failure in nature, a binomial distribution with mean equal to the maximum likelihood estimates was used to generate the optimistic and pessimistic parameters. For the optimistic scenario, the 97.5 percentile of each distribution describing a transition into a "better" health state was selected, and the 2.5 percentile of each distribution describing a transition into a "worse", the same, or the death state. For the pessimistic scenario, the 2.5 percentiles of each distribution describing a transition into a "better" health state were selected, and the 97.5 percentile of each distribution describing a transition into a "worse", the same, or the death state. All probabilities used are available on request from the authors.

A mixed initial distribution of health states was defined (Figure 1) as the starting point of our model, reflecting the SHCS during the period 1996-1997. A large cohort of 30'000 individuals were followed one at a time (Monte Carlo simulation) until death in both strategies, HAART and NART. For each patient, a new discount rate was sampled from a triangular distribution with the likeliest value and ranges depending on the perspective of the analysis. We assumed that these 30'000 simulated observations would approximate the distribution of lifetimes. The mean of these simulated observations are listed in Table 1.

Table 1. Projected survival in patients with highly active antiretroviral therapy (HAART) and no antiretroviral therapy (NART) in different scenarios of natural disease history.

Discount Rate % (Range)	Average survival					
	base-case		optimistic		pessimistic	
	HAART	NART	HAART	NART	HAART	NART
0%	14.85	6.64	26.69	7.83	10.23	4.96
3.5% (2%-3.5%) ^a	13.02	6.21	21.06	7.33	9.30	4.69
4% (2.5%-8%) ^b	12.12	5.99	18.68	7.02	8.84	4.56

^a societal perspective

^b health care perspective

To account for the initial size of the real-world cohort (Huinink et al., 1998), a sample of 3856 individuals (with replacement) from the respective distributions based on 30'000 observations was used to compute the mean increase in life-expectancy (Wright and Weinstein, 1998). This procedure was repeated 5000 times. For each scenario, the mean and 95% prediction interval for the gain in life-expectancy with HAART compared to NART was then calculated. The uncertainty in the final estimate results from the uncertainty of each individual's path, the finite size of the cohort, and the varying discount rate (triangular distribution).

Estimates of costs

Health care costs were estimated from a random sample of charts from SHCS enrollees followed up at the University of Basel HIV clinic. Patients with symptomatic AIDS were included and stratified by CD4 cell count (0-199 x 10⁶ cells/l and 200-499 x 10⁶ cells/l). Patients with a history of an AIDS-defining disease and a CD4 cell count \geq 500 x 10⁶ cells/l were assumed to consume no more health care resources than patients without AIDS. Only individuals who were taking HAART were included in the sample. Quantities of resource consumption were abstracted on a per patient basis and to a detailed extent (micro-costing) (Drummon et al., 1997) including antiretroviral and prophylactic drugs, all medical interventions for diagnostics and therapy, in-patient and out-patient care, consulting of specialists, nursing time and doctor's time. Costs were expressed in 1997 Swiss Francs (100 CHF correspond to about 43 £) per six-month of follow-up using the Swiss consumer price index for health care. These estimates were then averaged to derive a baseline value for each CD4 stratum. Health care costs in patients with AIDS who did not take HAART were extracted from a previous study (Meier, 1999). We used the same procedure to derive 6-month estimates.

It was assumed that patients without AIDS had regular check-up visits and laboratory examinations and that those with a CD4 cell count below 200 x 10⁶

cells/l received *Pneumocystis carinii* prophylaxis. The drug costs for individuals receiving HAART were based on the actual consumption of potent antiretroviral combination therapies observed in the SHCS and the average wholesale prices in Switzerland (Arzneimittelkompendium der Schweiz, 1997).

The 6-month estimates for resource consumption were assigned to the respective health states as displayed in Table 2. It was assumed that the average health care costs in patients with AIDS (CD4: < 500 x 10⁶ cells/l) taking HAART, because of less frequent in-patient care, would only be lower compared to NART in the added years of life. Therefore, future average health care cost estimates in the health states of AIDS (CD4: 0-199 x 10⁶ cells/l) and AIDS (CD4: 200-499 x 10⁶ cells/l) were substantially higher after 8.5 years in the base case scenario, after 19 years in the optimistic scenario, and after 5.5 years in the pessimistic scenario of natural disease history (see Table 2, footnotes b and c). This assumption is conservative and represents our opinion that health care costs in patients on HAART would increase in later years. The same cohort of

Table 2. Monthly health care cost and productivity estimates in patients with highly active antiretroviral therapy (HAART) and no antiretroviral therapy (NART).

Health state	Average worked hours (SD)		Health care costs in 1997 CHF ^a (Range)	
	HAART	NART	HAART	NART
No AIDS, 0-199 CD4 cells/mm ³	95 (83)	80 (83)	1206 (996-1408)	318 (169-470)
No AIDS, 200-400 CD4 cells/mm ³	113 (80)	94 (83)	1176 (972-1372)	288 (145-434)
No AIDS, >500 CD4 cells/mm ³	127 (79)	110 (82)	1176 (972-1372)	288 (145-434)
AIDS, 0-199 CD4 cells/mm ³	63 (77)	50 (72)	2991 (1500-6960) ^b	6213 (870-33,930)
AIDS, 200-400 CD4 cells/mm ³	95 (85)	59 (79)	1819 (1620-1980) ^c	3779 (529-20,640)
AIDS, >500 CD4 cells/mm ³	110 (81)	102 (84)	1176 (972-1372)	288 (145-434)

^a CHF denotes Swiss Francs (100 CHF correspond to about 43 £). SD, standard deviation

^b 7101 (range: 1697-34,868) after 8.5 years (base-case scenario), 19 years (optimistic scenario), and 5.5 years (pessimistic scenario)

^c 4667 (range: 1356-21,578) after 8.5 years (base-case scenario), 19 years (optimistic scenario), and 5.5 years (pessimistic scenario)

30'000 individuals that was followed through the model for approximating the distribution of lifetimes was used to approximate the distribution of costs. Health care costs were modeled stochastically using triangular distributions in each deterministic scenario concerning natural disease history. To reflect the fluctuations in resource use for each individual, a new sample was taken every

six months until the patient entered the death state. Since our cost estimates were derived from patients followed at the University of Basel HIV clinic, all samples for costs were multiplied by 0.86 (range: 0.83-0.88) to adjust for the average resource use in Switzerland (Meier, 1999). On this basis, the lifetime estimates for consumption of health care resources were computed as shown in Table 3.

Productivity changes were included in the analysis from the societal perspective. In an analysis from the societal perspective, all costs are considered (Drummond et al., 1997). Costs other than productivity changes are considered to be negligible in this analysis. The SHCS database contains detailed information on the ability to work and the number of worked hours per month. The ability to work (a value between 0% and 100%) does not reflect the actual productivity of an individual. Consequently, the average number of hours worked in a specific health state was extracted to derive the true estimates for productivity. We computed separate estimates for patients with HAART and NART (Table 2). These turned out to approximate a normal distribution.

Again, the same cohort of 30'000 patients used for health care costs was followed through the model, one at a time, to approximate the distribution of productivity over a lifetime. To reflect fluctuations in productivity, every 6 months a new sample for the number of worked hours was taken. This value was then multiplied by 25 (range: 20 - 31) which is the average hourly income in Swiss Francs (Ledergerber et al., 1998; Bundesamt für Statistik, 1997). The means of these distributions are shown in Table 3.

Table 3. Projected health care cost and productivity estimates in patients with highly active antiretroviral therapy (HAART) and no antiretroviral therapy (NART) in different scenarios of natural disease history.

Discount Rate % (Range)	base-case		optimistic		pessimistic	
	HAART	NART	HAART	NART	HAART	NART
<i>Health care costs in 1997 CHF^c</i>						
0%	505'290	209'052	616'591	248'664	418'770	169'446
3.5% (2%-3.5%) ^a	430'829	194'383	451'475	228'539	377'577	164'119
4% (2.5%-8%) ^b	389'033	187'078	386'642	218'561	351'498	159'382
<i>Productivity in 1997 CHF^c</i>						
0%	486'936	178'834	920'699	215'331	315'211	132'959
3.5% (2%-3.5%) ^a	419'760	168'042	734'050	200'301	289'440	126'421

^a societal perspective

^b health care perspective

^c CHF denotes Swiss Francs (CHF 100 correspond to about £43).

To account for the initial size of the real-world cohort, 3856 individuals (with replacement) were sampled from the respective distributions and the mean increase in health care costs and productivity were computed. In the societal analysis, the gain in productivity with HAART, compared with NART, was subtracted from the consumption of health care resources. Thus, productivity changes as a consequence of differences in morbidity and mortality were included (Johannesson and Meltzer, 1998). This procedure was repeated 5000 times. For each scenario, the mean and 95% prediction interval for incremental costs with HAART compared with NART were calculated. The uncertainty in the final estimate results from the uncertainty of each individual's path, the variability of cost and productivity estimates (triangular and normal distributions), the finite size of the cohort, and the discount rate (triangular distribution).

Table 4. Cost effectiveness of highly active antiretroviral therapy compared to no antiretroviral therapy in different scenarios of natural disease history.

	Health care perspective ^a			Societal perspective ^b		
	<i>base-case</i>	<i>optimistic</i>	<i>pessimistic</i>	<i>base-case</i>	<i>optimistic</i>	<i>pessimistic</i>
<i>Costs (1997 CHF)^c</i>	201'870	168'023	191'023	<i>savings</i>	<i>savings</i>	50'554
<i>Years of life gained</i>	6.13	11.67	4.27	6.82	13.73	4.61
<i>Cost per year</i>	33'000	14'000	45'000	-	-	11'000

^aOnly increases in discounted health care costs were included.

^bDiscounted productivity gains owing to changes in morbidity and mortality were subtracted from increases in consumption of health care resources.

^cCHF denotes Swiss Francs (100 CHF correspond to about £ 43).

Estimates of cost-effectiveness

The cost-effectiveness ratio is the difference in costs divided by the difference in effectiveness observed between two alternatives. The cost-effectiveness ratio is only an unambiguous measure when both the denominator and numerator have a positive sign (Stinnett and Mullahy, 1998). Therefore, in those cases only, the ratio of mean cost and mean effectiveness was used to derive a point estimate for the cost-effectiveness ratio (Stinnett and Paltiel, 1997). To assess the uncertainty in the cost effectiveness of HAART, the cost-effectiveness ratio was also calculated during the sampling procedure for estimating the uncertainty in cost and effectiveness. This allowed the density of the cost-effectiveness ratio based on 5000 samples to be investigated.

Results

The point estimates of the cost-effectiveness analysis are shown in Table 4. In the analysis from the health care perspective, the increase in costs are highest in the base-case scenario and lowest in the optimistic scenario of natural disease history. Patients in the pessimistic scenario have a much lower life expectancy. Less health care resources are, therefore, consumed in the pessimistic scenario, which leads to lower incremental costs compared to the base-case scenario. The cost-effectiveness ratio, however, increases from CHF 14,000 per year of life gained in the optimistic scenario to CHF 45,000 per year of life gained in the pessimistic scenario.

In the analysis from the societal perspective, the policy of providing unrestricted access to HAART is cost saving in all scenarios with the exception of the pessimistic scenario. In the pessimistic scenario the cost-effectiveness ratio is CHF 11,000 per year of life gained.

The 95% prediction intervals for years of life gained and the corresponding intervals for the increase in health care costs with HAART are shown in Figure 2A for each scenario. Figure 2B shows the results when productivity changes are included. The 95% prediction interval for the increase in societal costs crosses the zero-line in the base-case scenario, which indicates that the HAART strategy is not cost saving in a small proportion of samples (out of 5000). But in those cases where the incremental costs are positive, the cost-effectiveness ratio hardly reaches CHF 5000 per year of life gained (Figure 3B, to the right of the zero-line). The optimistic scenario is not shown in Figure 2B and Figure 3B since the productivity gains exceed by far the health care costs. The optimistic scenario is always cost saving from a societal perspective.

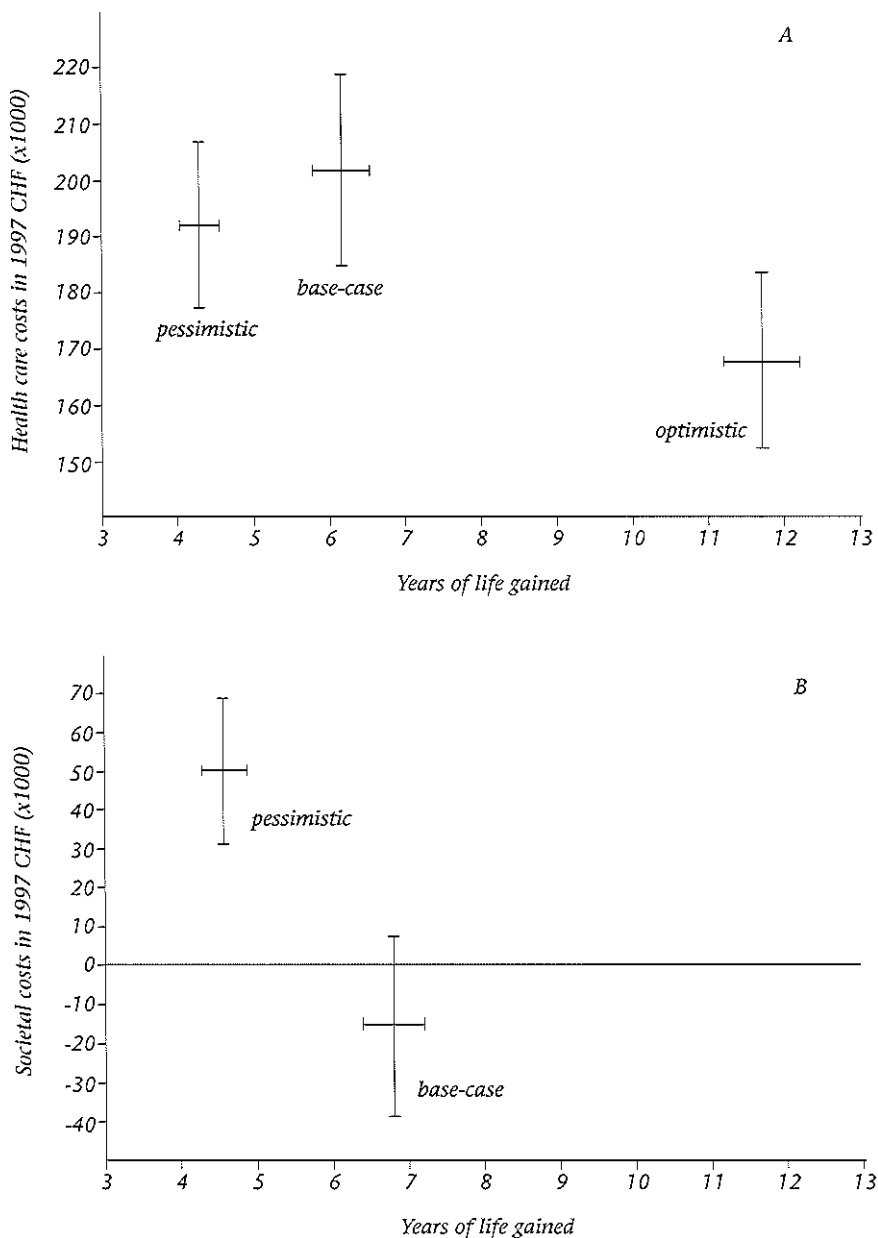


Figure 2. Incremental costs and survival in HIV-infected patients with highly active anti-retroviral therapy in different scenarios of natural disease history. A, based on health care costs; B, based on societal costs. Vertical bars represent the 95% prediction intervals for incremental costs. Horizontal bars represent the 95% prediction intervals for incremental survival. Costs and survival with HAART are compared to no antiretroviral therapy.

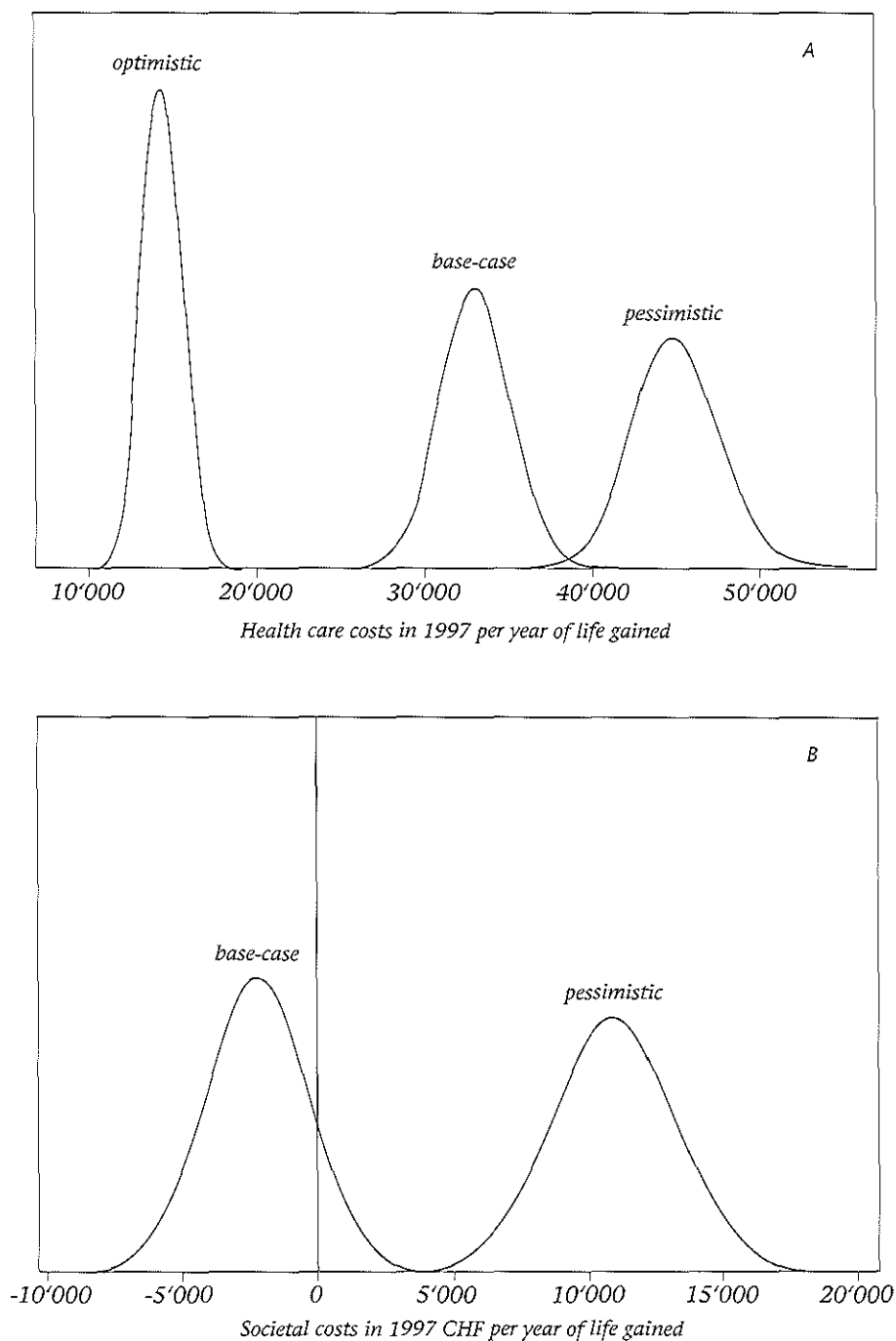


Figure 3. Density of cost effectiveness ratios in HIV-infected patients with highly active antiretroviral therapy in different scenarios of natural disease history. A, based on health care costs; B, based on societal costs. Where cost effectiveness ratios are negative (Figure 2B), highly active antiretroviral therapy is cost saving.

Discussion

Newer antiretroviral combination therapies including proteinase inhibitors represent a major improvement in treating HIV-infected individuals. Overall health care costs with HAART, which includes acquisition costs for antiretroviral drugs, exceed the average health care costs with NART substantially. This is because individuals have a higher life expectancy with HAART, consequently more health care resources are needed to treat this chronic disease condition. However, since the expensive costs for in-patient treatment are postponed to later years in patients receiving HAART, discounting has a major impact on overall health care costs. For example, undiscounted health care costs in the optimistic scenario (CHF 617,000) are higher than in the base-case scenario (CHF 505,000). But when respecting time preference, the same health care costs are CHF 387,000 and CHF 389,000, respectively. In most cases over all scenarios, however, the cost effectiveness was below CHF 50,000 per year of life gained in our sampling exercise.

One of the most important causes of death in young people in Switzerland is AIDS (Bundesamt für Statistik, 1997), which affects the society as a whole. The societal viewpoint is the broadest viewpoint and, therefore, the most relevant. The policy of providing HAART to HIV-infected individuals saves costs to the society. Only in the pessimistic scenario is this not the case. Even though there are no Swiss standards to assess the acceptability of a cost-effectiveness ratio, we believe that CHF 11,000 per year of life saved is not a high price relative to what is currently provided. Our analysis from the viewpoint of the health care system illustrates that HAART increases both average survival and health care costs. If the health care system wants to contain costs, it would need to find programs to be canceled where the loss in health terms will be smaller than the health gains from the HAART program (Birch and Gafni, 1993). Our analysis from the health care perspective can provide some input into this process.

The cost-effectiveness of HAART has also been investigated in two previous studies in the United States (Moore and Bartlett, 1996) and Canada (Anis et al., 1998). The results of these studies are comparable to the present study. However, the authors did not assess the societal implications of treating HIV-infected individuals with HAART. We think that our study provides better evidence of the clinical and economic consequences of prescribing these newer antiretroviral combination therapies to HIV-infected patient because natural history and cost data are extracted from the same patient population, enrolled in the SHCS. Furthermore, observational data reflecting the real-world situation (external validity) are used (Drummond, 1998). The cost-effectiveness exercise, therefore, does encompass non-adherence to complex drug regimens, as observed in general practice. Finally, the SHCS is one of the world largest cohort studies on HIV disease, which increases the reliability of the results.

This cost effectiveness analysis has limitations that should be considered. A model is always a simplification of the real world. This study does not explicitly model all AIDS-defining diseases separately. However, more complicated models do not necessarily provide more reliable results (Naimark et al., 1997). Importantly, extrapolation into the future was involved (Buxton et al., 1997) but the future is unknown for many aspects in this highly dynamic field. Consequently, extreme scenarios of natural history of HIV disease were devised. Changes in therapy such as moving from a three-drug or four-drug regimen to five or more drugs were rarely observed in the SHCS. Such a shift would lower the cost-effectiveness of HAART. Not only would the acquisition costs be higher, but also patient would be less likely to adhere to such complex drug regimens. However, we believe that the emerging knowledge about drug-resistance patterns and the advent of new antiretroviral drugs will lead to a more efficient use of drug combinations. Finally, patients were assumed to remain on HAART until death in our model. Patients may not be on therapy until death in reality. But this would reduce acquisition costs of antiretroviral drugs, and the assumption may, therefore, be regarded as a conservative assumption.

For decision makers in Switzerland, equity considerations have principally been more important than maximizing health benefits from a fixed resource pool. This conception is also shared by many policy and decision makers in other countries (Ubel et al., 1996). The promising results here, including the pessimistic societal scenario, justify the policy of providing unrestricted access to HAART for all HIV-infected individuals in Switzerland. Society will likely benefit even in the case where the policy would be based solely on economic grounds. The presented results also suggest that this policy could be of interest for other developed countries. Decision makers in developed countries where access to HAART is limited should re-evaluate their policy for the benefit of the society at large.

■ Chapter 9

Cost-effectiveness of azithromycin for preventing Mycobacterium avium complex infection in HIV-infected patients in the era of highly active anti-retroviral therapy

Summary

We conducted a cost-effectiveness analysis to determine the clinical and economic consequences of *Mycobacterium avium* complex (MAC) prophylaxis in HIV-infected patients in the era of highly active antiretroviral therapy (HAART) in a health care system with access unrestricted by financial barriers. The analysis was performed from a health care perspective and compared azithromycin (1200 mg/week) with no prophylaxis over a period of 10 years based on data from the Swiss HIV Cohort Study (SHCS) and randomized controlled trials. The main outcome measures were: expected survival; average health care costs; and cost-effectiveness in 1997 Swiss Francs (£1 corresponds to about CHF 2.3) per life-year saved. In patients with an initial CD4 count <50 cells/mm³ and no AIDS, azithromycin increased expected survival by 4 months. In patients with AIDS, HAART durability had a major impact on expected survival and costs. Incremental survival increased from 2 to 4 months if we assumed a 10 year, instead of a 3 year, HAART effect. The cost-effectiveness of azithromycin relative to no prophylaxis in patients without AIDS was between CHF 47,000 (3-year HAART effect) and CHF 60,000 (10-year HAART effect) per life-year saved. The cost-effectiveness ratio increased to CHF 118,000 per life-year saved in patients with symptomatic AIDS. In conclusion, in the era of HAART, MAC prophylaxis with azithromycin increases expected survival and health care costs substantially. Starting MAC prophylaxis in patients without AIDS is more effective and cost-effective than in patients with AIDS.

Introduction

Disseminated *Mycobacterium avium* complex (MAC) infection in severely immunosuppressed HIV-infected patients is associated with increased morbidity and mortality (Horsburgh, 1991). Randomized controlled trials have documented the benefit of MAC prophylaxis with macrolides in HIV-infected patients with advanced immunosuppression (Pierce et al., 1996; Havlir et al., 1996; Oldfield et al., 1998). Economic studies, based on models with clinical data gathered before (Freedberg et al., 1997; Freedberg et al., 1998) and after (Bayoumi and Redelmeier, 1998) highly active antiretroviral therapy (HAART) became widely available, have investigated the policy implications of MAC prophylaxis in the USA. However, the cost-effectiveness of MAC prophylaxis within a European setting has not yet been evaluated. The Swiss health care system, as an example of a Western European-type health care system, provides unrestricted access to all approved therapies for patients with HIV infection. The majority (66.2%) of the Swiss health care resources are funded by consumers either directly (out-of-pocket payment) or indirectly (insurance companies) (Bundesamt für Statistik, 1998). Official federal organizations fund most of the remainder (Bundesamt für Statistik, 1998). We conducted a cost-effectiveness analysis from the health care perspective to address the clinical and economic implications of MAC prophylaxis with azithromycin in the era of HAART. Our analysis is based on the Swiss HIV Cohort Study (SHCS) (Ledergerber et al., 1994). This study offers additional insights about the consequences of MAC prophylaxis in HIV-infected individuals receiving care in a system with access unrestricted by financial barriers. In addition, we applied Bayesian analytical techniques to reflect *overall* parameter uncertainty (Craig et al., 1999).

Methods

The model

We developed a Markov (or state-transition) model (Sonnenberg and Beck, 1993) that describes the disease history of HIV-infected subjects as a sequence of monthly health states. We defined four broad categories of health: No AIDS (asymptomatic HIV-positive), AIDS (non-MAC), MAC and death. We used the European classification for AIDS (Ancelle-Park et al., 1995). The No AIDS and AIDS states were further stratified into three CD4-cell count categories: 0-49 cells/mm³, 50-74 cells/mm³ and ≥ 75 cells/mm³. A patient currently in a No AIDS state is at risk of dying from non-AIDS-related causes, developing MAC or developing an AIDS-defining disease other than MAC. A patient with AIDS is at risk of dying from AIDS or developing MAC. A patient with MAC is at risk of dying from MAC. Prophylactic drug efficacy is expressed as a reduction in MAC incidence. A low adherence in turn is modeled as a low drug efficacy. Severe drug toxicity results in discontinuation of MAC prophylaxis. The model

was implemented in DATA 3.0 (TreeAge Software, Williamstown, MA, USA) and self-written FORTRAN 90 code. The validation procedures applied to our model are described in detail elsewhere (Sendi et al., 1999b). Expected survival and average costs were computed over a 10-year period using matrix multiplication. We felt that 10 years would be the maximum realistic time-horizon for extrapolation in this highly dynamic and changing field where far-reaching predictions are rarely possible.

In Switzerland, HAART was introduced in 1996 (Egger et al., 1997). There is a paucity of data on the long-term efficacy of HAART. Therefore, we analyzed this model under three scenarios assuming different levels of HAART durability: a continuous time effect scenario (CTES), a 5-year effect scenario (5-YES) and a 3-year effect scenario (3-YES). We used Swiss HIV Cohort Study (SHCS) data from 1996-1997 to estimate the transition probabilities in the era of HAART. We used probability estimates derived from the SHCS 1993-1995 data set, before those therapies became widely available, to reflect the loss of HAART effect.

Costs in Swiss francs (£1 corresponds to about CHF 2.3) and survival were discounted at an annual rate of 4% to correspond with the discounting practice of major Swiss Insurance companies (Schweizerische Unfallversicherungsanstalt, personal communication, 1998) (Krahn and Gafni, 1997).

Clinical data

The SHCS, a multi-center, prospective study, started in 1988, has enrolled more than 9000 patients over a period of 10 years (Ledergerber et al., 1994). We used the SHCS data set to obtain maximum likelihood estimates of transition probabilities describing the natural history of HIV disease. Formation of posterior distributions for the Bayesian analysis is available on request from the authors.

For estimating transition probabilities among CD4 count strata, we included only patients with a CD4 count <75 cells/mm³ after January 1, 1993 and at least one follow-up. Individuals contributed to the model from the first date characterized by a CD4-cell count <75 /mm³. A rise in CD4-cell count above 75/mm³ after that date was accepted. We pooled follow-up data recorded before and after December 31, 1995 separately, to estimate the probabilities for the two periods. We converted these 6-month transition matrices into 1-month transition matrices applying matrix decomposition (Table I) (Craig and Sendi, 1998).

Probability estimates for developing an AIDS-defining disease (MAC/non-MAC) and dying from AIDS given a specified CD4-cell stratum were also extracted from the SHCS (Table II). The monthly risk of dying from MAC was derived from an analysis by Low and colleagues (1997). Pre-AIDS mortality may vary among different populations (Laurichesse et al., 1998; Prins et al., 1997).

Table I. Monthly probabilities of transitions among CD4-cell count strata in two time periods in the SHCS

SHCS period	Initial CD4-cell stratum (cells/mm ³)	Final CD4-cell stratum		
		0-49	50-74	≥75
1993-1995	0-49	0.9819	0.0122	0.0059
	50-74	0.1766	0.7517	0.0717
	≥75	0.0177	0.0933	0.8830
1996-1997	0-49	0.8785	0.0735	0.0480
	50-74	0.1226	0.6607	0.2167
	≥75	0.0096	0.0249	0.9655

We integrated this assumption into our model using SHCS data and Swiss life-table estimates. The base case was a 33-year-old HIV-infected individual to coincide with the mean age of SHCS participants.

Efficacy and toxicity estimates for azithromycin were extracted from a randomized controlled trial (Oldfield et al., 1998). We computed for azithromycin (1200 mg once weekly) an efficacy of 0.6561 and a monthly risk of severe toxicity of 0.006. We did not include clarithromycin in our analysis. Its efficacy and toxicity are comparable to azithromycin but it is much more expensive in Switzerland (Pierce et al., 1996; Oldfield et al., 1998; *Arzneimittelkompendium der Schweiz*, 1997). Furthermore, the dosing schedule with azithromycin (once weekly) is favorable since it reduces the pill burden of patients. Rifabutin was excluded from our analysis because it is less effective, more toxic and more expensive than azithromycin (Havir et al., 1996; *Arzneimittelkompendium der Schweiz*, 1997).

Cost data

Since we chose the viewpoint of the health care system, only treatment costs are considered. We reviewed a random sample of charts of HIV-infected patients enrolled in the SHCS to estimate use of health care resources. These patients receive their main ambulatory care at the internal medicine outpatient services in four University Hospitals (Basel, Bern, Geneva and Zurich). We included 46 patients with MAC infection and 62 patients with an AIDS-defining disease other than MAC.

Quantities of resource use were abstracted on a per patient basis. We estimated each component of resource use (micro-costing) (Drummond et al., 1997). As protease inhibitors were not available at the time of cost data collection (1993-1995), the central cost for protease inhibitors was derived from an estimated 70% of patients taking protease inhibitors (Sendi et al., 1999a) at a daily cost of CHF 21 (Flepp et al., 1997). The 'hotel component' of hospital

Table II. Monthly probabilities of *Mycobacterium avium* complex infection and other opportunistic diseases stratified by CD4-cell count in two time periods in the SHCS

Opportunistic infection	CD4-cell stratum (cells)	Monthly risk	Reference SHCS period
M. avium complex	0-49	0.0204	93-95
		0.0076	96-97
	50-74	0.0099	93-95
		0.0016	96-97
	≥75	0.0052	93-95
		0.0003	96-97
Other AIDS-defining diseases	0-49	0.0393	93-95
		0.0212	96-97
	50-74	0.0305	93-95
		0.0103	96-97
	≥75	0.0167	93-95
		0.0013	96-97

Table III. Monthly costs (CHF)^a of care for AIDS-free patients, patients with MAC and patients with other AIDS-defining diseases in the SHCS

Location	No AIDS ^b	AIDS without MAC ^c	AIDS with MAC ^c
Basel	-	8244	11191
Bern	-	5675	7353
Geneva	-	7272	9841
Zurich	-	7751	8937
Mean	1017	7235	9330

^aInflated to 1997 Swiss francs (CHF) using the Swiss CPI for health care. £1 corresponds to about 2.3 CHF.

^bIncludes regular check-up visits, laboratory examinations, *Pneumocystis carinii* prophylaxis, antiretroviral drugs.

^cCosts were extracted from a random sample of patient charts from four Swiss university hospitals. Costs for protease inhibitors were added.

expenditure in case of stationary health care was estimated on the basis of patient-days (assuming average daily hotel costs). We assumed that patients who were asymptomatic had regular check-up visits, routine laboratory examinations, *Pneumocystis carinii* prophylaxis and antiretroviral drugs. Costing details are described elsewhere (Meier, 1992).

Monthly cost estimates were averaged for each institution. We then linked these average resource use estimates to the three states: No AIDS (pre-AIDS), AIDS with MAC and AIDS without MAC (Table III). For patients receiving

MAC prophylaxis we added the wholesale price of azithromycin (200 CHF per month) (Arzneimittelkompendium der Schweiz, 1997). Azithromycin toxicity was assumed not to lead to additional costs, since these are captured by the regular physician visits and laboratory tests for check-up examinations. All costs were inflated to 1997 CHF using the Swiss consumer price index for health care (Swiss Federal Statistics Office, Bern Switzerland).

Bayesian analysis

The expected survival and average costs are both functions of the model parameters. Therefore, it is important to account for the joint uncertainty in the parameters when comparing prophylactic strategies (O'Brien et al., 1994). Bayesian analysis relies on the idea that uncertainty can be described by a distribution. We took a Bayesian approach thereby creating a joint distribution of model parameters (posterior), which is conditional on the model, prior opinion and the data. In turn, 5000 samples from this joint distribution were used to approximate distributions of expected survival and average costs. For each set of sampled model parameters, we computed the expected survival and average costs of the two strategies using matrix multiplication. These results were then combined to form the approximate distributions of each summary. The resulting distributions reflect our joint uncertainty of the model parameters. A detailed description of the Bayesian methodology is available on request from the authors.

Table IV. Costs, life-expectancy and cost-effectiveness of preventing *M. avium* complex infection with azithromycin in patients with an initial CD4 count <50 cells/mm³

Scenario ^a	Strategy ^b	No AIDS			AIDS		
		Costs (CHF) ^c	LE ^d (months)	ICER ^e (CHF/YLS)	Costs (CHF) ^c	LE ^d (months)	ICER ^e (CHF/YLS)
CTES	no prophylaxis	210,155	73.77		487,554	66.95	
	azithromycin	230,885	77.94	60,000	522,319	70.50	118,000
5-YES	no prophylaxis	189,064	62.66		395,756	53.98	
	azithromycin	205,629	66.47	52,000	421,149	56.56	118,000
3-YES	no prophylaxis	165,242	52.27		316,766	43.01	
	azithromycin	179,589	55.95	47,000	335,490	44.92	118,000

^aScenario relates to HAART durability assumptions. CTES denotes continuous-time effect scenario, 5-YES denotes 5 year effect scenario, 3-YES denotes 3 year effect scenario.

^bDoses for prophylaxis were 1200 mg once weekly for azithromycin.

^cAll costs are in 1997 CHF (Swiss francs).

^dLife expectancy over a 10 year period.

^eICER denotes incremental cost-effectiveness ratio (rounded up to nearest 1000 CHF), which is the difference in cost divided by the difference in life-expectancy in terms of years of life saved (YLS) for azithromycin compared with no prophylaxis.

Results

Baseline analysis

The survival curves in patients with a CD4 count <50 cells/mm³ and without MAC prophylaxis are shown in Figure 1. In all scenarios with the exception of the CTES the survival probability was about 10% or below at year 10. Expected survival and costs are shown in Table IV. Starting prophylaxis at a CD4 cell level of 50-74 cells/mm³ instead of 0-49 cells/mm³ was always less cost effective. All calculations were also done undiscounted and at an annual discount rate of 8% but no major effect on the incremental cost-effectiveness ratios was observed.

Table V. 95% credible intervals for incremental costs, life-expectancy and cost-effectiveness ratios of preventing *M. avium* complex infection with azithromycin in patients with an initial CD4 count <50 cells/mm³

Initial status	Outcome ^a	CTES	5-YES	3-YES
No AIDS	incremental costs (CHF) ^b	17,000-31,000	12,000-26,000	9000-24,000
	incremental LE (months)	2.63-6.13	2.35-5.48	2.25-5.36
	ICER (CHF/YLS) ^b	48,000-88,000	37,000-81,000	29,000-76,000
AIDS	incremental costs (CHF) ^b	25,000-54,000	17,000-49,000	12,000-29,000
	incremental LE (months)	2.31-5.58	1.64-3.90	1.17-2.92
	ICER (CHF/YLS) ^b	91,000-151,000	86,000-157,000	79,000-165,000

^aIncremental costs is the difference in costs for azithromycin compared with no prophylaxis. Incremental life-expectancy (LE) is the difference in life-expectancy for azithromycin compared with no prophylaxis. ICER denotes incremental cost-effectiveness ratio, which is the difference in costs divided by the difference in life-expectancy for azithromycin compared with no prophylaxis.

^bRounded to nearest 1000 CHF.

Abbreviations as in Table IV.

Bayesian analysis

The 95% credible intervals for incremental costs, life expectancy and cost-effectiveness ratios are shown in Table V. We present for azithromycin (Figure 2) the joint posterior distribution of incremental costs and incremental effects as iso-probability contour plots (Hunink et al., 1998). The size of the contour plot reflects the level of uncertainty in the estimates. The central contour circumscribes the area where the joint posterior for incremental costs and effects will

lie with highest probability. Average costs and life expectancy are positively correlated leading to the depicted characteristic shape of the contour plots. This correlation is positive because only treatment costs were included. The higher the expected survival, the more resources are needed to treat a chronic disease condition. This is shown by the contour plots shifting upward and to the right when we move from the 3-YES to the CTES. When MAC prophylaxis is started in asymptomatic HIV-infected patients, this shift is less pronounced. The slopes of the two lines in each cell reflect the upper and lower limits of the 95% credible interval of the incremental cost-effectiveness ratio. These slopes suggest that starting antibiotic prophylaxis in patients with AIDS is less cost effective than in patients without AIDS.

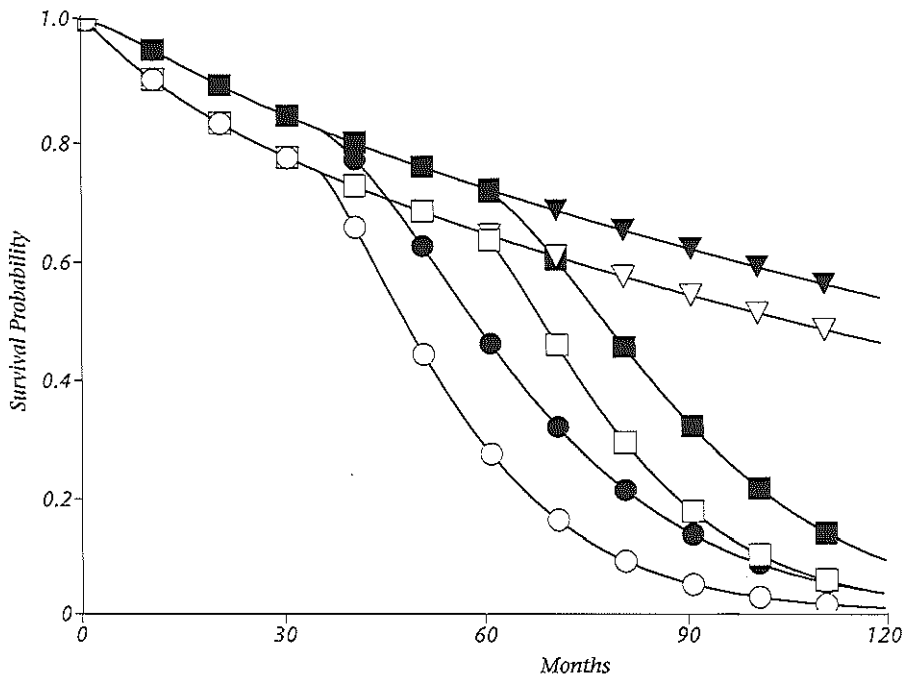


Figure 1. Survival probability in patients with an initial CD4 count <50 cells/mm³. We used different scenarios concerning highly active antiretroviral therapy durability. CTES denotes continuous-time effect scenario, 5-YES denotes 5 year effect scenario. 3 YES denotes 3-year effect scenario, A denotes AIDS (patients with AIDS initially), NA denotes No AIDS (patients without AIDS initially). ▼, NA, CTES; ■, NA, 5-YES; ●, NA, 3-YES; ▽, A, CTES; □, A, 5-YES; ○, 3-YES.

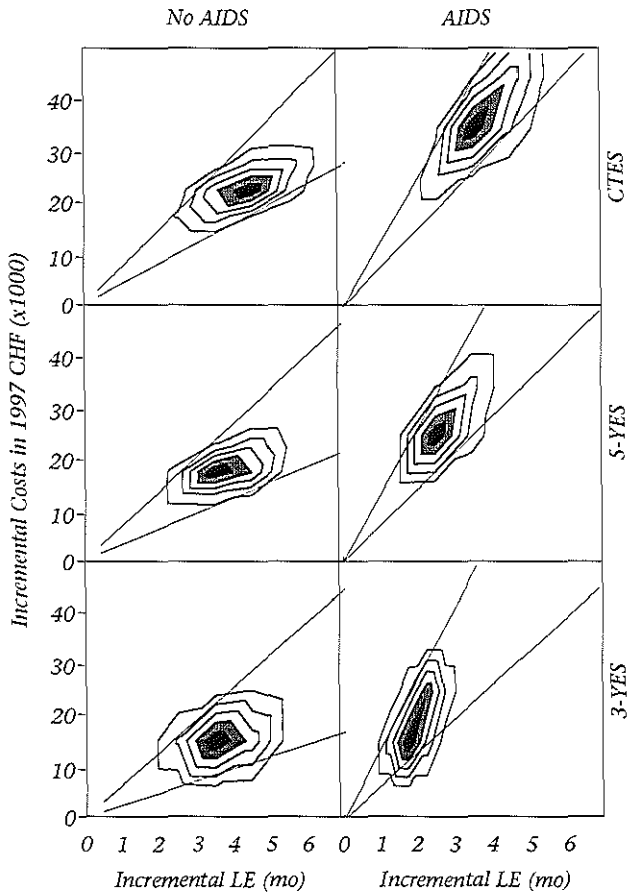


Figure 2. Iso-probability contour plots of the joint distribution of the mean incremental costs and effectiveness for starting azithromycin prophylaxis in patients with and without AIDS. CHF, Swiss Francs, rounded to nearest 1000. LE, Life-expectancy (months). We used different scenarios concerning highly active antiretroviral therapy durability. CTES denotes continuous-time effect scenario, 5-YES denotes 5 year effect scenario, 3-YES denotes 3 year effect scenario.

Discussion

In the era of HAART, MAC infection is still one of the most frequent opportunistic infections among HIV- positive individuals in Switzerland and parts of Europe (Egger, 1998). Nonetheless, the incidence of AIDS-defining diseases, including MAC, has declined since the introduction of HAART (Egger et al., 1997; Gebhardt et al., 1998), which disfavors antibiotic prophylaxis (Wright and Weinstein, 1998). However, the expected survival of patients with advanced CD4 cell depletion has increased remarkably. This, in contrast, makes MAC prophylaxis more beneficial (Wright and Weinstein, 1998). Although HAART lowers the monthly risk of acquiring MAC at a given CD4 cell level and may also partially restore immune function, our model shows that these effects are by far outweighed by a higher cumulative risk of MAC infection associated with a higher life expectancy. This is documented by an increasing gain in survival with azithromycin in the more optimistic scenarios of HAART durability. Azithromycin was only discontinued when severe toxic reactions were experienced, but not when HAART increased the CD4 cell count above the cut-off point (≤ 50 CD4 cells/mm³) for MAC prophylaxis (USPHS/IDSA Prevention of Opportunistic Infections Working Group, 1997). We found an average gain in survival comparable to the estimates reported by Bayoumi and Redelmeier (1998) for a North American setting.

MAC prophylaxis leads to a substantial amount of resource consumption within the Swiss health care sector. Antibiotic prophylaxis in patients with AIDS increases direct medical costs more than in AIDS-free patients and results in a lower gain in survival. This translates into a cost-effectiveness ratio that is higher. It would not be uncommon for the cost-effectiveness ratio for azithromycin in patients with AIDS to exceed CHF 150,000 per life-year saved. If MAC prophylaxis is started in AIDS-free patients, there is a negligible chance that this would cost CHF 100,000 per life-year saved. If the health care system wants to contain costs, it needs to cancel programs where the loss in health terms is lower than the health gains from the azithromycin program (Birch and Gafni, 1992). Alternatively, policy decision-makers should find ways to increase the health care budget.

■ Chapter 10

Discussion

In this thesis, three different approaches to the decision rule of cost-effectiveness analysis have been discussed when costs and effects are uncertain: i) the alternative decision rule, ii) the classical decision rule, and iii) portfolio theory for choosing among health care programs.

The alternative decision rule

In chapter 2 the alternative decision rule has been illustrated when costs and effects are subject to uncertainty. The motivation for using the alternative decision rule is that a decision-maker's available resources may all be used by current programs. If a new program becomes available which contributes to gains in QALYs but calls for additional resources, then one must ask where these resources will come from. In such a situation, other programs need to be cancelled in order to free up resources to fund the new program. If the health benefits gained by introducing the new program are greater than those lost by relinquishing the old program, then an unambiguous improvement in the allocation of resources is achieved. This is a second-best approach, since more than one program in the current portfolio might satisfy these requirements (Gafni, 1996). However, in practice, the information on the costs and effects of all programs in the current portfolio might not be available. The practical advantage of the alternative decision rule then becomes apparent: information on the costs and effects of only one program that satisfies the requirements of the decision rule is sufficient for increasing the efficiency of resource allocation.

The decision-making plane has been introduced as a means to graphically present the results of the alternative approach, plotting $\Delta C(A) - \Delta C(B)$ on the vertical axis against $\Delta E(A) - \Delta E(B)$ on the horizontal axis. If we write out the terms, the vertical axis denotes $(C_A - C_d) - (C_B - C_b)$, i.e. the incremental costs of introducing program A compared to the costs which would accrue if program A was not available, minus the resources that would be released if program B was cancelled. Note that by introducing program A we replace program a with program A, and by canceling program B we replace it with program b. The same principle holds true for the horizontal axis: writing out the terms $\Delta E(A) - \Delta E(B)$ is equivalent to $(E_A - E_d) - (E_B - E_b)$. The alternative decision rule requires that $\Delta C(A) - \Delta C(B) \leq 0$ and $\Delta E(A) - \Delta E(B) \geq 0$. If both $\Delta C(A) - \Delta C(B) = 0$ and $\Delta E(A) - \Delta E(B) = 0$, then we would be indifferent with respect to introducing program A since this neither results in any health gains nor releases resources that could be used otherwise to improve health.

An interesting alternative approach to view the decision-making plane is that it actually corresponds to the cost-effectiveness plane, but with the difference that two strategies are compared, each representing a combination of two programs. Note that $(C_A - C_d) - (C_B - C_b) = (C_A + C_b) - (C_B + C_d) = C_{A+b} - C_{B+d}$, i.e. the costs of the combination of program A plus b are compared to the costs

of the combination of program B plus a. The same holds true for the effects. The term "decision-making plane" has been chosen in order to emphasize that this comparison actually involves four programs instead of two. In this comparison, the alternative decision rule requires that the combination of program A plus b should be dominant over the combination of program B plus a. In the presence of uncertainty associated with the costs and effects of health care programs, the joint distribution of costs and effects may not be limited to the southeastern quadrant of the decision-making plane. However, only outcomes that fall in the southeastern quadrant of the decision-making plane are consistent with an improvement in the efficiency of resource allocation. In such a situation it has been suggested that the decision-maker's acceptable risk of accepting outcomes in other quadrants may be limited to an arbitrary level, such as the arbitrary decision of accepting a 5% Type I error in hypothesis testing.

However, a more elegant approach to summarize uncertainty on the decision-making plane is to apply the cost-effectiveness acceptability curve (van Hout et al., 1994). If the joint distribution of costs and effects falls completely in the southeastern quadrant of the decision-making plane, which is what we aim for when applying the alternative decision rule, then this switch of programs would be cost-effective for all levels of the threshold ratio. That is, the cost-effectiveness acceptability curve would correspond to a horizontal line at the probability level of one. In case the joint distribution also extends over other quadrants of the decision-making plane, then the cost-effectiveness acceptability curve would inform the decision-maker about the range of the threshold ratio for which the switch of program would be cost-effective with a high probability.

Combining the cost-effectiveness acceptability curve with the alternative decision rule in the presence of uncertainty can be seen as a "marriage" between the two approaches. The use of the cost-effectiveness acceptability curve to summarize uncertainty on the decision making plane seems, perhaps, to be inconsistent with the original idea that led to the development of the alternative decision rule. The alternative decision rule has been suggested as an alternative to using a fixed-threshold cost-effectiveness ratio, since this would lead to uncontrolled growth of health care expenditures as more programs with an acceptable cost-effectiveness ratio are implemented (Gafni and Birch, 1993). However, it should be noted that the alternative decision rule, on the other hand, does not allow growth of the health care budget. The use of the cost-effectiveness acceptability curve in combination with the decision-making plane may, therefore, be seen as a method that allows for controlled growth of the budget.

In chapter 3 the alternative decision rule was analyzed from a different perspective. Stochastic dominance rules were used to provide a way to make decisions based on little or limited knowledge of a decision-maker's risk prefe-

rence. The alternative decision rule shifts the cumulative distribution of health outcomes to the right and the cumulative distribution of costs to the left. First-order stochastic dominance requires that the decision-maker prefers more to less, no matter his risk-preference. First-order stochastic dominance requires that choice A+b is always preferred to choice B+a if the cumulative density function associated with B+a is not less than that with A+b for any outcome level and is greater than that with A+b for at least one outcome level. However, when the decision-maker prefers less to more, as in the case of costs, then first-order stochastic dominance requires that choice A+b is always preferred to choice B+a if the cumulative density function associated with B+a is not more than that with A+b for any outcome level and is smaller than that with A+b for at least one outcome level. In order to make this distinction of preferring less to more we have used the term "affordability". As emphasized in chapter 3, the use of stochastic dominance rules is complementary to the approach of presenting the results on the decision-making plane. However, the more the joint distribution of costs and effects shifts to the southeast on the decision-making plane, the more the cumulative distributions of the costs and effects of programs A+b and B+a will move apart.

An advantage of using the cumulative distribution of costs and effects as a basis for decision-making is that the uncertainty associated with all programs in the current portfolio can be included in the analysis. If the decision-maker has a total budget from which to fund all health care programs, then the cumulative distribution of total portfolio costs can be used to assess the probability that the budget is exceeded and whether this risk is acceptable to the decision-maker. Note that the budget does not need to be constant for this approach; it could be that a decision-maker needs to deal with a lower budget than in the preceding years. For example, policy-makers may decide to curtail the available budget to providers such as hospitals as a measure to reduce overall health care costs. In such a situation, program A can only be introduced if a program B can be found that would not only release sufficient resources to fund program A, but would also shift the cumulative distribution of total costs to the left to such a degree that the risk of exceeding the budget becomes acceptable.

In chapter 8 a cost-effectiveness analysis of highly active antiretroviral therapy (HAART) in HIV-infected patients has been presented. The analysis was conducted from the societal as well as the health care perspective. In the analysis from the societal perspective, when productivity costs were included HAART resulted in cost-savings as well as gains in life-years. However, when the analysis was limited to health care costs, HAART was more effective but also more costly, with the cost-effectiveness ratio ranging from 14,000 CHF to 45,000 CHF. The societal perspective is broad in the sense that everyone affected by the intervention is considered and all health outcomes and costs

that result from the intervention are counted. However, as shown in the study described in chapter 8, a strategy that is dominant from the societal perspective need not be dominant when a health care perspective is taken. The HAART program calls for additional health care resources and consideration must therefore be given as to where these resources will come from. If the health care budget is already spent on current programs and there is no other possibility to increase the health care budget, then the alternative decision rule may be used, i.e. a program B may be identified and cancelled that releases sufficient resources to fund HAART. However, deleting a program that is well established is a difficult task and often not feasible. Decision-makers may therefore prefer to increase the health care budget, e.g. by taxation or by increasing insurance premiums (Weinstein, 1995). In that case, the opportunity costs of the additional resources would be in areas other than health. However, increasing the health care budget would only be justifiable from an economics perspective if the health benefits gained from the HAART program are greater than those lost by cutting the budget of other sectors of the economy. It could also be said that by deciding to increase the health care budget society has implicitly applied the alternative decision rule across sectors of economy.

In chapter 9, the cost-effectiveness of azithromycin for preventing *Mycobacterium avium* complex infection in HIV-positive patients taking HAART was assessed. The analysis showed that azithromycin is more cost-effective in patients without clinical AIDS (47,000 CHF – 60,000 CHF per life-year gained) than in patients with AIDS (118,000 CHF per life-year gained). Starting azithromycin in HIV-infected patients without AIDS therefore represents a more efficient allocation of resources than waiting until the patient has experienced an AIDS-defining disease. However, in both patient subgroups the incremental costs were positive. This means that more health care resources are needed in order to prevent *Mycobacterium avium* complex infections in HIV-infected patients. Here again, as discussed above, the required resources may come from cutting the budget of other health care departments or from increasing the health care budget by taxation, higher insurance premiums, or reducing the budget of other sectors of economy such as education or national defense. In either case, a choice has to be made with respect to resource allocation, which forces the decision-maker to think in terms of opportunity costs of scarce resources.

The classical decision rule

In chapter 4 the assumption of complete divisibility of the classical decision rule of cost-effectiveness has been addressed. We argued that an integer programming approach where patients represent individual units might be more appropriate than a linear programming approach to formulate the budget allocation problem. Then we showed that treatments ruled-out by a linear pro-

programming approach could be provided to some patients in order to maximize total health benefit, subject to a budget constraint. It should be noted that there is a difference between the integer programming approach suggested by Birch and Gafni (1992) and the one discussed in chapter 4. In chapter 4 the number of patients to be treated were programmed as integers (i.e. 0 – 1000), which allows the size of the program to vary. Birch and Gafni, on the other hand, suggested that the whole program should be handled with an integer variable (i.e. 1 or 0) in order to model complete indivisibility (Birch and Gafni, 1992). Chapter 4 simply addresses the fact that patients are not divisible, but accepts the assumption of constant return to scale and divisibility at the program level. However, sub-optimal budget allocation decisions at the margin can be corrected for if individuals are modeled as integers.

Another idea introduced in chapter 4 is the application of simulation optimization to maximize the objective function of the constrained optimization problem. We defined expected aggregate effects as the objective function, which is penalized in case the budget is exceeded. This method allows the inclusion of the opportunity costs of the additional resource requirements in the analysis. Described in the first part of chapter 4, the method assumes that decision-makers are risk-neutral towards health effects and risk-averse towards costs. This may certainly be reasonable for decision-makers at the sub-societal level, who have budget constraints to meet. However, since the benefits of the programs only accrue to some individuals, a decision-maker might also be risk-averse towards health effects. In that case, the variance of aggregate effects may need to be minimized, subject to the constraint that some aspiration level for expected aggregate effects is met. Al (2001) suggested that for societal decision-making, risk-neutrality towards costs and risk-aversion towards health outcomes may be more in line with the arguments of Arrow and Lind (1970), and therefore formulated the optimization problem as minimizing expected costs under the constraint that the probability of total effects exceeding some aspiration level was at least 95%.

Zivin (2001) also recently discussed the appropriate risk-posture for societal decision-making and illustrated the limitations associated with the Pareto compensation criterion in health care and argued that social planners should be risk-averse towards health outcomes. Assuming a normal distribution for outcomes, the *ex ante* mean is usually not the same as the *ex post* mean. The *ex ante* uncertainty may be separated into the two components of statistical uncertainty (sampling variability) inherent in a trial and uncertainty about the appropriate values assigned to various components of the analysis, which is generally evaluated by traditional sensitivity analysis. Once a program is implemented by moving from a clinical trial to the general health care setting, some of the uncertainty will be reduced and the *ex post* mean will usually differ from the *ex ante* mean. Only when the *ex ante* sample is sufficiently large,

a very expensive undertaking, will the *ex post* distribution be approximated. Therefore, it is not true that *ex post* half of the outcomes will be above the *ex ante* mean and half below it, i.e. the winners are not necessarily able to compensate the losers. Moreover, Zivin (2001) argues that even if the uncertainty embodied in cost-effectiveness analyses is a reflection of true stochasticity, justifying a risk-neutral societal decision-maker based on the Pareto compensation criterion may be problematic because people are usually risk-averse with respect to lifetime. Risk-aversion implies that the utility gained from one additional year is less than the utility lost from one less year. This means that those who experience above average results will not be able to compensate for those who experience below average results.

The main difference between the variants of the classical approach discussed in chapter 4 and the classical approach presented in Al (2001) is that in chapter 4 the objective function is penalized in case the budget is exceeded. However, Al (2001) also suggested a much wider perspective of the budget allocation problem by extending the idea of a fixed budget to a flexible budget, which may compete with resources from other sectors of economy (such as education or national defense). This is accomplished by extending the maximization of health outcomes subject to a budget constraint in order to optimize the value derived from health outcomes and non-health care budgets competing with health care expenditures (Al, 2001). This method is then extended when costs and health outcomes are uncertain by defining a utility function for both money and health outcomes. However, defining an explicit utility function may prove difficult for practical decision-making and pragmatic alternative approaches such as those discussed above may be less demanding in terms of information required.

Hutubessy et al. (2001) suggested an alternative approach to decision-making when the distribution of costs and effects of all the available programs are known. In their hypothetical example the authors defined mutually exclusive alternatives for different disease conditions. They then constructed a "stochastic league table" by i) taking random draws from the distribution of total costs and effects for each treatment option in the menu, ii) constructing a standard league table for each iteration of the simulation (for a given budget level), and iii) estimating the number of times that an intervention is included in the optimal mix of programs (Hutubessy et al., 2001). The probability an intervention is included in the optimal mix of programs for all levels of resource availability allows the construction of what the authors call an expansion path. This method and the method presented in chapter 4 both assume that the budget as well as the distribution of the costs and effects of the programs is known. In chapter 4, however, a constrained optimization problem with an explicit objective function has been formulated. The information contained in

stochastic league tables, on the other hand, is probabilistic in nature and can rather be seen as a method to summarize uncertainty.

The method described in chapter 4 requires that the costs and effects of the whole portfolio of programs and the budget is known. For societal decision-making, a real-world budget cannot be defined (Johannesson and Meltzer, 1998), and the costs and effects of the total portfolio of health care programs are not usually known. On the contrary, decision-makers at the sub-societal level (e.g. health care providers and insurance companies) may know their budget, but the information on total costs and effects of all health care programs is not available in most health care systems. The use of a threshold ratio as a cut-off level may be seen as a pragmatic response to these limitations without any reference to an explicit optimization problem. In the presence of uncertainty, the cost-effectiveness acceptability curve plots for all possible values of the critical ratio the probability of an intervention being cost-effective. However, in the absence of an optimization problem, cost-effectiveness alone may be insufficient to decide whether a program should be funded, and consideration must be given to the impact of the program on the available health care budget.

In chapter 5 the cost-effectiveness affordability curve has been introduced as an extension of the cost-effectiveness acceptability curve. The cost-effectiveness affordability curve plots the probability that for a given budget level and for all possible values of the critical ratio the program is both cost-effective and does not exceed the available budget. Decision-makers who hold budgets from which to fund health care programs may prefer this type of information to cost-effectiveness alone. In particular, budgetary impact may be relevant for reimbursement decisions of new pharmaceuticals, decision-makers may not only be interested in assessing whether a new drug represents value for money but also what demands will be made on the total health care budget (Nuijten and Rutten, 2002).

Recently, several other extensions of the cost-effectiveness acceptability criterion have been suggested in the literature. For example, O'Brien et al. (2002) have questioned whether the threshold ratio is symmetrical for both gains and losses: whether the threshold ratio can be represented as a straight line through the northeastern and southwestern quadrant of the cost-effectiveness plane. In their paper, O'Brien et al. (2002) illustrate in a literature review that the consumers' willingness-to-accept monetary compensation to forgo a program is usually greater than the willingness-to-pay for the same program. A difference in slope of the acceptability criterion in the southwestern and northeastern quadrant of the cost-effectiveness plane would, of course, require a modification of the standard approach of constructing the cost-effectiveness acceptability curve (O'Brien et al., 2002).

Another alternative representation of uncertainty in cost-effectiveness analysis suggested is the concept of the cost-effectiveness frontier. Fenwick et al. (2001) argue that decisions should be based on expected net benefit and that interventions with a higher probability of a positive incremental net benefit are not necessarily those with a higher expected gain in net benefit. This happens if outcome distributions are skewed. The cost-effectiveness frontier, which is based on the expected net benefit decision rule, accounts for this skewing of data. The cost-effectiveness frontier is constructed by identifying the range of the threshold ratio for which each intervention represents the *a priori* decision (Fenwick et al., 2001). This approach can be extended to include more than two interventions. However, one limitation of the cost-effectiveness frontier is that it does not address the issue of affordability, i.e. the impact of the intervention on the health care budget.

In a recent paper, Briggs et al. (2002) suggest an extension of the cost-effectiveness acceptability curve that can be used to handle more than two mutually exclusive treatments. In their example, the authors use a Bayesian modeling framework to generate the joint distribution of the costs and effects for each of the six treatment options included in the analysis by sampling a large number of times from the distributions assigned to the model parameters. For each replication, the strategy of choice was that with the highest average net benefit. The proportion of times a treatment option had the greatest net benefit for each level of the threshold ratio was used to form a set of acceptability curves. The strategies with the highest probability of being cost-effective could then be identified for a wide range of the threshold ratio (Briggs et al., 2002). A further advantage of using net benefits in this framework was that stochastic dominance rules could be used to rule out strategies, because net benefits, as opposed to cost-effectiveness ratios, are separable. However, although the authors did not explicitly discuss the issue of budgetary impact, the authors' method could be extended to include the demands that are made on health care resources.

A further important recent development is the combination of regression modeling strategies with the net benefit framework, which explicitly makes use of a threshold ratio as a decision rule (Hoch et al., 2002). The linear nature of the net benefit statistic allows the use of standard regression analysis techniques to analyze patient level data from randomized controlled trials. The advantage of this method lies in the ability to include co-variates and interaction terms in the regression equation, and allows for the adjustment of imperfect randomization and the evaluation of the cost-effectiveness of interventions in different patient sub-groups (Hoch et al., 2002).

Portfolio theory

A further issue that has recently gained attention is the application of methods developed in financial economics to address the decision of how health care programs should be selected when costs and effects are uncertain. Most notably, a paper by O'Brien and Sculpher (2000) has started the discussion as to how portfolio theory can be used to build uncertainty into cost-effectiveness rankings of health care programs. The authors highlight two important principles of portfolio theory: i) the concept of return and risk and the decision maker's preferences over these two moments, and ii) the principle of diversification in order to reduce uncertainty for a given level of expected return (O'Brien and Sculpher, 2000). These two concepts are fundamental in portfolio theory as applied in financial economics. The first step in financial economics usually requires the construction of the portfolio opportunity set, i.e. for each level of expected return the standard deviation of a portfolio of risky assets that may be correlated with each other is minimized. That part of the portfolio opportunity set that is above the minimum variance portfolio is called the efficient frontier. The point of tangency between the decision-maker's indifference curve with the efficient frontier determines the optimal risky portfolio and hence the investment proportions in the respective risky assets.

The construction of the portfolio opportunity set corresponds to a constrained optimization problem, which is usually solved with specialized software packages such as NUOPT for S-Plus (see www.insightful.com) or RISKOptimizer (see www.palisade.com) since the number of risky assets that form a portfolio may be very large. These software packages also allow the inclusion of additional constraints in the analysis.

In chapter 6 we emphasized that the uncertainty associated with return on investment in a portfolio of risky assets in financial economics stems from the fluctuations in market value of the respective assets. The uncertainty associated with return on investment in health care finance, on the other hand, stems from the fact that costs and health outcomes of health care programs are inherently uncertain. This difference has important implications for the applicability of portfolio theory in health care finance. In chapter 6 we demonstrated that the *ex ante* investment proportions in the different health care programs do not necessarily reflect the *ex post* investment proportions. That is, standard portfolio theory can only be used in the special situation where all programs turn out to use the complete budget with a very high probability. However, since resource use is uncertain, the investment proportions may change over time as suggested by the algorithm developed in chapter 6. We have shown that the efficient frontier collapses to a single point on the risk-return plane once the total budget corresponds to the expected costs of the programs.

A further ethical problem that may follow from spreading the budget over many programs is partial implementation. Partial implementation occurs when optimal treatment is only provided to some patients and is withheld from other patients with the same disease and medical indications. This, of course, is against any egalitarian principle and may form an important characteristic of health care systems where basic health care is provided for the whole population. These concerns, however, are not new and are similar to the standard cost-effectiveness model under certainty where complete divisibility of programs is assumed, as discussed in more detail in the introduction to this thesis

In chapter 7 we introduced the idea of a risk-adjusted approach to comparing the return on investment in health care programs. The concept of capital allocation across a risky asset (i.e. a health care program) and a risk-free asset was used to construct a combined portfolio with a standard deviation that may vary according to the proportion of the budget invested in the risky and risk-free asset. The risk-free asset allows us technically to adjust the investment outcomes for risk since the standard deviation of the combined portfolio decreases when the proportion invested in the risk-free asset increases, or vice versa. This method can be used to choose between health care programs that are mutually exclusive at the program level; that is, we do not assume that the budget is spread over many programs for the same medical indication but instead is invested in one single program. This policy is in line with the ethical argument that all patients should be treated equally if they have the same disease condition. The construction of an efficient frontier, which has been discussed in chapter 6, is therefore not relevant under these circumstances. An efficient frontier would only be a mandatory step in the analysis if we were to accept the policy that patients with the same disease condition might be treated differently in order to be able to implement the optimal risky portfolio.

In order to rank mutually exclusive programs, in chapter 7 we suggest using the reward-to-variability ratio, i.e. the extra return we receive per extra risk. The program with the highest reward-to-variability ratio should be preferred by any decision-maker who is risk-averse. That is, the steeper the capital allocation line, the greater the extra expected return per extra risk offered by that program. An advantage of this approach is that the decision-maker's precise utility function is not needed in order to choose among risky programs that are mutually exclusive. This may be seen as a practical advantage of this approach. The decision-maker's utility function would only be needed if we were to determine the investment proportions in the risk-free and risky asset. However, varying the investment proportions does not impact the reward-to-variability ratio of the combined portfolio, and the analysis can therefore be limited to determining the program with the highest reward-to-variability ratio.

The method described in chapter 7 can easily handle more than two comparators and it would be interesting to compare this approach with that suggested by Briggs et al. (2002) where multiple mutually exclusive programs are evaluated according to their probability of being net beneficial. Briggs et al. (2002) estimate these probabilities for each mutually exclusive treatment and for all possible values for the threshold ratio. In chapter 7 we use a value of \$100,000 in order to estimate return, defined as the net monetary benefit over the cost of the program. The analysis could be repeated for all possible values for the threshold ratio and the reward-to-variability ratios of the respective programs plotted. One advantage of evaluating multiple mutually exclusive programs using the reward-to-variability ratio may be that the reward-to-variability ratio is a measure that combines both expected return and risk. However, both approaches rely on the same assumption, the threshold ratio is incorporated in the outcome measure. It should also be noted that in chapter 7 no attempt was made to compare mutually exclusive programs incrementally. The concept of incremental cost-effectiveness analysis follows from a constrained optimization problem that is addressed with a linear programming approach. Linear programming assumes complete divisibility of programs, and the method described in chapter 7 focuses on the question of which single program from several mutually exclusive programs offers the highest expected return per extra unit of risk.

A recent paper by Bridges et al. (2002) has also focused on how portfolio theory may be applied in cost-effectiveness analysis. One novelty in the modified portfolio theory suggested by Bridges et al. (2002) is that it allows for a synergy between interventions. A synergistic treatment effect means that the joint health benefit of two interventions in a patient is greater than the sum of the health benefits separately. For example, highly active antiretroviral therapy in HIV-infected patients entails a combination of drugs where the joint effect of this drug cocktail in terms of patient survival is greater than the sum of the effects of the individual drugs alone. This is because a therapy with only one antiretroviral compound may lead to insufficient viral suppression and hence to the occurrence of viral resistance. In their paper, the authors used a deterministic cost component and a stochastic effect component to form standardized effectiveness ratios, which is the ratio of stochastic effects to deterministic costs (Bridges et al., 2002). The authors hereby shift the whole uncertainty to the effect side of the equation and therefore measure random increases in health per monetary unit spent. However, one limitation of this concept is that it assumes that, as is the case in financial economics, the budget can be spent *in toto* as contemplated. As we have shown in chapter 6, the resource requirements of health care programs are uncertain and the budget may not be consumed as initially distributed over individuals and programs. The investment in a treatment option can clearly not exceed the cost of that

treatment. Moreover, in chapter 6 we have shown that the benefit of diversification disappears as the health care budget in relation to the cost of the programs increases and approaches the expected cost of the programs.

An interesting recent approach that also uses methods developed in financial economics to decide whether a new technology should be introduced in the presence of uncertainty is the real option approach (Palmer and Smith, 2000). The real option approach is based on the following key characteristics: i) there is uncertainty about the future state of the world, ii) the investment decision is at least partially irreversible, i.e. implies sunk costs, and iii) there is the possibility to defer an investment decision. If the benefit of a technology is uncertain and its implementation would be (partially) irreversible, then flexibility in the timing of the decision entails an option with economic value. The real option approach implies that the ICER of a technology be adjusted for the degree of uncertainty and irreversibility before being compared with the threshold ratio. The higher the degree of irreversibility and uncertainty implicit in the decision, the higher the value of the adjusted ICER will be. However, it should be emphasized that the possibility of delaying a decision (a basic assumption of the real option approach) with respect to the introduction of a new technology until more information has become available is often not possible in the real world because of ethical reasons. For example, there is some evidence that genotypic and phenotypic antiretroviral resistance testing to identify compounds to which the HIV is resistant may help to optimize treatment strategies and lead to a better virological suppression. However, there is no evidence that this would improve the patient's immunological status and (AIDS-free) survival since this would require randomized controlled trials with a time-horizon of 5-10 years. Yet this technology has been introduced in clinical practice and is included in current guidelines for the treatment of HIV infection. That is, the option of delaying the introduction of a potentially beneficial new technology with highly uncertain evidence about its long-term (cost-)effectiveness is often not feasible in health care. Finally, irreversibility is likely to play a role in health care investment decisions that require high capital costs (e.g. equipment in radio-oncology) but might be less important in pharmacoeconomics where an old drug A ought to be replaced with new drug B for the same disease condition.

Areas for future research

The decision-making plane presented in this thesis has been suggested as a means to graphically present the results of the alternative decision rule in the presence of uncertainty. When the joint distribution of costs and effects is not limited to the southeastern quadrant, then there is a corresponding probability that the alternative decision rule does not lead to a more efficient allocation of resources. How decision-makers may value the outcomes in the different

quadrants and to what extent such deviations are acceptable is an interesting area for future research.

A further topic that needs exploration is empirical evidence as to what extent the assumptions of constant returns to scale and complete divisibility are acceptable in practice. Such empirical research is needed in order to confirm or question these critical assumptions in different areas of health care.

Methods developed in financial economics offer a rich source of approaches to deal with decision-making under uncertainty in health care finance. In this thesis we have borrowed the principle of capital allocation across a risky and a risk-free asset for ranking mutually exclusive programs according to their reward-to-variability ratio. However, financial methods are available that allow the ranking of programs that are not mutually exclusive and their application to economic evaluation in health care should be subject to future research.

Epilogue

In this thesis different decision rules in the presence of uncertain costs and effects were discussed. The decision rule adopted depends on the school of thought adhered to: there are those who adopt the use of a critical ratio and those who question the assumptions on which it is based. Uncertainty affects both schools of thought, and methods to deal with uncertainty are relevant for both perspectives, as demonstrated in this thesis. Ultimately, empirical evidence about the assumptions of the different decision rules is needed in order to make judgements about how research efforts should be directed towards methods for handling uncertainty in cost-effectiveness analysis. This line of thinking may offer a potentially fruitful agenda for future research.

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■ Samenvatting

*Beslisregels en onzekerheid bij de economische evaluatie
van interventies in de gezondheidszorg*

Inleiding

De discussie over het toepassen van de juiste beslisregel heeft tot dusverre plaatsgevonden in een deterministische context waarin de kosten en effecten van gezondheidszorgprogramma's vast staan. De laatste jaren zijn dankzij gerandomiseerd gecontroleerd onderzoek meer gegevens over kosten en effecten op patiëntniveau beschikbaar gekomen. Op basis daarvan is in toenemende mate onderzoek gedaan naar statistische methoden voor het omgaan met onzekerheid in kosteneffectiviteitsanalyses (O'Brien et al., 1994; Briggs en Gray, 1999). Het werd al snel duidelijk dat bij schatting van de betrouwbaarheidsintervallen voor kosteneffectiviteitsratio's technische problemen kunnen optreden als gevolg van de discontinue verdeling van de kosteneffectiviteitsratio, alsook interpretatieproblemen (Briggs en Gray, 1999). Om tegemoet te komen aan deze beperkingen zijn in de literatuur twee benaderingen voorgesteld: de kosteneffectiviteits-"acceptability" curve (van Hout et al., 1994) en de benadering gebaseerd op netto gezondheidsvoordeel (Stinnett en Mullahy, 1998). In beide benaderingen wordt expliciet gebruik gemaakt van een kritische ratio als afkappunt voor de allocatie van middelen. Opgemerkt dient te worden dat de kritische ratio hierbij niet meer voortkomt uit de oplossing van een optimalisatieprobleem. De budgetbeperking is niet expliciet en middelen kunnen ook afkomstig zijn van andere ministeries dan volksgezondheid, zoals onderwijs of defensie.

In afwezigheid van een expliciete budgetbeperking voor gezondheidszorg zijn de alternatieve kosten voor hulpbronnen in de gezondheidszorg gewoonlijk te vinden op andere terreinen dan de gezondheid. De kwestie van kosteneffectiviteit komt dan neer op de vraag hoe veel de maatschappij bereid is te betalen per gewonnen QALY, zoals voorgesteld door Weinstein (1995) en Johannesson en Meltzer (1998). Volgens Johannesson en Meltzer (1998) is het gebruik van een vast budget als beslisregel problematisch bij maatschappelijke beslissingen, aangezien dan een fictief totaal kostenniveau voor de maatschappij moet worden bepaald, waarin alle relevante kosten zijn verwerkt. Dit zou dan niet overeenkomen met het werkelijke budget. Desalniettemin werken de meeste besluitvormers op een lager niveau dan dat van de maatschappij als geheel, en hebben ze te maken met budgetbeperkingen. Daardoor is het niet duidelijk hoe ze informatie over kosteneffectiviteit en onzekerheid in feite moeten gebruiken als vanwege de beperkte middelen niet alle programma's die als kosteneffectief worden beschouwd, kunnen worden geïmplementeerd. Bovendien worden in de huidige benaderingen voor het omgaan met onzekerheid in kosteneffectiviteitsanalyses de aannamen van constante schaalopbrengsten en volledige deelbaarheid niet aan de orde gesteld.

Een ander onderwerp dat de aandacht heeft getrokken is het toepassen van de portfoliotheorie om te kunnen kiezen tussen programma's in de gezondheidszorg als de kosten en effecten onzeker zijn (O'Brien en Sculpher, 2000).

Het onderliggende idee is dat door het spreiden van het budget over een groot aantal programma's de risico/rendementskarakteristiek van de investeringen in gezondheidszorgprogramma's kan worden verbeterd. Met andere woorden: als het budget wordt geïnvesteerd in een mix van programma's in plaats van in afzonderlijke programma's, zal het verwachte rendement bij hetzelfde risico-niveau hoger zijn (aangenomen dat de programma's niet volledig gecorreleerd zijn). De optimale portfolio wordt dan bepaald door de voorkeuren van de besluitvormer ten aanzien van het verwachte rendement en het risico. Daarbij moet echter worden bedacht dat de financiering van de gezondheidszorg in een aantal opzichten verschilt van de normale financiële economie, een aspect waaraan in dit proefschrift ook aandacht wordt besteed.

In dit proefschrift worden drie verschillende benaderingen besproken van de beslisregel voor de kosteneffectiviteitsanalyse bij onzekere kosten en effecten: i) de alternatieve beslisregel, ii) de klassieke beslisregel en iii) de portfoliotheorie voor het kiezen tussen verschillend programma's in de gezondheidszorg.

De alternatieve beslisregel

In hoofdstuk 2 worden de beperkingen besproken van de op een kritische ratio gebaseerde beslisregel, en wordt voortgebouwd op de door Birch en Gafni (1992,1993) beschreven alternatieve beslisregel. De hoofdgedachte hierbij is dat alle middelen reeds worden gebruikt door de bestaande programma's. Een nieuw programma kan dus alleen worden geïntroduceerd door een bestaand programma te schrappen, om zodoende middelen vrij te maken voor het nieuwe. De gezondheidsvoordelen die verdwijnen door het wegvallen van het oude programma dienen kleiner te zijn dan de voordelen die worden verkregen door het invoeren van het nieuwe programma. Deze beslisregel wordt besproken in een context van onzekerheid ten aanzien van kosten en effecten. Als er een nieuw programma beschikbaar komt dat bijdraagt aan een toename in het aantal QALYs maar aanvullende middelen vereist, moet de vraag worden gesteld waar deze middelen vandaan moeten komen. In een dergelijke situatie dienen andere programma's geschrapt te worden om middelen voor het nieuwe programma vrij te maken. Als de gezondheidsvoordelen die verdwijnen door het schrappen van het oude programma geringer zijn dan die welke bereikt worden door het invoeren van het nieuwe, wordt hiermee een ondubbelzinnige verbetering in de allocatie van de middelen verkregen. Dit is nog niet de ideale aanpak, aangezien er in de bestaande portfolio meer dan één programma aanwezig kan zijn dat aan deze vereisten voldoet (Gafni, 1996). In de praktijk echter kan het voorkomen dat de informatie over kosten en effecten niet voor alle programma's in de huidige portfolio beschikbaar is. Op dat moment blijken de praktische voordelen van de alternatieve beslisregel: zelfs als er maar voor één programma informatie over kosten en effecten beschik-

baar is en dit programma voldoet aan de vereisten van de beslisregel, is dit voldoende voor het verhogen van de efficiëntie van de allocatie van middelen. Vervolgens wordt het "decision-making plane" geïntroduceerd als middel om met beleidsmakers te communiceren en om op grafische wijze de resultaten te tonen van de analyse in een context van onzekerheid, d.w.z. de kans dat de beslisregel zal leiden tot een efficiëntere allocatie van middelen.

In hoofdstuk 3 wordt de alternatieve beslisregel geanalyseerd vanuit een ander perspectief. In deze studie werden stochastische dominantieregels gebruikt als middel om beslissingen te nemen terwijl weinig of geen kennis aanwezig is over de risicopreferentie van een besluitvormer. In dit hoofdstuk wordt benadrukt dat het gebruik van stochastische dominantieregels een aanvulling betekent op de benadering waarbij de resultaten op het decision-making plane worden gepresenteerd. Een voordeel van het gebruik van de cumulatieve verdelingen van kosten en effecten als basis voor het nemen van beslissingen is dat voor alle in de huidige portfolio opgenomen programma's de ermee samenhangende onzekerheid in de analyse kan worden opgenomen. Indien de besluitvormer beschikt over een totaal budget waarmee alle programma's in de gezondheidszorg moeten worden gefinancierd, kan de cumulatieve verdeling van de totale portfoliokosten gebruikt worden om te bepalen wat de kans is dat het budget zal worden overschreden en of dit risico voor de besluitvormer aanvaardbaar is. Merk op dat het voor deze benadering niet nodig is dat het budget constant blijft. Het kan zijn dat een besluitvormer te maken krijgt met een lager budget dan in de voorafgaande jaren. Zo kunnen beleidsmakers besluiten te korten op het bestaande budget voor aanbieders zoals ziekenhuizen, teneinde te bezuinigen op de totale kosten van de gezondheidszorg. In een dergelijke situatie kan een nieuw programma alleen worden ingevoerd als een bestaand programma kan worden gevonden waarvan het schrappen voldoende middelen zou vrijmaken om het nieuwe programma te financieren, maar dat ook de cumulatieve verdeling van de totale kosten zodanig naar links doet verschuiven dat het risico van budgetoverschrijding aanvaardbaar wordt.

In hoofdstuk 8 wordt een kosteneffectiviteitsanalyse gepresenteerd van de zogenaamde highly active antiretroviral therapy (HAART) voor met HIV besmette patiënten. De analyse is uitgevoerd vanuit zowel maatschappelijk perspectief als het perspectief van de gezondheidszorg. De analyse vanuit maatschappelijk perspectief, waarbij productiviteitskosten werden meegenomen, liet zien dat de HAART resulteerde in kostenbesparingen en een verhoging van het aantal gewonnen levensjaren. Maar toen de analyse werd beperkt tot de kosten van de gezondheidszorg, bleek de HAART weliswaar effectiever, maar ook duurder, waarbij de kosteneffectiviteitsratio uiteenliep van CHF 14.000 tot CHF 45.000 (€ 9000 – 28.000, omrekeningskoers dd. 19 november 2003). Aangezien invoering van het HAART-programma additionele middelen vereist voor de gezondheidszorg, moet aandacht worden besteed aan de vraag waar

deze vandaan moeten komen. Als het gehele budget voor gezondheidszorg al wordt gebruikt voor de bestaande programma's, en het niet mogelijk is het budget te verhogen, dan kan de alternatieve beslisregel worden toegepast. Dit wil zeggen dat er een bestaand programma kan worden gezocht, waarvan het schrappen voldoende middelen vrijmaakt om de HAART te bekostigen. In de studie die wordt beschreven in hoofdstuk 9 werd de kosteneffectiviteit bepaald van het gebruik van azitromycine ter voorkoming van infecties met *Mycobacterium avium* complex bij HIV-positieve patiënten die de HAART gebruiken. Uit de analyse bleek dat de kosteneffectiviteit van azitromycine hoger is bij patiënten zonder klinische aids (CHF 47.000 – 60.000) per gewonnen levensjaar) dan bij patiënten met aids (CHF 118.000) per gewonnen levensjaar). Dit betekent dat het starten van een behandeling met azitromycine bij HIV-geïnfekteerden zonder aids een meer efficiënte allocatie van middelen inhoudt dan wachten tot de patiënt een aids-definiërende aandoening krijgt. Maar bij beide patiëntengroepen waren de alternatieve kosten positief, hetgeen betekent dat er meer hulpbronnen nodig zijn om infecties met *Mycobacterium avium* complex bij HIV-geïnfekteerden te voorkomen. Ook hier kunnen de benodigde middelen worden gevonden door te korten op het budget van andere sectoren in de gezondheidszorg, en kan de alternatieve beslisregel worden toegepast.

De klassieke beslisregel

In hoofdstuk 4 wordt de bij de klassieke beslisregel voor kosteneffectiviteit gemaakte aanname van volledige deelbaarheid aan de orde gesteld. Gesteld wordt dat bij het formuleren van het budgetallocatieprobleem een benadering middels integer programming, waarin de patiënten de afzonderlijke eenheden vormen, geschikter kan zijn dan het gebruik van lineaire programmering. Voorts wordt aangetoond dat behandelingen die bij lineaire programmering zouden worden afgewezen, bij sommige patiënten toch zouden worden toegepast om de totale gezondheidsvoordelen te maximaliseren bij een bepaalde budgetbeperking. Een ander idee dat in hoofdstuk 4 wordt geïntroduceerd is de toepassing van simulatie-optimalisatie voor het maximaliseren van de doelfunctie van het optimalisatieprobleem onder randvoorwaarden. Hierbij wordt de doelfunctie gedefinieerd als de verwachte totale effecten min een korting als het budget wordt overschreden. Deze methode maakt het mogelijk de opportuniteitskosten van de vereiste aanvullende middelen in de analyse mee te nemen. De in het eerste deel van hoofdstuk 4 beschreven methode gaat ervan uit dat besluitvormers zich risiconutraal gedragen ten opzichte van gezondheidseffecten en risicomijdend ten opzichte van kosten. Deze aanname lijkt redelijk voor besluitvormers op een lager niveau dan de maatschappij als geheel, die te maken hebben met budgetbeperkingen. Maar aangezien de voordelen alleen aan sommige individuen ten goede komen, zou een

besluitvormer zich ook risicomijdend kunnen opstellen ten opzichte van de gezondheidseffecten. In dat geval kan hij/zij ervoor kiezen de variantie van de totale effecten te minimaliseren, gegeven dat wordt voldaan aan een bepaald aspiratieniveau voor de verwachte totale effecten.

In hoofdstuk 5 wordt de kosteneffectiviteits-“affordability” curve geïntroduceerd. Dit is een uitbreiding van de kosteneffectiviteits-“acceptability” curve, en geeft de waarschijnlijkheid aan dat een interventie kosteneffectief en betaalbaar is. De behoefte aan deze aanvullende informatie vloeit voort uit het feit dat de voor besluitvorming gebruikte kritische ratio gewoonlijk niet gekoppeld is aan een expliciete budgetbeperking. In plaats daarvan gaat het gewoonlijk om een gemakkelijk rond getal, dat vaak door onderzoekers wordt gebruikt om te bepalen of een interventie kosteneffectief is. Maar aangezien besluitvormers op lager niveau dan de maatschappij als geheel in werkelijkheid vaak te maken hebben met een beperkt budget, kan de aanvullende informatie over de betaalbaarheid van een programma (d.w.z. de kans dat de kosten van het programma binnen het beschikbare budget blijven) relevant zijn voor de beslissing of er voldoende middelen zijn om het programma te implementeren.

Portfoliotheorie

Hoofdstuk 6 handelt over een van de speciale kenmerken van de financiering van de gezondheidszorg die in acht moeten worden genomen als men de portfoliotheorie wil gebruiken om te kiezen uit een aantal gezondheidszorgprogramma's waarvan de kosten en effecten onzeker zijn. In de financiële economie kan de beslissing om het budget te spreiden over een groot aantal programma's gewoonlijk vanaf het begin worden gerealiseerd, en vloeit de onzekerheid aangaande het rendement voort uit de volatiliteit van de risicodragende activa. Daarentegen vloeit bij de financiering van de gezondheidszorg de onzekerheid aangaande het rendement van investeringen in zorgprogramma's voort uit het feit dat de kosten en gezondheidsvoordelen inherent onzeker zijn. Dit verschil heeft belangrijke gevolgen voor de toepasbaarheid van de portfoliotheorie op de financiering van de gezondheidszorg. In hoofdstuk 6 wordt aangetoond dat de ex ante investeringsverhoudingen over de verschillende programma's in de gezondheidszorg niet noodzakelijkerwijze worden weerspiegeld door de ex post investeringsverhouding. Dat houdt in dat de standaard portfoliotheorie alleen kan worden toegepast in de speciale situatie waarin alle programma's met een zeer grote mate van waarschijnlijkheid het volledige budget blijken te gebruiken. Aangezien de benutting van de middelen echter onzeker is, kunnen de investeringsverhoudingen in de loop van de tijd veranderen als gevolg van herverdeling van budgetten. Wij hebben aangetoond dat de efficiënt frontiers (efficiënte grens) ineenkrimpt tot één punt op het risk-return plane als het totale budget overeenkomt met de verwachte

kosten van de programma's. Een ethisch probleem dat kan voortvloeien uit het spreiden van het budget over een groot aantal programma's is dat van de partiële implementatie. Dit houdt in dat de optimale behandeling alleen wordt verstrekt aan bepaalde patiënten, terwijl andere patiënten, met dezelfde aandoening en dezelfde medische indicatie, deze behandeling wordt onthouden. Deze problemen zijn echter niet nieuw; ze treden ook op bij het gebruikelijke kosteneffectiviteitsmodel zonder onzekerheid als wordt uitgegaan van volledige deelbaarheid.

In hoofdstuk 7 wordt het idee geïntroduceerd van een voor risico gecorrigeerde aanpak voor het vergelijken van de rendementen van investeringen in programma's in de gezondheidszorg. Het concept van kapitaalverdeling over een risicovol actief (d.w.z. een programma) en een risicoloos actief wordt gebruikt voor het construeren van een gecombineerde portfolio met een standaardafwijking die kan variëren met het deel van het budget dat wordt geïnvesteerd in de risicovolle en risicoloze activa. De helling van de kapitaalallocatielijijn, die wordt gedefinieerd door het rendement van het risicovrije actief en de risico/rendementskarakteristiek van het risicovolle actief, de zogenaamde reward-to-variability ratio, staat in de financiële economie bekend als de Sharpe-Ratio. Deze helling zegt iets over het extra rendement dat we kunnen verwachten per additionele eenheid van risico. Hoe steiler de kapitaalallocatielijijn, hoe beter het programma presteert; met andere woorden, een programma met een hogere reward-to-variability ratio verdient de voorkeur. Deze methode kan worden toegepast bij het kiezen tussen programma's in de gezondheidszorg die elkaar op programmaniveau wederzijds uitsluiten. Dit betekent dat we niet aannemen dat het budget wordt gespreid over een groot aantal programma's voor dezelfde medische indicatie, maar wordt toegewezen aan één programma. Dit beleid is in overeenstemming met de ethische overweging dat alle patiënten met dezelfde aandoening gelijk behandeld moeten worden.

Epiloog

Dit proefschrift handelt over verschillende beslisregels in een situatie die wordt gekenmerkt door onzekerheden wat betreft kosten en effecten. Welke beslisregel wordt toegepast, hangt af van de denkrichting die men aanhangt: sommigen prefereren het gebruik van een kritische ratio, terwijl anderen de aannamen waarop deze is gebaseerd, ter discussie stellen. Aangezien onzekerheid van invloed is op beide denkrichtingen, zijn methoden voor het omgaan met onzekerheid relevant voor beide perspectieven, zoals in dit proefschrift wordt aangetoond. Uiteindelijk zullen empirische gegevens over de aannamen bij de verschillende beslisregels nodig zijn om te kunnen beoordelen welk onderzoek gedaan moet worden naar methoden voor het omgaan met onzekerheid bij de kosteneffectiviteitsanalyse. Deze gedachtegang kan een potentieel vruchtbare agenda opleveren voor toekomstig onderzoek.

■ Curriculum vitae

Pedram Sendi was born in Basel in 1969. He studied medicine at the Universities of Basel and Lausanne, Switzerland, and graduated in 1996, receiving his Doctorate in Medicine from the University of Lausanne in the same year. He worked as a research fellow in the outpatient department of internal medicine at Basel University Hospital from 1997, and held a fellowship from the Swiss National Science Foundation between 1999 and 2002. In 1999, he visited McMaster University, and completed the nihes MSc and DSc program in Health Services Research while working at the institute for Medical Technology Assessment (iMTA), Erasmus University Rotterdam, from 2000 to 2002. He returned to Basel in 2002 where he is focusing his research on methodological and applied issues in economic evaluation.

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