## A new proof of the Lagrange multiplier rule Jan Brinkhuis and Vladimir Protassov

## EI2015-39

**Abstract.** We present an elementary self-contained proof for the Lagrange multiplier rule. It does not refer to any substantial preparations and it is only based on the observation that a certain limit is positive. At the end of this note, the power of the Lagrange multiplier rule is analyzed.

Keywords. Lagrange multiplier rule; penalty function.

We prove the following.

**Theorem (the Lagrange multiplier rule).** Assume that G is a set in  $\mathbb{R}^n$  and that  $f_i, 0 \le i \le m$ are continuously differentiable functions on G. Let  $\hat{x}$  be an interior point of G that is a minimizer of  $f_0(x)$  on the set of of points in G for which  $f_i(x) = 0, 1 \le i \le m$ . Then the set of derivatives  $f'_i(\hat{x}), 0 \le i \le m$ , the n-dimensional row vectors of the partial derivatives of the  $f_i, 0 \le i \le m$  in  $\hat{x}$ , is linearly dependent.

The given formulation of the conclusion of the rule is equivalent to the following one, which is more familiar: if the derivatives  $f'_i(\hat{x}), 1 \leq i \leq m$  are linearly independent, then  $\hat{x}$  is a stationary point of the function  $f_0(x) + \lambda_1 f_1(x) + \cdots + \lambda_m f_m(x)$  for suitable numbers (Lagrange multipliers)  $\lambda_i, 1 \leq i \leq m$ .

The existing proofs of the multiplier rule in the literature require effort. Either they refer to substantial preparations or they contain technical arguments. Such preparations are the implicit function theorem ([1],[2]), the inverse function theorem (of which the multiplier rule is an immediate consequence [3]), the tangent space theorem ([4], [5]), the Brouwer fixed-point theorem ([6]) or the Ekeland variational principle ([7]). Technical arguments are needed to establish inequalities and estimates ([8]). Then the resulting proofs are elementary but they tend to be relatively long and involved ([9], 10]). The new proof given in the present note requires essentially no effort: it is not only elementary, but also simple, short and insightful. Its novelty consists in the easy observations that a certain limit is positive and that this implies that boundary points are excluded as minimizers of a certain penalty function. The remainder of the proof is obvious. All elementary proofs for the multiplier rule, including the one given in this note, make use of the theorem that a continuous function assumes its minimal value over a closed ball.

**Proof.** By contraposition.

• Preparations. Assume that  $\hat{x}$  is an interior point of G that is a solution of the system of equations  $f_i(x) = 0, 1 \le i \le m$  for which  $f'_i(\hat{x}), 0 \le i \le m$  are linearly independent. We will show that  $\hat{x}$  is not a minimum of the function  $f_0(x)$  on the set of  $x \in G$  for which  $f_i(x) = 0, 1 \le i \le m$ .

Without loss of generality it is assumed that  $f_0(\hat{x}) = 0$ ,  $\hat{x} = 0$  and n = m + 1—the latter can be achieved by adding if necessary constraints  $a_i x = 0$ ,  $i \in I$ , chosen in such a way that the set  $a_i, i \in I$  completes the linearly independent set  $f'_i(0), 0 \leq i \leq m$  to a basis of the space  $(\mathbb{R}^n)^T$ of *n*-dimensional row vectors. Define  $F(x) = (f_0(x), \ldots, f_m(x))^T$  for  $x \in \mathbb{R}^n$ . Then F(0) = 0, F'(x) is the  $n \times n$ -matrix that has as rows the derivatives  $f'_i(x), 0 \leq i \leq m = n - 1$ , F' is continuous and

$$F(x) = F'(0)x + o(|x|)(x \to 0)$$
(1)

('Landau little o')—as the  $f_i, 0 \leq i \leq m$  are continuously differentiable and F(0) = 0. The assumption that  $f'_i(0), 0 \leq i \leq m = n - 1$  are linearly independent means that the  $n \times n$ -matrix F'(0) has rank m + 1 = n, so F'(0) is invertible. Choose for each  $k \in \mathbb{N}$  a minimizer  $x_k$  of the penalty function

$$p_k(x) = |F(x) + (1/k^2, 0, \dots, 0)^T|$$
(2)

on the closed ball  $|x| \leq 1/k$ , where  $|\cdot|$  is the Euclidean norm.

• Exclusion of boundary minimizers for the penalty function. We consider the limit

$$L = \lim_{x \to 0} \frac{|F(x) + (|x|^2, 0, \dots, 0)^T| - |(|x|^2, 0, \dots, 0)^T|}{|F'(0)x|}.$$
(3)

Here we recall that F'(0) is invertible. Note that

$$\lim_{x \to 0} |x|^2 / |F'(0)x| = 0$$

Therefore,

$$L = \lim_{x \to 0} |F(x)| / |F'(0)x| = 1 > 0,$$
(4)

using (1) and the invertibility of F'(0). It follows from (3) and (4) that for k sufficiently large and for each point  $\bar{x}$  on the sphere |x| = 1/k, one has

$$|F(\bar{x}) + (|\bar{x}|^2, 0, \dots, 0)^T| > |(|\bar{x}|^2, 0, \dots, 0)^T|,$$

that is, the penalty function  $p_k$ , given by (2), takes a larger value in  $\bar{x}$  than in 0—here we use also F(0) = 0. Therefore, boundary points of the ball  $|x| \leq 1/k$  cannot be minimizers of the penalty function  $p_k$ , given by (2), on this ball. That is,  $x_k$  is an interior point of this ball,  $|x_k| < 1/k$ .

• Conclusion of the proof. Moreover, for k sufficiently large,  $|x_k| < 1/k$  implies that the matrix  $F'(x_k)$  is invertible as F'(0) is invertible and F' is continuous. From this, and as the minimizer  $x_k$  is an interior point of the closed ball  $|x| \le 1/k$ , it is obvious that

$$F(x_k) + (1/k^2, 0, \dots, 0)^T = 0.$$
(5)

Indeed, otherwise a local decrease of the penalty function  $p_k$ , given by (2), would be possible. Here is a precise analytic verification. The stationarity vector equation

$$0 = \frac{d}{dx}|F(x) + (1/k^2, 0, \dots, 0)^T|^2|_{x=x_k} = 2(F(x_k)^T + (1/k^2, 0, \dots, 0))F'(x_k)$$

holds as the minimizer  $x_k$  is interior. Here we use that the minimizers of a nonnegative valued function do not change if the objective function is squared and that  $|v|^2 = v^T v$  for a column vector v. This gives (5) as  $F'(x_k)$  is invertible. That is, by the definition of F,

$$f_0(x_k) = -1/k^2 < 0 = f_0(0), f_i(x_k) = 0, 1 \le i \le m.$$

It follows that  $\hat{x} = 0$  is not a minimizer of the function  $f_0(x)$  on the set of points in G for which  $f_i(x) = 0, 1 \le i \le m$ . This concludes the proof of the theorem.

**Comment on the power of the rule.** The power of the rule lies in the reversal of the natural order of two main tasks, elimination and differentiation. The natural order would be to eliminate m of the variables  $x_1, \ldots, x_n$ , using the equality constraints  $f_i(x) = 0, 1 \le i \le m$ , substitute into the objective function  $f_0(x)$ , and then put the partial derivatives of the resulting expression in n - m variables equal to zero. The elimination task is often a nonlinear problem that is difficult or even impossible. Differentiating first gives the following statement, which is a reformulation of the conclusion of the theorem: all solutions  $h \in \mathbb{R}^n$  of the system of linear equations

$$f_i'(\widehat{x})h = 0, 1 \le i \le m \tag{6}$$

satisfy

$$f_0'(\widehat{x})h = 0$$

provided the vectors  $f'_i(\hat{x}), 1 \leq i \leq m$  are linearly independent. The remaining elimination task is now just a *linear* problem. It is easy to eliminate m of the n variables  $h_1, \ldots, h_n$  using the system of linear equations (6). Then one can substitute in  $f'_0(\hat{x})h$ . Finally one should put the coefficients of the resulting expression in n-m variables equal to zero. This completes elimination without multipliers. In particular, multipliers are not essential to the power of the rule, but merely provide a convenient way to carry out the linear elimination task. See Ch 3 of [4] for more details on the power of the rule.

Acknowledgment. We would like to thank Jan van de Craats for his suggestions on the presentation.

## References.

[1] Lang, S., Calculus of Several Variables, Reading, MA: Addison-Wesley, (1973)

[2] Luenberger, D.G., Ye Y., Linear and Nonlinear Programming, Springer (2008)

[3] Alexeev, V.M., Tikhomirov, V.M., Fomin, S.V., *Optimal Control*, Consultants Bureau, New York (1987)

[4] Brinkhuis, J., Tikhomirov, V.M., *Optimization: Insights and Applications*, Princeton University Press, (2005)

[5] Giaquinta, M., Modica, G., Mathematical Analysis, An Introduction to Functions of Several Variables, Birkhäuser, (2009) [6] Halkin, H., Implicit functions and optimization problems without continuous differentiability of the data, SIAM J. Control 12, 229-236 (1974)

[7] Clarke, F.H., Optimization and nonsmooth analysis, Wiley (1983)

[8] Brezhneva, O., Tret'vakov, A.A., Wright, S.E., A short elementary proof of the Lagrange multiplier theorem, Optim. Lett. (2012) 6:1597-1601.

- [9] McShane, E.J., The Lagrange multiplier rule, Amer. Math. Monthly 80, 922-925 (1973)
- [10] Rockafellar, R.T., Lagrange multipliers and optimality, SIAM Rev. 35, 183-238 (1993)